

Pf: By def of a "patch" $d\alpha(q)$ has rank k , $n \left(\begin{matrix} k \\ d\alpha(q) \end{matrix} \right)$ so it has k indep. rows.

For convinces, assume these are the first k rows, and let $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^k$ be given by dropping the last $(n-k)$ coords of a vector in $\mathbb{R}^n$

Set $g = \pi \circ \alpha$, $dg = \begin{pmatrix} I_k & 0 \\ 0 & \dots \end{pmatrix} (d\alpha) = (\text{first } k \text{ rows of } d\alpha)$

So $dg(q)$ has k indep rows. so $dg(q)$ is invertible.

By the IFT, g is a diffeomorphism near q .

Corollary: "Transition function are C^r "

$\sigma = \alpha_2^{-1} \circ \alpha_1$ on $\alpha_1^{-1}(V_1 \cap V_2)$.

Claim: σ is C^r

Pf: find a projection: $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^k$ s.t.

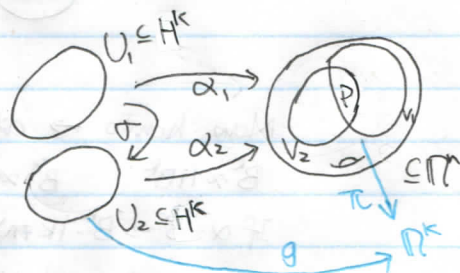
$g = \pi \circ \alpha_2$ is a diffeomorphism near some arbitrary pt. $p \in V_1 \cap V_2$.

Claim: $\sigma = \alpha_2^{-1} \circ \alpha_1 = g^{-1} \circ \pi \circ \alpha_1$ (near p)

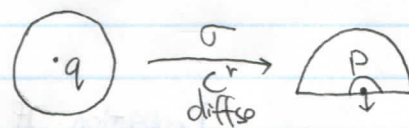
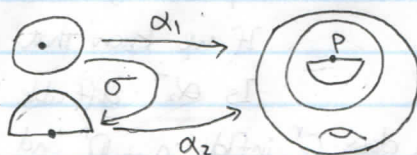
Pf: (by composing with g , nts $g \circ \alpha_2^{-1} \circ \alpha_1 \stackrel{?}{=} g \circ g^{-1} \circ \pi \circ \alpha_1$; $g \circ \alpha_2^{-1} \circ \alpha_1 \stackrel{?}{=} \pi \circ \alpha_1$.

Recall $g = \pi \circ \alpha_2$, $\pi \circ \alpha_2 \circ \alpha_1^{-1} \circ \alpha_1 \stackrel{?}{=} \pi \circ \alpha_1$ ✓

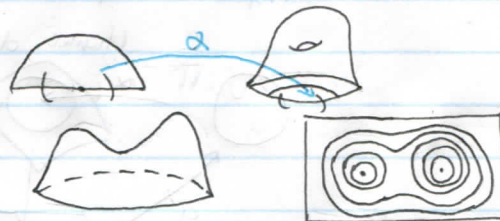
So $\sigma = g^{-1} \circ \pi \circ \alpha_1$ is a composition of C^r functions, hence it is C^r as required.



Cor. ∂M make sense.



Easy. ∂M is itself a mfd, with no bdy. Sketch:



If $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is C^r and t is a height at which df has no singularities, then $f^{-1}(t)$ is a mfd.

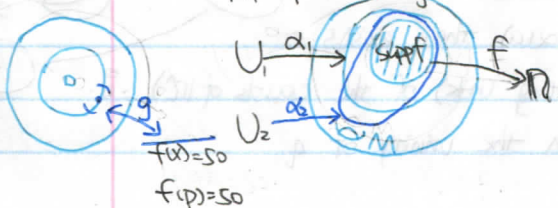
Thm. If $A \subseteq \mathbb{R}^n$ is open, $f: A \rightarrow \mathbb{R}^m$ is C^r , then for most h , $f^{-1}(h)$ is a manifold. $(m-1)$ -dim. manifold

Precisely: If $h \in \mathbb{R}^m$ s.t. whenever $p \in f^{-1}(h)$, $df(p)$ is of rank 1 ($\Leftrightarrow df(p) \neq 0$)

then $f^{-1}(h)$ is a mfd, so is $M = f^{-1}([1, \infty, h])$. Finally, $\partial M = N$.

Example: $f = x^2 + y^2 + z^2$ $df \neq (2x, 2y, 2z)$. So spheres are mflds.

Sketch of proof: Integration on (compact) mflds.



In that case, define $\int_M f dV = \int_U (f \circ \alpha) V(d\alpha)$

Q: Does $\int_M f dV$, as defined above, depend on α ?

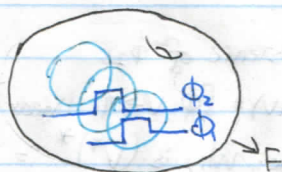
$$\int_U (f \circ \alpha_1) V(d\alpha_1) \stackrel{?}{=} \int_U (f \circ \alpha_2) V(d\alpha_2)$$

Jan 30.

What if supp f is big?

1. Theory answer: use a partition of unity (POU)

$$\int_M f := \sum_{i=1}^N \int_M \phi_i f$$



$$\sum \phi_i = 1$$

Thm. This procedure is indep of the POU namely, if ϕ_i & ψ_i are POU, then $\sum \int_M \phi_i f = \sum \int_M \psi_i f$

In practice



Chop to pieces with overlaps of mea-o. integrate on pieces & add.



$$v_1, \dots, v_k \mapsto f(v_1, \dots, v_k)$$

What does f need to be so that we'll be able to use it for an integration theory?

"diff form"
fdw = $\int_M$

$$f(\begin{smallmatrix} | & | & | & | \end{smallmatrix}) = f(\begin{smallmatrix} | & | & | \end{smallmatrix}) + f(\begin{smallmatrix} | & | & | \end{smallmatrix}) \quad f(v_1+v_2, v_3) = f(v_1, v_3) + f(v_2, v_3)$$

Ans. to (*). 1. f should be linear in each of its arguments.

2. If two of the arguments of f are equal, $f=0$.

Def. Let V be a v.s. $\mathcal{L}^k(V) = \left\{ f: V^k \rightarrow \mathbb{R} : \begin{array}{l} V \mapsto f(v_1, \dots, v_{i-1}, v, v_{i+1}, \dots, v_k) \\ \text{is linear for every } i, 1 \leq i \leq k \text{ and} \\ \text{every choice of } v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_k \end{array} \right\}$

Challenge: $\dim \mathcal{L}^k(V) = ?$

k -linear forms

Feb 01.

Def. $\mathcal{L}^k(V) = \{ f: V^k \rightarrow \mathbb{R} \mid \forall 1 \leq i \leq k, \forall v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_k \in V, V \mapsto f(v_1, \dots, v_{i-1}, v, v_{i+1}, \dots, v_k) \text{ is linear} \}$

Claim: $\mathcal{L}^k(V)$ is a vector space. better phrasing $\mathcal{L}^k(V)$ is a sub-vector space of $\text{Fun}(V^k \rightarrow \mathbb{R})$.

(Aside: $X \text{ Fun}(X \rightarrow \mathbb{R})$ is a vector space.

N.T.S: if $f, g \in \mathcal{L}^k(V)$ $f+g \in \mathcal{L}^k(V)$ if $\lambda \in \mathbb{R}, f \in \mathcal{L}^k(V), \lambda f \in \mathcal{L}^k(V)$

$$\begin{aligned} \text{e.g. } (f+g)(v+v', v_2, \dots, v_k) &\stackrel{\text{def of } f+g}{=} f(v+v', v_2, \dots, v_k) + g(v+v', v_2, \dots, v_k) \\ &\stackrel{f, g \in \mathcal{L}^k}{=} f(v, v_2, \dots, v_k) + f(v', v_2, \dots, v_k) + g(v, v_2, \dots, v_k) + g(v', v_2, \dots, v_k) \\ &\stackrel{\text{def of } f+g}{=} (f+g)(v, v_2, \dots, v_k) + (f+g)(v', v_2, \dots, v_k) \end{aligned}$$

Thm. If $(a_1, \dots, a_n)$ is a basis of V and $I = (i_1, \dots, i_k) \in \{1, \dots, n\}^k = \mathbb{N}^k$

there is a unique $\phi_I \in \mathcal{L}^k(V)$ s.t. $\phi_I(a_{j_1}, \dots, a_{j_k}) = \begin{cases} 1 & \text{if } I = J = (j_1, \dots, j_k) \\ 0 & \text{if } I \neq J \end{cases} = \delta_{IJ}$

Further more: $\{\phi_I : I \in \mathbb{N}^k\}$ is a basis of $\mathcal{L}^k(V)$ ($\dim \mathbb{N}^k$)

proof: Step 1: Lemma: an element of $\mathcal{L}^k(V)$ is determined by its values on sequences of basis vectors.
 $\Rightarrow$ if $\phi_1, \phi_2 \in \mathcal{L}^k$ have same values on seqs of basis vectors, then $\phi_1 = \phi_2$

So ϕ_I is uniquely determined.

proof of lemma: Suppose $\phi \in \mathcal{L}^k$ $v_i = \alpha_{i1} a_1 + \alpha_{i2} a_2 + \dots + \alpha_{in} a_n$

$$v_k = \alpha_{k1} a_1 + \dots + \alpha_{kn} a_n$$

$$\text{Then } \phi(v_1, \dots, v_k) = \phi\left(\sum_{j=1}^n \alpha_{1j} a_j, \dots, \sum_{j=1}^n \alpha_{kj} a_j\right) = \sum_{j_1=1}^n \alpha_{1j_1} \dots \sum_{j_k=1}^n \alpha_{kj_k} \phi(a_{j_1}, a_{j_2}, \dots, a_{j_k})$$

□

Step 2. Existence of ϕ_1 . V is always f.d.

$$\mathcal{L}^1(V) = \{\phi: V \rightarrow \mathbb{R} \text{ linear}\} =: V^* = \text{"the dual of } V"$$

Aside: Why is $(V^*)^* = V$

There is a unique $\phi_i \in V^*$ s.t. $\phi_i(a_j) = \delta_{ij}$ (already known).

$$\text{If } I = (i_1, \dots, i_k), \text{ let } \phi_I(V_1, \dots, V_k) = \phi_{i_1}(V_1) \cdot \phi_{i_2}(V_2) \cdot \dots \cdot \phi_{i_k}(V_k) = \phi_{i_1}(a_{j_1}) \cdot \phi_{i_2}(a_{j_2}) \cdot \dots \cdot \phi_{i_k}(a_{j_k})$$

$$a) \phi_I \text{ is multi-linear } \dots V \quad b) \phi_I(a_j) = x+y = \delta_{i_1 j_1} \delta_{i_2 j_2} \dots \delta_{i_k j_k} = \delta_{Ij}$$

Step 3. $\{\phi_I\}$ is linear indep. Assume $(*) 0 = \sum_{I \in \mathcal{I}^k} \alpha_I \phi_I$. Evaluate $(*)$ on $a_j = (a_{j_1}, \dots, a_{j_k})$

$$0 = \sum_I \alpha_I \phi_I(a_j) = \sum_I \delta_{Ij} \alpha_I = \alpha_j \quad \square$$

Step 5. $\{\phi_I\}$ span.

Feb. 03.

V : v.s. with basis $\{a_1, \dots, a_n\}$

Def: $\mathcal{L}^k(V) = \{\text{multi-linear } f: V^k \rightarrow \mathbb{R}\}$ "k-tensors", a vector space.

$$\text{For } I \in \mathcal{I}^k, \exists! \phi_I \in \mathcal{L}^k \text{ s.t. } \phi_I(a_j) = \phi_I(a_{j_1}, \dots, a_{j_k}) = \delta_{Ij}$$

These make a basis of $\mathcal{L}^k$, so $\dim \mathcal{L}^k(V) = n^k$ Lin. indep: done. NTS: $\{\phi_I\}$ span $\mathcal{L}^k$

Claim: $\{\phi_I\}$ span $\mathcal{L}^k(V)$

pf: Take some $f \in \mathcal{L}^k(V)$ Let $\lambda_I = f(a_I)$.

$$(f = \sum_{I \in \mathcal{I}^k} \lambda_I \phi_I \quad \lambda_I \in \mathbb{R} \text{ evaluate } a_j \quad f(a_j) = \sum_I \lambda_I \phi_I(a_j) = \lambda_j)$$

Claim: $\sum \lambda_I \phi_I = f$. Enough to show that LHS=RHS when evaluated on a_j 's.

tensor product

$$\text{In deed, } f(a_j) = \sum_I \lambda_I \phi_I(a_j) = \lambda_j$$

Extra pt 1. Define $\otimes: \mathcal{L}^k(V) \times \mathcal{L}^m(V) \rightarrow \mathcal{L}^{k+m}(V)$.

$$\text{by if } f \in \mathcal{L}^k, g \in \mathcal{L}^m \quad (f \otimes g)(V_1, \dots, V_{k+m}) = f(V_1, \dots, V_k) \otimes g(V_{k+1}, \dots, V_{k+m})$$

Already shown that indeed $f \otimes g \in \mathcal{L}^{k+m}(V)$

Extra props: 1. $\otimes$ is bilinear: $(f_1 + f_2) \otimes g = f_1 \otimes g + f_2 \otimes g \quad \lambda \dots$

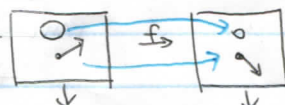
2. $\otimes$ is assoc: $(f \otimes g) \otimes h = f \otimes (g \otimes h)$

$$3. \phi_I(V_1, \dots, V_k) = \phi_{i_1}(V_1) \cdot \phi_{i_2}(V_2) \cdot \dots \cdot \phi_{i_k}(V_k) \quad \phi_I = \phi_{i_1} \otimes \phi_{i_2} \otimes \phi_{i_3} \otimes \dots \otimes \phi_{i_k}$$

$\mathbb{R}^n \xrightarrow{f} \mathbb{R}^n$ "points push forward" "tangent push forward"

"functions pull back" "subsets pull back"

$$\text{Given a linear } T: V \rightarrow W, \quad \mathcal{L}^k(V) \xleftarrow{T^*} \mathcal{L}^k(W)$$



$$f^{-1}(A \cap B) = f^{-1}(A) \cap f^{-1}(B)$$

Def. $(T^*f)(V_1, \dots, V_k) = f(TV_1, \dots, TV_k)$ T^*f really is a mlti of $\mathcal{L}^k(V)$

1. $T^*: \mathcal{L}^k(W) \xrightarrow{f, g} \mathcal{L}^k(V)$ is linear. $\lambda \in \mathbb{R}, \quad T^*(f + \lambda g) = (T^*f) + \lambda(T^*g)$

2. "Contravariant" (all pull back operations are "Contravariant")

$$V \xrightarrow{T} W \xrightarrow{S} Z \quad \mathcal{L}^k(V) \xleftarrow{T^*} \mathcal{L}^k(W) \xleftarrow{S^*} \mathcal{L}^k(Z)$$

$$(S \circ T)^* = T^* \circ S^*$$