

Pensieve header: Notebook for DBN Lecture 3 in Matemale, April 2018. See <http://www.math.toronto.edu/~drorbn/Talks/Matemale-1804/>.

Today. First Dror, then Roland.

Unrelated Question. Anybody wants a French (azerty) keyboard for a surface pro?

Before we Start...

Please think about our Partial To do List!

A Partial To Do List.

- Complete all “docility” arguments by identifying a “contained” docile substructure.
- Understand denominators and get rid of them.
- See if much can be gained by including P in the exponential: $\mathbb{Q}^{L+Q} P \sim \mathbb{Q}^{L+Q+P}$?
- Clean the program and make it efficient.
- Run it for all small knots and links, at $k = 2, 3$.
- Understand the centre and figure out how to read the output.
- Execute the Drinfel’d double procedure at \mathbb{B} -level (and thus get rid of `DeclareAlgebra` and all that is around it!).
- Extend to sl_3 and beyond.
- Do everything with `Zip` and `Bind` as the fundamentals, without ever referring back to (quantized) Lie algebras.
- Prove a genus bound and a Seifert formula.
- Obtain “Gauss-Gassner formulas” ($\omega\epsilon\beta$ /NCSU).
- Relate with Melvin-Morton-Rozansky and with Rozansky-Overbay.
- Understand the braid group representations that arise.
- Find a topological interpretation. The Garoufalidis-Rozansky “loop expansion” [GR]?
- Figure out the action of the Cartan automorphism.
- Disprove the ribbon-slice conjecture!
- Figure out the action of the Weyl group.
- Do everything at the “arrow diagram” level of finite-type invariants of (rotational) virtual tangles.
- What else can you do with the “solvable approximations”?
- And with the “Gaussian zip and bind” technology?

Recall the Zipping Formula...

The Zipping / Contraction Theorem. If P has a finite ζ -degree and the y ’s and the q ’s are “small” then

$$\left\langle P(z_i, \zeta^j) e^{\eta^i z_i + y_j \zeta^j} \right\rangle_{(\zeta^j)} = \left\langle P(z_i + y_i, \zeta^j) e^{\eta^i (z_i + y_i)} \right\rangle_{(\zeta^j)},$$

(proof: replace $y_j \rightarrow \hbar y_j$ and test at $\hbar = 0$ and at ∂_{\hbar}), and

$$\begin{aligned} \left\langle P(z_i, \zeta^j) e^{c + \eta^i z_i + y_j \zeta^j + q_j^i z_i \zeta^j} \right\rangle_{(\zeta^j)} \\ = \det(\tilde{q}) \left\langle P(\tilde{q}_i^k (z_k + y_k), \zeta^j) e^{c + \eta^i \tilde{q}_i^k (z_k + y_k)} \right\rangle_{(\zeta^j)} \end{aligned}$$

where \tilde{q} is the inverse matrix of $1 - q$: $(\delta_j^i - q_j^i) \tilde{q}_k^j = \delta_k^i$ (proof: replace $q_j^i \rightarrow \hbar q_j^i$ and test at $\hbar = 0$ and at ∂_{\hbar}).

... and that we only need to compute operations on exponentials...

Proposition. If $F: \mathcal{S}(B) \rightarrow \mathcal{S}(B')$ is linear and “continuous”, then ${}^t F = \exp\left(\sum_{z_i \in B} \zeta_i z_i\right) // F$.

Our Algebra QU

$QU = \langle y, a, x, t \rangle$, with t central and subject to the relations $[a, x] = \gamma x$, $[a, y] = -\gamma y$, and $xy - qyx = \frac{1-TA^2}{\hbar}$, where $q = e^{\hbar\gamma\epsilon}$, $T = e^{\hbar t}$ ($t = \epsilon a - \gamma b$, as Roland derived the algebra), and $A = e^{-\hbar\epsilon a}$. For convenience we set $\mathcal{A} = e^{\gamma\epsilon}$.

QU has a co-product Δ and an antipode S given by

$$\begin{aligned} \Delta(y,a,x,t) &= (y_1 + T_1 y_2 A_1, a_1 + a_2, x_1 + A_1 x_2) \\ S(y,a,x,t) &= (-T^{-1} A^{-1} y, -a, -A^{-1} x, -t) \end{aligned}$$

The Program

Initialization / Utilities

DeclareAlgebra

DeclareMorphism

Meta-Operations

Implementing $CU = \mathcal{U}(\mathfrak{sl}_2^{\gamma\epsilon})$

Implementing $QU = \mathcal{U}_q(\mathfrak{sl}_2^{\gamma\epsilon})$

The representation ρ

tSW

The 2D Lie Algebra. Clever people know* that if $[a, x] = \gamma x$ then $e^{\xi x} e^{\alpha a} = e^{\alpha a} e^{e^{-\gamma\alpha} \xi x}$. Ergo with

$$SW_{ax} \left(\begin{array}{c} \curvearrowright \\ \mathcal{S}(a, x) \end{array} \begin{array}{c} \xrightarrow{\mathbb{O}_{ax}} \\ \xrightarrow{\mathbb{O}_{xa}} \end{array} \mathcal{U}(a, x) \right)$$

we have ${}^tSW_{ax} = e^{\alpha a + e^{-\gamma\alpha} \xi x}$.

* Indeed $xa = (a - \gamma)x$ thus $xa^n = (a - \gamma)^n x$ thus $x e^{\alpha a} = e^{\alpha(a-\gamma)} x = e^{-\gamma\alpha} e^{\alpha a} x$ thus $x^n e^{\alpha a} = e^{\alpha a} (e^{-\gamma\alpha})^n x^n$ thus $e^{\xi x} e^{\alpha a} = e^{\alpha a} e^{e^{-\gamma\alpha} \xi x}$.

Goal. In either U , compute $F = e^{-\eta y} e^{\xi x} e^{\eta y} e^{-\xi x}$. First compute $G = e^{\xi x} y e^{-\xi x}$, a finite sum. Now F satisfies the ODE $\partial_\eta F = \partial_\eta (e^{-\eta y} e^{\eta G}) = -yF + FG$ with initial conditions $F(\eta = 0) = 1$. So we set it up and solve:

In[]:=

```

SWxy[U_, kk_] :=
  SWxy[U, kk] = Block[{ $U = U, $k = kk, $p = kk}, Module[{G, F, fs, f, bs, e, b, es},
    G = Simp[Table[ξk/k!, {k, 0, $k + 1}].NestList[Simp[B[xU, #]] &, yU, $k + 1]];
    fs = Flatten@Table[fi,i,j,k[η], {1, 0, $k}, {i, 0, 1}, {j, 0, 1}, {k, 0, 1}];
    F = fs.(bs = fs /. fL_,i_,j_,k_[η] := εL U@{yi, aj, xk});
    es = Flatten[
      Table[Coefficient[e, b] == 0, {e, {F - 1U /. η → 0, F ** G - yU ** F - ∂ηF}}, {b, bs}]];
    F = F /. DSolve[es, fs, η][[1]];
    E[0,
      ξ x + η y + (U /. {CU → -t η ξ, QU → η ξ (1 - T) / ħ}),
      F + 0$k /. {e → 1, U → Times}
    ] /. (v : η | ξ | t | T | y | a | x) → v1
  ]];
tSWxy[_i_, _j_ → k_] := SWxy[$U, $k] /. {ξ1 → ξi, η1 → ηj, (v : t | T | y | a | x)1 → vk};
tSWxa[_i_, _j_ → k_] := E[αj ak, e-γ αj ξi xk, 1];
tSWay[_i_, _j_ → k_] := E[αi ak, e-γ αi ηj yk, 1];

```

Exponentials as needed.

Task. Define $\text{Exp}_{U_i,k}[\xi, P]$ which computes $e^{\xi Q(P)}$ to ϵ^k in the algebra U_i , where ξ is a scalar, X is x_i or y_i , and P is an ϵ -dependent near-docile element, giving the answer in \mathbb{E} -form. Should satisfy

$$U @ \text{Exp}_{U_i,k}[\xi, P] == \mathbb{S}_U[e^{\xi X}, X \rightarrow Q(P)].$$

Methodology. If $P_0 := P_{\epsilon=0}$ and $e^{\xi Q(P)} = \mathcal{O}(e^{\xi P_0} F(\xi))$, then $F(\xi = 0) = 1$ and we have:

$$\mathcal{O}(e^{\xi P_0}(P_0 F(\xi) + \partial_\xi F)) = \mathcal{O}(\partial_\xi e^{\xi P_0} F(\xi)) = \partial_\xi \mathcal{O}(e^{\xi P_0} F(\xi)) = \partial_\xi e^{\xi Q(P)} = e^{\xi Q(P)} \mathcal{O}(P) = \mathcal{O}(e^{\xi P_0} F(\xi)) \mathcal{O}(P).$$

This is an ODE for F . Setting inductively $F_k = F_{k-1} + \epsilon^k \varphi$ we find that $F_0 = 1$ and solve for φ .

In[]:=

```

(* Bug: The first line is valid only if 0 (eP0) == e0 (P0). *)
(* Bug: ξ must be a symbol. *)
ExpU_i,0[_ξ_, P_] := Module[{LQ = Normal@P /. ε → 0},
  E[ξ LQ /. (x | y)i → 0, ξ LQ /. (t | a)i → 0, 1]];
ExpU_i,k[_ξ_, P_] := Block[{ $U = U, $k = k},
  Module[{P0, φ, φs, F, j, rhs, at0, atξ},
    P0 = Normal@P /. ε → 0;
    φs =
      Flatten@Table[φj1,j2,j3[ξ], {j2, 0, k}, {j1, 0, 2k + 1 - j2}, {j3, 0, 2k + 1 - j2 - j1}];
    F = Normal@Last@ExpU_i,k-1[_ξ_, P] + εk φs.(φs /. φjs_[ξ] := Times@@{yi, ai, xi}{js});
    rhs = Normal@
      Last@mi,j→i[E[ξ P0 /. (x | y)i → 0, ξ P0 /. (t | a)i → 0, F + 0k] mi→j@E[0, 0, P + 0k]];
    at0 = (# == 0) & /@ Flatten@CoefficientList[F - 1 /. ξ → 0, {yi, ai, xi}];
    atξ = (# == 0) & /@ Flatten@CoefficientList[(∂ξF) + P0 F - rhs, {yi, ai, xi}];
    E[ξ P0 /. (x | y)i → 0, ξ P0 /. (t | a)i → 0, F + 0k] /.
      DSolve[And@@(at0 | atξ), φs, ξ][[1]]
  ]

```

Zip and Bind

Tensorial Representations

Alternative Algorithms

New Utilities (not on handout)

$$\text{In[*]:= } \alpha 2 \mathcal{A} = \{e^{c \cdot \alpha_i + b \cdot} \rightarrow \mathcal{A}_i^{c/\gamma} e^b, e^{c \cdot \alpha + b \cdot} \rightarrow \mathcal{A}^{c/\gamma} e^b, e^{\mathcal{E}} \rightarrow e^{\text{Expand}[\mathcal{E}]} \};$$

Some Runs

The Structure Tensors

$$\text{In[*]:= } \mathbf{\$k} = \mathbf{1}; \quad \gamma = \mathbf{1};$$

$$\text{In[*]:= } \mathbf{tm}_{1,2 \rightarrow 3} \quad // \quad \alpha 2 \mathcal{A}$$

$$\begin{aligned} \text{Out[*]:= } & \mathbb{E} \left[\mathbf{a}_3 \alpha_1 + \mathbf{a}_3 \alpha_2 + \mathbf{t}_3 (\tau_1 + \tau_2), \mathbf{y}_3 \eta_1 + \frac{\mathbf{y}_3 \eta_2}{\mathcal{A}_1} + \frac{\mathbf{x}_3 \xi_1}{\mathcal{A}_2} + \frac{(1 - \mathbf{T}_3) \eta_2 \xi_1}{\hbar} + \mathbf{x}_3 \xi_2, \right. \\ & 1 + \frac{1}{4 \hbar} \eta_2 \xi_1 \left(8 \hbar \mathbf{a}_3 \mathbf{T}_3 + \frac{4 \hbar^2 \mathbf{x}_3 \mathbf{y}_3}{\mathcal{A}_1 \mathcal{A}_2} + \frac{2 \hbar \mathbf{y}_3 \eta_2}{\mathcal{A}_1} - \frac{6 \hbar \mathbf{T}_3 \mathbf{y}_3 \eta_2}{\mathcal{A}_1} + \right. \\ & \left. \left. \frac{2 \hbar \mathbf{x}_3 \xi_1}{\mathcal{A}_2} - \frac{6 \hbar \mathbf{T}_3 \mathbf{x}_3 \xi_1}{\mathcal{A}_2} + \eta_2 \xi_1 - 4 \mathbf{T}_3 \eta_2 \xi_1 + 3 \mathbf{T}_3^2 \eta_2 \xi_1 \right) \right] \in + \mathbf{O}[\epsilon]^2 \end{aligned}$$

But that's not the form we like! Let's open **Zip and Bind!**

How was it computed? Let's open the **tSW** box!

$$\text{In[*]:= } \mathbf{tS}_1$$

$$\begin{aligned} \text{Out[*]:= } & \mathbb{E} \left[-\mathbf{a}_1 \alpha_1 - \mathbf{t}_1 \tau_1, \frac{1}{\hbar \mathbf{T}_1} \left(-e^{\alpha_1} \hbar \mathbf{y}_1 \eta_1 - e^{\alpha_1} \hbar \mathbf{T}_1 \mathbf{x}_1 \xi_1 + e^{\alpha_1} \eta_1 \xi_1 - e^{\alpha_1} \mathbf{T}_1 \eta_1 \xi_1 \right), \right. \\ & 1 + \frac{1}{4 \hbar \mathbf{T}_1^2} \left(4 e^{\alpha_1} \hbar^2 \mathbf{T}_1 \mathbf{y}_1 \eta_1 - 4 e^{\alpha_1} \hbar^2 \mathbf{a}_1 \mathbf{T}_1 \mathbf{y}_1 \eta_1 - 2 e^{2 \alpha_1} \hbar^2 \mathbf{y}_1^2 \eta_1^2 - 4 e^{\alpha_1} \hbar^2 \mathbf{a}_1 \mathbf{T}_1^2 \mathbf{x}_1 \xi_1 - \right. \\ & 4 e^{\alpha_1} \hbar \mathbf{T}_1 \eta_1 \xi_1 + 8 e^{\alpha_1} \hbar \mathbf{a}_1 \mathbf{T}_1 \eta_1 \xi_1 + 4 e^{\alpha_1} \hbar \mathbf{T}_1^2 \eta_1 \xi_1 - 4 e^{2 \alpha_1} \hbar^2 \mathbf{T}_1 \mathbf{x}_1 \mathbf{y}_1 \eta_1 \xi_1 + \\ & 6 e^{2 \alpha_1} \hbar \mathbf{y}_1 \eta_1^2 \xi_1 - 2 e^{2 \alpha_1} \hbar \mathbf{T}_1 \mathbf{y}_1 \eta_1^2 \xi_1 - 2 e^{2 \alpha_1} \hbar^2 \mathbf{T}_1^2 \mathbf{x}_1^2 \xi_1^2 + 6 e^{2 \alpha_1} \hbar \mathbf{T}_1 \mathbf{x}_1 \eta_1 \xi_1^2 - \\ & \left. \left. 2 e^{2 \alpha_1} \hbar \mathbf{T}_1^2 \mathbf{x}_1 \eta_1 \xi_1^2 - 3 e^{2 \alpha_1} \eta_1^2 \xi_1^2 + 4 e^{2 \alpha_1} \mathbf{T}_1 \eta_1^2 \xi_1^2 - e^{2 \alpha_1} \mathbf{T}_1^2 \eta_1^2 \xi_1^2 \right) \right] \in + \mathbf{O}[\epsilon]^2 \end{aligned}$$

How was it computed? Let's open **Exponentials as Needed!**

$$\text{In[*]:= } \mathbf{t}\Delta_{1 \rightarrow 1,2}$$

$$\begin{aligned} \text{Out[*]:= } & \mathbb{E} \left[(\mathbf{a}_1 + \mathbf{a}_2) \alpha_1 + (\mathbf{t}_1 + \mathbf{t}_2) \tau_1, \mathbf{y}_1 \eta_1 + \mathbf{T}_1 \mathbf{y}_2 \eta_1 + \mathbf{x}_1 \xi_1 + \mathbf{x}_2 \xi_1, \right. \\ & 1 + \frac{1}{2} \left(-2 \hbar \mathbf{a}_1 \mathbf{T}_1 \mathbf{y}_2 \eta_1 + \hbar \mathbf{T}_1 \mathbf{y}_1 \mathbf{y}_2 \eta_1^2 - 2 \hbar \mathbf{a}_1 \mathbf{x}_2 \xi_1 + \hbar \mathbf{x}_1 \mathbf{x}_2 \xi_1^2 \right) \right] \in + \mathbf{O}[\epsilon]^2 \end{aligned}$$

$$\text{In[*]} := \{\mathbf{tR}_{1,2}, \overline{\mathbf{tR}}_{1,2}\}$$

$$\text{Out[*]} := \left\{ \mathbb{E} \left[-\hbar \mathbf{a}_2 \mathbf{t}_1, \hbar \mathbf{x}_2 \mathbf{y}_1, \mathbf{1} + \left(\hbar \mathbf{a}_1 \mathbf{a}_2 - \frac{1}{4} \hbar^3 \mathbf{x}_2^2 \mathbf{y}_1^2 \right) \epsilon + \mathcal{O}[\epsilon^2] \right], \right. \\ \left. \mathbb{E} \left[\hbar \mathbf{a}_2 \mathbf{t}_1, -\frac{\hbar \mathbf{x}_2 \mathbf{y}_1}{\mathbf{T}_1}, \mathbf{1} + \frac{1}{4 \mathbf{T}_1^2} \left(-4 \hbar \mathbf{a}_1 \mathbf{a}_2 \mathbf{T}_1^2 - 4 \hbar^2 \mathbf{a}_1 \mathbf{T}_1 \mathbf{x}_2 \mathbf{y}_1 - 4 \hbar^2 \mathbf{a}_2 \mathbf{T}_1 \mathbf{x}_2 \mathbf{y}_1 - 3 \hbar^3 \mathbf{x}_2^2 \mathbf{y}_1^2 \right) \epsilon + \mathcal{O}[\epsilon^2] \right] \right\}$$

$$\text{In[*]} := \{\mathbf{tC}_1, \overline{\mathbf{tC}}_2\}$$

$$\text{Out[*]} := \left\{ \mathbb{E} \left[\mathbf{0}, \mathbf{0}, \sqrt{\mathbf{T}_1} - \hbar \mathbf{a}_1 \sqrt{\mathbf{T}_1} \epsilon + \mathcal{O}[\epsilon^2] \right], \mathbb{E} \left[\mathbf{0}, \mathbf{0}, \frac{1}{\sqrt{\mathbf{T}_2}} + \frac{\hbar \mathbf{a}_2 \epsilon}{\sqrt{\mathbf{T}_2}} + \mathcal{O}[\epsilon^2] \right] \right\}$$

Some Testing

Associativity of tm.

$$\text{In[*]} := \mathbf{tm}_{1,2 \rightarrow 2} \sim \mathbf{B}_2 \sim \mathbf{tm}_{2,3 \rightarrow 1}$$

$$\text{Out[*]} := \mathbb{E} \left[\mathbf{a}_1 \alpha_1 + \mathbf{a}_1 \alpha_2 + \mathbf{a}_1 \alpha_3 + \mathbf{t}_1 \tau_1 + \mathbf{t}_1 \tau_2 + \mathbf{t}_1 \tau_3, \right. \\ \frac{1}{\hbar} e^{-\alpha_1 - \alpha_2 - \alpha_3} \left(e^{\alpha_1 + \alpha_2 + \alpha_3} \hbar \mathbf{y}_1 \eta_1 + e^{\alpha_2 + \alpha_3} \hbar \mathbf{y}_1 \eta_2 + e^{\alpha_3} \hbar \mathbf{y}_1 \eta_3 + e^{\alpha_1} \hbar \mathbf{x}_1 \xi_1 + e^{\alpha_1 + \alpha_2 + \alpha_3} \eta_2 \xi_1 - e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_2 \xi_1 + \right. \\ \left. e^{\alpha_1 + \alpha_3} \eta_3 \xi_1 - e^{\alpha_1 + \alpha_3} \mathbf{T}_1 \eta_3 \xi_1 + e^{\alpha_1 + \alpha_2} \hbar \mathbf{x}_1 \xi_2 + e^{\alpha_1 + \alpha_2 + \alpha_3} \eta_3 \xi_2 - e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_3 \xi_2 + e^{\alpha_1 + \alpha_2 + \alpha_3} \hbar \mathbf{x}_1 \xi_3 \right), \\ \left. \mathbf{1} + \frac{1}{4 \hbar} e^{-\alpha_1 - 2 \alpha_2 - \alpha_3} \left(8 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \hbar \mathbf{a}_1 \mathbf{T}_1 \eta_2 \xi_1 + 4 e^{\alpha_2} \hbar^2 \mathbf{x}_1 \mathbf{y}_1 \eta_2 \xi_1 + 2 e^{2 \alpha_2 + \alpha_3} \hbar \mathbf{y}_1 \eta_2^2 \xi_1 - \right. \right. \\ \left. \left. 6 e^{2 \alpha_2 + \alpha_3} \hbar \mathbf{T}_1 \mathbf{y}_1 \eta_2^2 \xi_1 + 8 e^{\alpha_1 + \alpha_2 + \alpha_3} \hbar \mathbf{a}_1 \mathbf{T}_1 \eta_3 \xi_1 + 4 \hbar^2 \mathbf{x}_1 \mathbf{y}_1 \eta_3 \xi_1 + 4 e^{\alpha_2 + \alpha_3} \hbar \mathbf{y}_1 \eta_2 \eta_3 \xi_1 - \right. \right. \\ \left. \left. 12 e^{\alpha_2 + \alpha_3} \hbar \mathbf{T}_1 \mathbf{y}_1 \eta_2 \eta_3 \xi_1 + 2 e^{\alpha_3} \hbar \mathbf{y}_1 \eta_3^2 \xi_1 - 6 e^{\alpha_3} \hbar \mathbf{T}_1 \mathbf{y}_1 \eta_3^2 \xi_1 + 2 e^{\alpha_1 + \alpha_2} \hbar \mathbf{x}_1 \eta_2 \xi_1^2 - \right. \right. \\ \left. \left. 6 e^{\alpha_1 + \alpha_2} \hbar \mathbf{T}_1 \mathbf{x}_1 \eta_2 \xi_1^2 + e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \eta_2^2 \xi_1^2 - 4 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_2^2 \xi_1^2 + 3 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \mathbf{T}_1^2 \eta_2^2 \xi_1^2 + 2 e^{\alpha_1} \hbar \mathbf{x}_1 \eta_3 \xi_1^2 - \right. \right. \\ \left. \left. 6 e^{\alpha_1} \hbar \mathbf{T}_1 \mathbf{x}_1 \eta_3 \xi_1^2 + 2 e^{\alpha_1 + \alpha_2 + \alpha_3} \eta_2 \eta_3 \xi_1^2 - 8 e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_2 \eta_3 \xi_1^2 + 6 e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1^2 \eta_2 \eta_3 \xi_1^2 + \right. \right. \\ \left. \left. e^{\alpha_1 + \alpha_3} \eta_3^2 \xi_1^2 - 4 e^{\alpha_1 + \alpha_3} \mathbf{T}_1 \eta_3^2 \xi_1^2 + 3 e^{\alpha_1 + \alpha_3} \mathbf{T}_1^2 \eta_3^2 \xi_1^2 + 8 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \hbar \mathbf{a}_1 \mathbf{T}_1 \eta_3 \xi_2 + 4 e^{\alpha_2} \hbar^2 \mathbf{x}_1 \mathbf{y}_1 \eta_3 \xi_2 + \right. \right. \\ \left. \left. 2 e^{\alpha_2 + \alpha_3} \hbar \mathbf{y}_1 \eta_3^2 \xi_2 - 6 e^{\alpha_2 + \alpha_3} \hbar \mathbf{T}_1 \mathbf{y}_1 \eta_3^2 \xi_2 + 4 e^{\alpha_1 + \alpha_2} \hbar \mathbf{x}_1 \eta_3 \xi_1 \xi_2 - 12 e^{\alpha_1 + \alpha_2} \hbar \mathbf{T}_1 \mathbf{x}_1 \eta_3 \xi_1 \xi_2 + \right. \right. \\ \left. \left. 2 e^{\alpha_1 + \alpha_2 + \alpha_3} \eta_3^2 \xi_1 \xi_2 - 8 e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_3^2 \xi_1 \xi_2 + 6 e^{\alpha_1 + \alpha_2 + \alpha_3} \mathbf{T}_1^2 \eta_3^2 \xi_1 \xi_2 + 2 e^{\alpha_1 + 2 \alpha_2} \hbar \mathbf{x}_1 \eta_3 \xi_2^2 - \right. \right. \\ \left. \left. 6 e^{\alpha_1 + 2 \alpha_2} \hbar \mathbf{T}_1 \mathbf{x}_1 \eta_3 \xi_2^2 + e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \eta_3^2 \xi_2^2 - 4 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \mathbf{T}_1 \eta_3^2 \xi_2^2 + 3 e^{\alpha_1 + 2 \alpha_2 + \alpha_3} \mathbf{T}_1^2 \eta_3^2 \xi_2^2 \right) \epsilon + \mathcal{O}[\epsilon^2] \right]$$

$$\text{In[*]} := \mathbf{tm}_{1,2 \rightarrow \text{fran}} \sim \mathbf{B}_{\text{fran}} \sim \mathbf{tm}_{\text{fran},3 \rightarrow 1} \equiv \mathbf{tm}_{2,3 \rightarrow 2} \sim \mathbf{B}_2 \sim \mathbf{tm}_{1,2 \rightarrow 1}$$

$$\text{Out[*]} := \text{True}$$

tS is an anti-homomorphism for tm.

$$\text{In[*]} := (\mathbf{tS}_1 \mathbf{tS}_2) \sim \mathbf{B}_{1,2} \sim \mathbf{tm}_{1,2 \rightarrow 1} \equiv \mathbf{tm}_{2,1 \rightarrow 1} \sim \mathbf{B}_1 \sim \mathbf{tS}_1$$

$$\text{Out[*]} := \text{True}$$

Testing convolution inverse:

$$\text{In[*]} := \mathbf{t\Delta}_{1 \rightarrow 1,2} \sim \mathbf{B}_1 \sim \mathbf{tS}_1 \sim \mathbf{B}_{1,2} \sim \mathbf{tm}_{1,2 \rightarrow 1}$$

$$\text{Out[*]} := \mathbb{E} \left[\mathbf{0}, \mathbf{0}, \mathbf{1} + \mathcal{O}[\epsilon]^2 \right]$$

Testing quasi-triangular axioms

$$\text{In[*]} := (\mathbf{t\Delta}_{1 \rightarrow 1,2} \mathbf{tR}_{3,4}) \sim \mathbf{B}_{1,2,3,4} \sim (\mathbf{tm}_{1,3 \rightarrow 1} \mathbf{tm}_{2,4 \rightarrow 2}) \equiv (\mathbf{t\Delta}_{1 \rightarrow 2,1} \mathbf{tR}_{3,4}) \sim \mathbf{B}_{1,2,3,4} \sim (\mathbf{tm}_{3,1 \rightarrow 1} \mathbf{tm}_{4,2 \rightarrow 2})$$

$$\text{Out[*]} := \text{True}$$

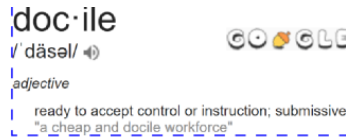
Testing R3

```
In[ ]:= (tr2,3 tr1,4 tr5,6) ~ B1,2,3,4,5,6 ~ (tm1,5→1 tm2,6→2 tm3,4→3) ≡
        (tr1,2 tr5,3 tr6,4) ~ B1,2,3,4,5,6 ~ (tm1,5→1 tm2,6→2 tm3,4→3)
```

Out[]:= True

Docility and why it matters:

Definition. A “docile perturbed Gaussian” in the variables $(z_i)_{i \in S}$ over the ring R is an expression of the form



$$e^{q^{ij} z_i z_j} P = e^{q^{ij} z_i z_j} \left(\sum_{k \geq 0} \epsilon^k P_k \right),$$

where all coefficients are in R and where P is a “docile series”: $\deg P_k \leq 4k$.

Docility Matters! The rank of the space of docile series to ϵ^k is polynomial in the number of variables $|S|$.

In our case our invariants and operations are of the form $e^{L+Q} P$, where

- L is a quadratic of the form $\sum l_{z\zeta} z\zeta$, where z runs over $\{t_i, \alpha_i\}_{i \in S}$ and ζ runs over $\{t_i, a_i\}_{i \in S}$, with integer coefficients $l_{z\zeta}$.
- Q is a quadratic of the form $\sum q_{z\zeta} z\zeta$, where z runs over $\{x_i, \eta_i\}_{i \in S}$ and ζ runs over $\{\xi_i, y_i\}_{i \in S}$, with coefficients $q_{z\zeta}$ in the ring R_S of rational functions in $(T_i)_{i \in S}$ and $(\mathcal{A}_i)_{i \in S}$.
- $P = \sum \epsilon^k P_k$ is a docile power series in $\{y_i, a_i, x_i, \eta_i, \xi_i\}_{i \in S}$, where $\deg(y_i, a_i, x_i, \eta_i, \xi_i) = (1, 2, 1, 1, 1)$.

The Trefoil

Seeing that our invariant is poly-time and the trefoil knot is tiny, the following will compute in no time at all:

```
In[ ]:= Timing@Block[{ $k = 1 },
    Z = tr1,5 tr6,2 tr3,7 tC4 tKink8 tKink9 tKink10;
    Do[Z = Z ~ B1,k ~ tm1,k→1, {k, 2, 10}]; Z]
```

```
Out[ ]:= {108.703,
    E[0, 0,  $\frac{T_1}{1 - T_1 + T_1^2} + ((-2 \hbar a_1 T_1 - \hbar T_1^2 + 2 \hbar a_1 T_1^2 + 2 \hbar T_1^3 - 3 \hbar T_1^4 - 2 \hbar a_1 T_1^4 + 2 \hbar T_1^5 + 2 \hbar a_1 T_1^5 - 2 \hbar^2 T_1 x_1 y_1 - 2 \hbar^2 T_1^4 x_1 y_1) \epsilon) / (1 - 3 T_1 + 6 T_1^2 - 7 T_1^3 + 6 T_1^4 - 3 T_1^5 + T_1^6) + O[\epsilon]^2$  ] }
```

```
In[*]:= Timing@Block[{$k = 1},
  Z = tR1,5 tR6,2 tR3,7  $\overline{tC_4}$   $\overline{tKink_8}$   $\overline{tKink_9}$   $\overline{tKink_{10}}$  /. T- → T1;
  Do[Z = Z ~ B1,k ~ tm1,k→1 /. T- → T1, {k, 2, 10}]; Z]
```

```
Out[*]:= {4.875, E[0, 0,
   $\frac{T_1}{1 - T_1 + T_1^2} + ((-2 \hbar a_1 T_1 - \hbar T_1^2 + 2 \hbar a_1 T_1^2 + 2 \hbar T_1^3 - 3 \hbar T_1^4 - 2 \hbar a_1 T_1^4 + 2 \hbar T_1^5 + 2 \hbar a_1 T_1^5 - 2 \hbar^2 T_1 x_1 y_1 - 2 \hbar^2 T_1^4 x_1 y_1) \epsilon) / (1 - 3 T_1 + 6 T_1^2 - 7 T_1^3 + 6 T_1^4 - 3 T_1^5 + T_1^6) + O[\epsilon]^2]}$ 
```