

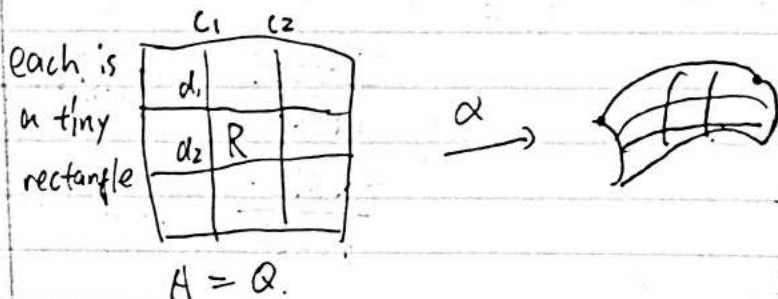
Read along: Sec 22 Mon. Jan 14th

Udunn $x_1, \dots, x_k \in \mathbb{R}^n$ in k dim.

$V(x_1, \dots, x_k) = |\det(x^T x)|^{1/2}$, $x = (x_1 | \dots | x_k)$
 rotation invariant, correct on \mathbb{R}^k



Def: A "parametrized" k -manifold in \mathbb{R}^n is a C^1 map, $\alpha: A \rightarrow \mathbb{R}^n$, where $A \subset \mathbb{R}^k$ is some open set. $\alpha(A) = Y$ "the manifold"
 α : the parametrized.



$$\text{Vol}(Y) = \sum_{R \in P} \text{Vol}(\alpha R) \sim \sum_{R \in P} V(D_x \alpha(c)) \cdot (d_1 - c_1)e_1 \cdot (d_2 - c_2)e_2 \cdot \dots \cdot D_x \alpha(c) \cdot (d_k - c_k)e_k$$

$$R = \pi \{ [c_i, d_i] \}$$

$$c = \begin{pmatrix} c_1 \\ \vdots \\ c_k \end{pmatrix}$$

Claim: $V(x, \lambda x_1, \dots, x_k) = |\lambda| V(x_1, \dots, x_k)$. $(d_i - c_i)$ is scalar. put it out

so above $\text{Vol}(x) = \sum_{x \in P} \prod_{i=1}^k |d_i - c_i| \cdot V(D_x \alpha e_1, \dots, D_x \alpha e_k)$

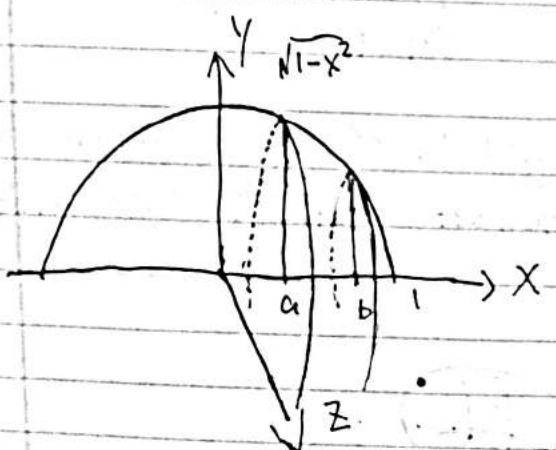
$$P = \pi \{ [c_i, d_i] \}$$

Remark. $X = D_x(c)$, $V(x_1, \dots, x_k) = |\det X^T X|^{1/2} = V(x)$, if $x \in \mathbb{R}^k$

So above = $\sum_{R \in \mathcal{P}} \text{Vol}(R) \cdot V(D_x(g)) \sim \int_Q V(D_x) \cdot g$ if g is .. as above

Def: $V(X) = V(X, \alpha) := \int_A V(D_x) = \int_A |\det(D_x^T D_x)|^{1/2}$

Example: Compute the amount of crust on a slice of a spherical loaf of bread



$$A = (a, b) \times [0, 2\pi]_{\theta}$$

$$\alpha(x, \theta) = \begin{pmatrix} x \\ \sqrt{1-x^2} \cos \theta \\ \sqrt{1-x^2} \sin \theta \end{pmatrix}$$

$$D_x = \begin{pmatrix} 1 & 0 \\ \frac{-x \cos \theta}{\sqrt{1-x^2}} & -\sqrt{1-x^2} \sin \theta \\ \frac{-x \sin \theta}{\sqrt{1-x^2}} & \sqrt{1-x^2} \cos \theta \end{pmatrix}$$

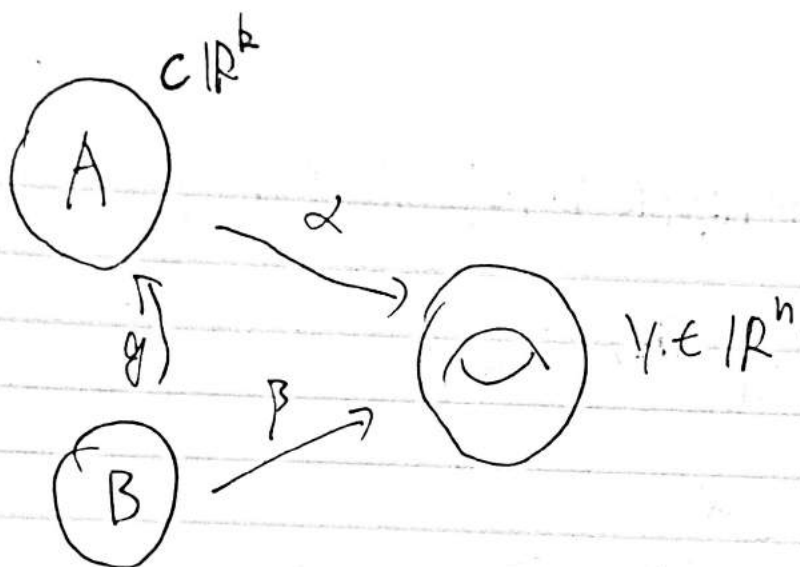
$$(D_x^T D_x) = \begin{pmatrix} 1 + \frac{x^2}{1-x^2} & 0 \\ 0 & 1-x^2 \end{pmatrix}$$

$$x = (x|y), \quad x^T = \begin{pmatrix} x^T \\ y^T \end{pmatrix} \quad \Rightarrow \quad x^T x = \begin{pmatrix} \|x\|^2 & \langle x, y \rangle \\ \langle y, x \rangle & \|y\|^2 \end{pmatrix}$$

$$V(D_x) = 1$$

$$\text{Vol} = \int_A 1 = \text{Area}(A) = 2\pi(b-a), \quad [a, b] = [-1, 1]$$

Surface area of a sphere is $4\pi r^2$.



Thm: if $\alpha: A \rightarrow \mathbb{R}^n$ is a manifold, and if $f: B \rightarrow A$ is diffeomorphism, then set $\beta = (\alpha \circ f)$, and then $\alpha(A) = \beta(B)$, silly and $V(Y, \alpha) = V(Y, \beta)$.

pf: $V(Y, \beta) = \int_B V(D\beta) = \int_B V(D(\alpha \circ f)) \quad D\alpha \circ f = D\alpha \text{ at } f$

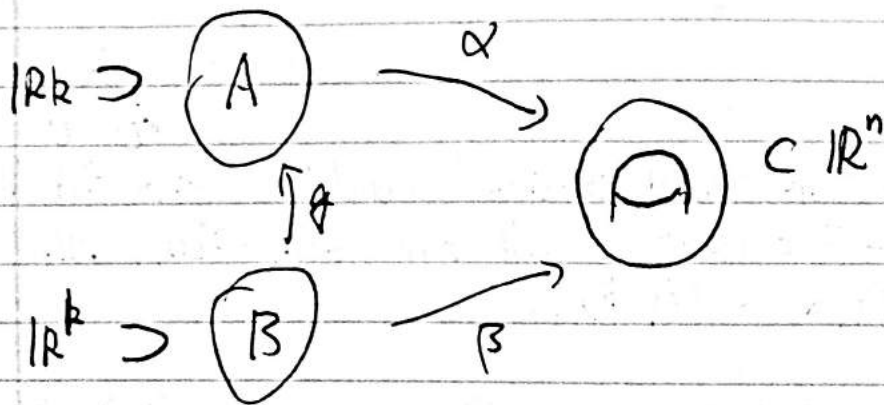
$$= \int_B V(D\alpha \circ f, Df) = \int_B |\det(Df)^T (D\alpha \circ f)^T (D\alpha \circ f) (Df)|^{1/2}$$

$$= \int_B |\det Df| V(D\alpha \circ f)$$

$$= \int_A V(D\alpha) = V(Y, \alpha)$$

Wed. Jan 18th. Manifolds in \mathbb{R}^n Read along 23.24

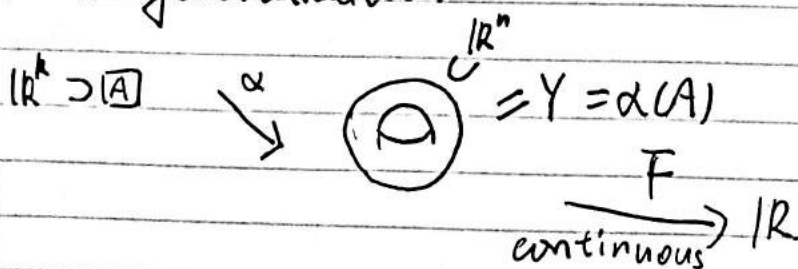
$$V(Y) = V(Y, \alpha) := \int_A V(D\alpha) := \int_A |\det((D\alpha)^T D\alpha)|^{1/2}$$



$$\beta = \alpha \circ \gamma \quad \cdot \quad V(Y, \alpha) = V(Y, \beta)$$

Precisely, $\gamma: B \rightarrow A$, diffeomorphism of open sets in \mathbb{R}^k and $\alpha: A \rightarrow \mathbb{R}^n$ is a manifold set $\beta = \alpha \circ \gamma$, and then $\alpha(A) = \beta(B) = Y$, and $V(Y, \alpha) = V(Y, \beta)$

Mild generalization



$$\text{Def: } \int_Y F \, d\text{vol} = \int_A (F \circ \alpha) V(D\alpha) \stackrel{\text{Thm}}{=} \int_B (F \circ \beta) V(D\beta)$$

Integral relative to k -dim volume

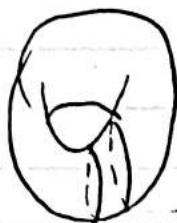
$$\text{Today: } \int_M dw = \int_{\partial M} w$$

M : "A nice and smooth ^{sweet} k -dim subset in \mathbb{R}^n "


Ex 0 : 0 dim in \mathbb{R}^3 : a point

Ex 1 : $\sim \mathbb{R}^2$ in \mathbb{R}^3

Ex 2 :  $S^2 \subset \mathbb{R}^3$



$T^2 = S^1 \times S^1$ use Σ .

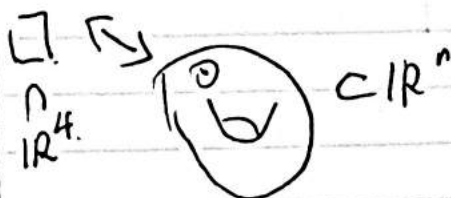
Σ_g  g holes in a sphere PA
($g \geq 0$)

Ex.

k -dim: k lin. indep. $\subset \mathbb{R}^4$

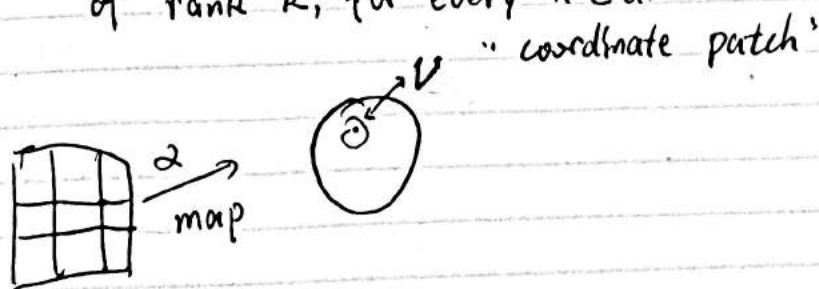
$$O(n) = \{A \in M_{n \times n} : A^T A = I\} \subset \mathbb{R}^{n^2}$$

$$O_2 = S^1 \cup S^1 \subset \mathbb{R}^4$$

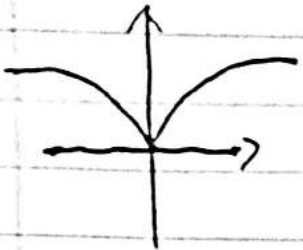


for every point, can find a subset in \mathbb{R}^k

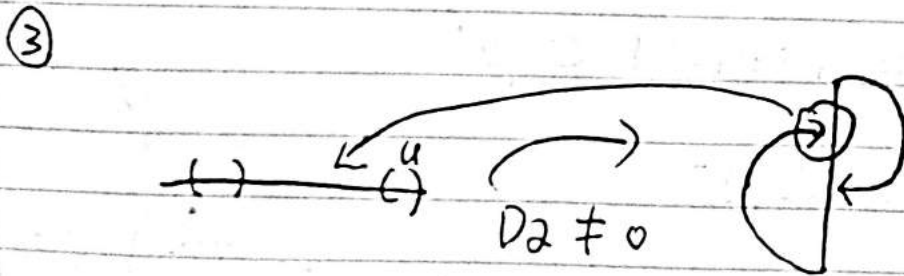
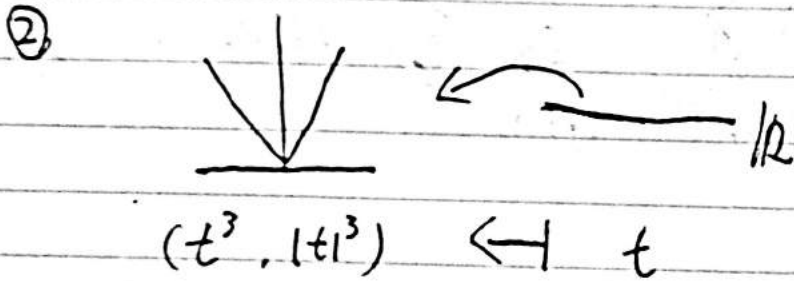
Def: A k -dim manifold (w/o boundary, of class C^r , $r \geq 1$) in \mathbb{R}^n is a subset $M^k \subset \mathbb{R}^n$ such that each point $x \in M$ has an open nbd U such that there is an open $V \subset \mathbb{R}^k$ and a C^r homeomorphism $\alpha: U \rightarrow V$ whose differential $D\alpha(x)$ is of rank k , for every $x \in U$.



non-Examples : ① $\alpha: \mathbb{R} \rightarrow \mathbb{R}^2$ by $t \mapsto (t^3, t^2)$
 α is a homeomorphism



$D\alpha = (3t^2, 2t)$, not rank 1 at $t=0$

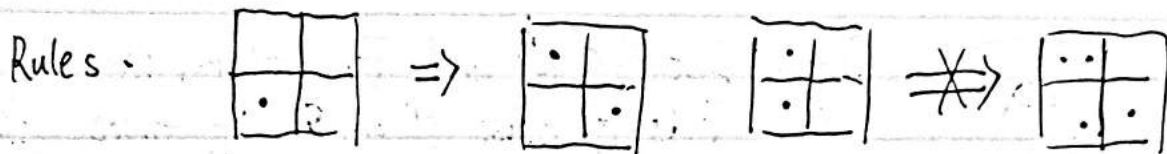


could write in coordinates

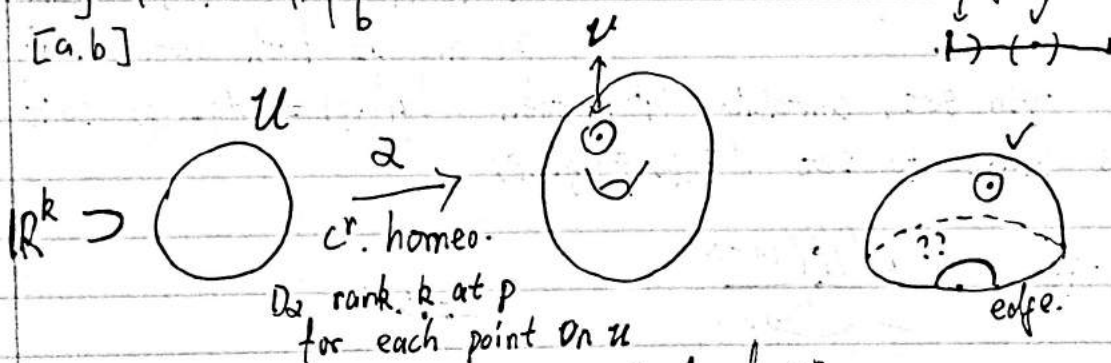
Jan. 2nd Friday. Manifolds in \mathbb{R}^n

Read along: Section 23, 24

Riddle: Gal's Riddle, from 16-475



$$\int_{[a,b]} F' = F \Big|_a^b$$

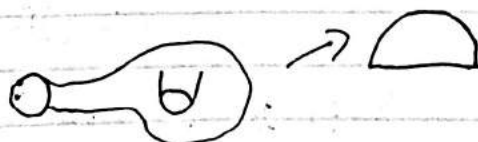


Premature Def: Let $H^k \rightarrow \text{half of } \mathbb{R}^k = \{x \in \mathbb{R}^k : x_k \geq 0\}$

A k -manifold (of class C^r , possibly with boundary) is a subset $M \subset \mathbb{R}^n$ such that each $p \in M$ has an open nbd (in M) such that there is an open $V \subset H^k$, and a C^r homeomorphism $\alpha: U \rightarrow V$ whose differential is of rank k , at every $x \in U$.

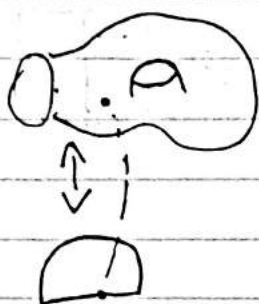
The ∂M (namely boundary, not $\text{bd} M$, same word with different meaning and notation) of M is $\partial M = \{p \in M, \text{ for some patch } \alpha: p = \alpha(q), \text{ where } q \in \partial H^k = \mathbb{R}^{k-1} \times \{0\}\}$.

* α is a map, p 's image of q , which at half space H^k

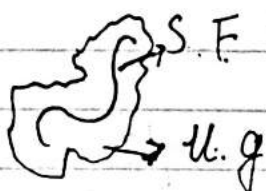


Claim: ∂M is also a manifold, without boundary, of dim $(k-1)$

- Issues:
1. What does differentiability mean on H^k ?
 2. Could it be that $\partial M = M$?
 3. Why is the claim true?

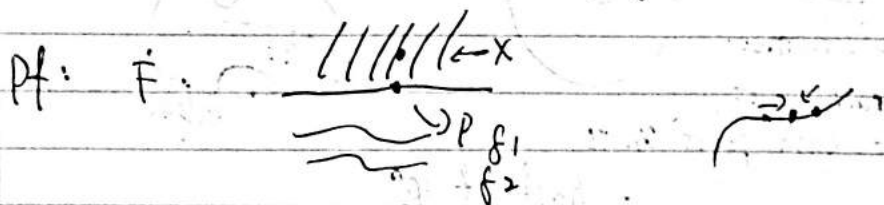


Def: Let $S \subset \mathbb{R}^k$ and $F: S \rightarrow \mathbb{R}^m$. We say that F is of class C^r on S , if there exists an open $U \supset S$ and a C^r function $g: U \rightarrow \mathbb{R}^m$ such that $g|_S = F$, namely $\forall x \in S, F(x) = g(x)$



Easy fact: If $F: H^k \rightarrow \mathbb{R}^m$, then $dF(p)$ is well-defined, even for $p \in \partial H^k$, where $H^k = \mathbb{R}^{k-1} \times \{0\}$, meaning if g_1 and g_2 both extend F to

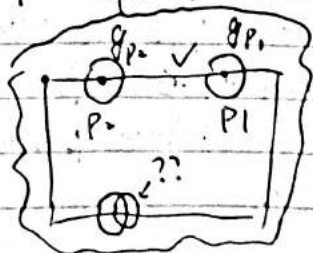
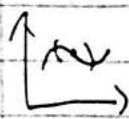
some open set, containing H^k , then $(dg_1)_p = (dg_2)_p$, so it makes sense to set $dF(p) = dg_1(p)$



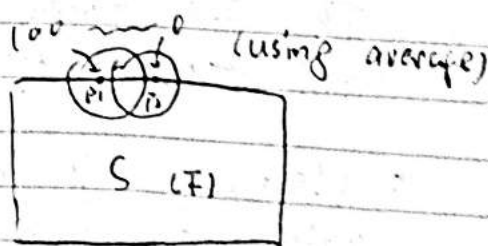
know that f_1, f_2 has derivative at p . can approach from x , which is independent of choosing f_1/f_2 .

Surprisingly hard fact: Differentiability on a set S is a "local property".

If $F: S \rightarrow \mathbb{R}^m$ has the property that for every $p \in S$, there is a nbd U_p and a differentiable function $g_p: U_p \rightarrow \mathbb{R}^m$ such that $F|_{S \cap U_p} = g_p|_{S \cap U_p}$, then F is differentiable on S , so:



→



* p_1, p_2 are close: $g_1 \neq g_2$ outside S .

Partition of Unity Lemma (Actually big theorem)

Given a collection \mathcal{A} of open sets in \mathbb{R}^n , whose overall union is $A = \bigcup_{U \in \mathcal{A}} U$, there exist a sequence $\{\phi_i\}$ of

non-negative compactly supported $\phi: \mathbb{R}^n \rightarrow \mathbb{R}$ functions such that the following holds

[Explanation: Supported $\phi: \text{Supp}(\phi) = \overline{\{x: \phi(x) \neq 0\}}$
compactly supported: $\text{Supp}(\phi)$ is compact.]

1. $\text{Supp}(\phi) \subset A$

2. something technical, next class

3. each supported ϕ_i is contained in one $U \in \mathcal{A}$

4. $\sum \phi_i(x) = 1$