

$$f(a+h) = f(a) + Df(a) \cdot h + o(h)$$

Class C^r : The first r derivatives exist and are cts.

Thm: If $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is C^2 , then $\partial_i := \frac{\partial}{\partial x_i}$

$$\partial_i \partial_j f = \partial_j \partial_i f$$

e.g.:

$$\begin{array}{ccc} & x^2 y & \\ \partial_x \swarrow & & \searrow \partial_y \\ xy & & x^2 \\ \partial_y \downarrow & & \swarrow \partial_x \\ 2x & & \end{array}$$

e.g.: $f(h, k)$ s.t.

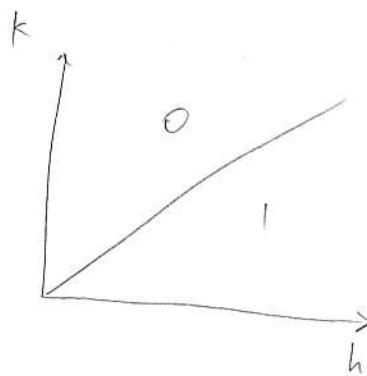
$$\lim_{h \rightarrow 0} \lim_{k \rightarrow 0} f(h, k) \neq \lim_{k \rightarrow 0} \lim_{h \rightarrow 0} f(h, k)$$

$$f(h, k) = \begin{cases} 0 & h \leq k \\ 1 & h > k \end{cases}$$

$$1 = \lim_{h \rightarrow 0} \underbrace{\lim_{k \rightarrow 0} f(h, k)}_{=1}$$

$$\neq \lim_{k \rightarrow 0} \underbrace{\lim_{h \rightarrow 0} f(h, k)}_{=0}$$

$$= 0$$



Lem: $\forall h, \exists p, q \in [x_0, x_0+h] \times [y_0, y_0+h]$

$$\partial_x \partial_y f(p) = \frac{f(x_0, y_0) - f(x_0+h, y_0) - f(x_0, y_0+h) + f(x_0+h, y_0+h)}{h^2} = (\partial_y \partial_x f)(q)$$

\downarrow

P $\rightarrow \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$

$h \rightarrow 0$

f $\rightarrow \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$

$$(\partial_x \partial_y f)(\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}) = (\partial_y \partial_x f)(\begin{pmatrix} x_0 \\ y_0 \end{pmatrix})$$

if φ cts,

$$\lim_{h \rightarrow 0} \lim_{k \rightarrow 0} \varphi(h, k) = \lim_{k \rightarrow 0} \lim_{h \rightarrow 0} \varphi(h, k)$$

$$\varphi(h, k) = \frac{f(x_0, y_0) - f(x_0+h, y_0) - f(x_0, y_0+h) + \dots}{h+k}$$

pf: let $g(x) = \frac{f(x, y_0+h) - f(x, y_0)}{h}, \lambda = \frac{g(x_0+h) - g(x_0)}{h}$

By MVT, $\exists x \in [x_0, x_0+h]$ s.t.

$$\begin{aligned} \lambda &= g'(x, 1) \\ &= \frac{\partial_x f(x, y_0+h) - \overbrace{\partial_x f(x, y_0)}^{x}}{h} \end{aligned}$$

$$z(y) = \partial_x f(x, y)$$

By MVT
for z , $\frac{\partial z}{\partial y} = \partial_y z(y, 1)$

$$= \partial_y \partial_x f(x, y)$$

Set $p = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$. Do the same with $x \leftrightarrow y$.

Find q

□