

Pensieve Header: Computing ρ_2 efficiently.

```
SetDirectory["~/AcademicPensieve/Talks/KnotTheoryCongress-2502/Rho2Data"];
<< "../../../Projects/KnotTheory/KnotTheory/init.m"
AppendTo[$Path, KnotTheoryDirectory[] = "../../../Projects/KnotTheory"];
Print[$Path = Cases[$Path, _String]];
<< "../Rot.m"
```

Loading KnotTheory` version of October 29, 2024, 10:29:52.1301.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/ktc25/ap> to compute rotation numbers.

```
In[ ]:= T2z[p_] := Module[{q = Expand[p], n, c},
  If[q === 0, 0, c = Coefficient[q, T, n = Exponent[q, T]];
  c z^{2^n} + T2z[q - c (T^{1/2} - T^{-1/2})^{2^n}]]];
```

Pre-computing the Feynman Diagrams

```
In[ ]:= CF[ε_] := Expand@Collect[ε, g_, F] /. F → Factor;
```

```
In[ ]:= {p*, x*, π*, ξ*} = {π, ξ, p, x}; (u_{-i})^* := (u^*)_i;
```

```
In[ ]:= Zip[_][ε_] := ε;
Zip[{ε_, εs___}[ε_] := (Collect[ε // Zip[{εs}, ε] /. f_ . ε^{d_} → (D[f, {ε*, d}])) /. ε* → 0
```

```
In[ ]:= px2g[ε_] := CF@Module[{ps, xs, Q, α, β},
  ps = Union[Cases[ε, p_, ∞]]; xs = Union[Cases[ε, x_, ∞]];
  Q = Sum[p0* x0* g_{p0[[2]], x0[[2]}, {p0, ps}, {x0, xs}];
  Expand[Zip_{ps ∪ xs}[ε e^Q]]
]
```

```
In[ ]:= px2g[ $\frac{S}{2} (x_i (p_i - p_j) ((T^S - 1) x_i p_j + 2 (1 - p_j x_j)) - 1)$ ]
```

```
Out[ ]:=  $-\frac{S}{2} + S g_{i,i} - S g_{j,i} + S (-1 + T^S) g_{i,i} g_{j,i} - S g_{i,j} g_{j,i} - S (-1 + T^S) g_{j,i}^2 - S g_{i,i} g_{j,j} + 2 S g_{j,i} g_{j,j}$ 
```

From AcademicPensieve/Talks/Beijing-2407/More.nb:

```

In[*]:=
q[s_, i_, j_] := x_i (p_{i+1} - p_i) + x_j (p_{j+1} - p_j) + (T^s - 1) x_i (p_{i+1} - p_{j+1});
r1[s_, i_, j_] := \frac{S}{2} (x_i (p_i - p_j) ((T^s - 1) x_i p_j + 2 (1 - p_j x_j)) - 1);
r2[1, i_, j_] :=
(-6 p_i x_i + 6 p_j x_i - 3 (-1 + 3 T) p_i p_j x_i^2 + 3 (-1 + 3 T) p_j^2 x_i^2 + 4 (-1 + T) p_i^2 p_j x_i^3 -
2 (-1 + T) (5 + T) p_i p_j^2 x_i^3 + 2 (-1 + T) (3 + T) p_j^3 x_i^3 + 18 p_i p_j x_i x_j - 18 p_j^2 x_i x_j -
6 p_i^2 p_j x_i^2 x_j + 6 (2 + T) p_i p_j^2 x_i^2 x_j - 6 (1 + T) p_j^3 x_i^2 x_j - 6 p_i p_j^2 x_i x_j^2 + 6 p_j^3 x_i x_j^2) / 12;
r2[-1, i_, j_] :=
(-6 T^2 p_i x_i + 6 T^2 p_j x_i + 3 (-3 + T) T p_i p_j x_i^2 - 3 (-3 + T) T p_j^2 x_i^2 - 4 (-1 + T) T p_i^2 p_j x_i^3 +
2 (-1 + T) (1 + 5 T) p_i p_j^2 x_i^3 - 2 (-1 + T) (1 + 3 T) p_j^3 x_i^3 + 18 T^2 p_i p_j x_i x_j -
18 T^2 p_j^2 x_i x_j - 6 T^2 p_i^2 p_j x_i^2 x_j + 6 T (1 + 2 T) p_i p_j^2 x_i^2 x_j -
6 T (1 + T) p_j^3 x_i^2 x_j - 6 T^2 p_i p_j^2 x_i x_j^2 + 6 T^2 p_j^3 x_i x_j^2) / (12 T^2);
\gamma_1[\varphi_, k_] := \varphi (1/2 - x_k p_k);
\gamma_2[\varphi_, k_] := -\varphi^2 p_k x_k / 2;
\mathcal{L}[X_{i,j}[s_]] := T^{s/2} \mathbb{E}[q[s, i, j] + \epsilon r_1[s, i, j] + \epsilon^2 r_2[s, i, j] + \mathbf{0}[\epsilon]^3];
\mathcal{L}[C_k[\varphi_]] := T^{\varphi/2} \mathbb{E}[-x_k (p_k - p_{k+1}) + \epsilon \gamma_1[\varphi, k] + \epsilon^2 \gamma_2[\varphi, k] + \mathbf{0}[\epsilon]^3];
\mathcal{L}[K_] := (2 \pi)^{-\text{Features}[K][[1]]} \text{CF}[\mathcal{L} / \text{Features}[K][[2]]];
vs[K_] := \text{Union} @@ \text{Table}[\{p_i, x_i\}, \{i, \text{Features}[K][[1]]\}]

```

```

In[*]:=
F[X_{i,j}[1]] = px2g[r2[1, i, j] + \frac{r1[1, i, j]^2}{2}]

```

Out[*]=

$$\begin{aligned}
& \frac{1}{8} - g_{i,i} + g_{i,i}^2 + g_{j,i} + (-1 - 2T) g_{i,i} g_{j,i} + 5(-1 + T) g_{i,i}^2 g_{j,i} + 2 g_{i,j} g_{j,i} - 6 g_{i,i} g_{i,j} g_{j,i} + 2T g_{j,i}^2 - \\
& (-1 + T)(11 + T) g_{i,i} g_{j,i}^2 + 3(-1 + T)^2 g_{i,i}^2 g_{j,i}^2 + (6 + T) g_{i,j} g_{j,i}^2 - 6(-1 + T) g_{i,i} g_{i,j} g_{j,i}^2 + \\
& 2 g_{i,j}^2 g_{j,i}^2 + (-1 + T)(6 + T) g_{j,i}^3 - 6(-1 + T)^2 g_{i,i} g_{j,i}^3 + 6(-1 + T) g_{i,j} g_{j,i}^3 + 3(-1 + T)^2 g_{j,i}^4 + \\
& 2 g_{i,i} g_{j,j} - 3 g_{i,i}^2 g_{j,j} - 4 g_{j,i} g_{j,j} + 2(6 + T) g_{i,i} g_{j,i} g_{j,j} - 6(-1 + T) g_{i,i}^2 g_{j,i} g_{j,j} - \\
& 2 g_{i,j} g_{j,i} g_{j,j} + 8 g_{i,i} g_{i,j} g_{j,i} g_{j,j} - 3(3 + T) g_{j,i}^2 g_{j,j} + 18(-1 + T) g_{i,i} g_{j,i}^2 g_{j,j} - 12 g_{i,j} g_{j,i}^2 g_{j,j} - \\
& 12(-1 + T) g_{j,i}^3 g_{j,j} - g_{i,i} g_{j,j}^2 + 2 g_{i,i}^2 g_{j,j}^2 + 3 g_{j,i} g_{j,j}^2 - 12 g_{i,i} g_{j,i} g_{j,j}^2 + 12 g_{j,i}^2 g_{j,j}^2
\end{aligned}$$

$$\text{In[*]:= } F[X_{i,j}[-1]] = \text{px2g}\left[r_2[-1, i, j] + \frac{r_1[-1, i, j]^2}{2}\right]$$

Out[*]=

$$\begin{aligned} & \frac{1}{8} - g_{i,i} + g_{i,i}^2 + g_{j,i} - \frac{(2 + T) g_{i,i} g_{j,i}}{T} - \frac{5(-1 + T) g_{i,i}^2 g_{j,i}}{T} + 2 g_{i,j} g_{j,i} - 6 g_{i,i} g_{i,j} g_{j,i} + \frac{2 g_{j,i}^2}{T} + \\ & \frac{(-1 + T)(1 + 11T) g_{i,i} g_{j,i}^2}{T^2} + \frac{3(-1 + T)^2 g_{i,i}^2 g_{j,i}^2}{T^2} + \frac{(1 + 6T) g_{i,j} g_{j,i}^2}{T} + \frac{6(-1 + T) g_{i,i} g_{i,j} g_{j,i}^2}{T} + \\ & 2 g_{i,j}^2 g_{j,i}^2 - \frac{(-1 + T)(1 + 6T) g_{j,i}^3}{T^2} - \frac{6(-1 + T)^2 g_{i,i} g_{j,i}^3}{T^2} - \frac{6(-1 + T) g_{i,j} g_{j,i}^3}{T} + \frac{3(-1 + T)^2 g_{j,i}^4}{T^2} + \\ & 2 g_{i,i} g_{j,j} - 3 g_{i,i}^2 g_{j,j} - 4 g_{j,i} g_{j,j} + \frac{2(1 + 6T) g_{i,i} g_{j,i} g_{j,j}}{T} + \frac{6(-1 + T) g_{i,i}^2 g_{j,i} g_{j,j}}{T} - \\ & 2 g_{i,j} g_{j,i} g_{j,j} + 8 g_{i,i} g_{i,j} g_{j,i} g_{j,j} - \frac{3(1 + 3T) g_{j,i}^2 g_{j,j}}{T} - \frac{18(-1 + T) g_{i,i} g_{j,i}^2 g_{j,j}}{T} - \\ & 12 g_{i,j} g_{j,i}^2 g_{j,j} + \frac{12(-1 + T) g_{j,i}^3 g_{j,j}}{T} - g_{i,i} g_{j,j}^2 + 2 g_{i,i}^2 g_{j,j}^2 + 3 g_{j,i} g_{j,j}^2 - 12 g_{i,i} g_{j,i} g_{j,j}^2 + 12 g_{j,i}^2 g_{j,j}^2 \end{aligned}$$

$$\text{In[*]:= } \text{Short}[F[X_{i0,j0}[1] X_{i1,j1}[1]] = \text{px2g}[r_1[1, i0, j0] r_1[1, i1, j1]]]$$

Out[*]//Short=

$$\frac{1}{4} - \frac{g_{i0,i0}}{2} + \langle\langle 274 \rangle\rangle + 4 g_{j0,i0} g_{j0,i1} g_{j1,j0} g_{j1,j1}$$

$$\text{In[*]:= } \text{Short}[F[X_{i0,j0}[1] X_{i1,j1}[-1]] = \text{px2g}[r_1[1, i0, j0] r_1[-1, i1, j1]]]$$

Out[*]//Short=

$$-\frac{1}{4} + \frac{g_{i0,i0}}{2} - g_{i0,i1} g_{i1,i0} + \langle\langle 302 \rangle\rangle + 2 g_{i0,i0} g_{j0,i1} g_{j1,j0} g_{j1,j1} - 4 g_{j0,i0} g_{j0,i1} g_{j1,j0} g_{j1,j1}$$

$$\text{In[*]:= } \text{Short}[F[X_{i0,j0}[-1] X_{i1,j1}[-1]] = \text{px2g}[r_1[-1, i0, j0] r_1[-1, i1, j1]]]$$

Out[*]//Short=

$$\frac{1}{4} - \frac{g_{i0,i0}}{2} + \langle\langle 304 \rangle\rangle + 4 g_{j0,i0} g_{j0,i1} g_{j1,j0} g_{j1,j1}$$

$$\text{In[*]:= } F[C_k[1]] = \text{px2g}\left[\gamma_2[1, k] + \frac{\gamma_1[1, k]^2}{2}\right]$$

Out[*]=

$$\frac{1}{8} - g_{k,k} + g_{k,k}^2$$

$$\text{In[*]:= } F[C_k[-1]] = \text{px2g}\left[\gamma_2[-1, k] + \frac{\gamma_1[-1, k]^2}{2}\right]$$

Out[*]=

$$\frac{1}{8} - g_{k,k} + g_{k,k}^2$$

$$\text{In[*]:= } \mathbf{F[X_{i,j} [1] C_{R_} [1]] = px2g[r_1[1, i, j] \gamma_1[1, k]]}$$

$$\begin{aligned} \text{Out[*]=} & -\frac{1}{4} + \frac{g_{i,i}}{2} - \frac{g_{j,i}}{2} + \frac{1}{2} (-1 + T) g_{i,i} g_{j,i} - \frac{1}{2} g_{i,j} g_{j,i} + \frac{1}{2} (1 - T) g_{j,i}^2 - \\ & \frac{1}{2} g_{i,i} g_{j,j} + g_{j,i} g_{j,j} - g_{i,k} g_{k,i} + (1 - T) g_{i,k} g_{j,i} g_{k,i} + g_{i,k} g_{j,j} g_{k,i} + g_{j,k} g_{k,i} + \\ & (1 - T) g_{i,i} g_{j,k} g_{k,i} + g_{i,j} g_{j,k} g_{k,i} + 2 (-1 + T) g_{j,i} g_{j,k} g_{k,i} - 2 g_{j,j} g_{j,k} g_{k,i} + \\ & g_{i,k} g_{j,i} g_{k,j} + g_{i,i} g_{j,k} g_{k,j} - 2 g_{j,i} g_{j,k} g_{k,j} + \frac{g_{k,k}}{2} - g_{i,i} g_{k,k} + g_{j,i} g_{k,k} + \\ & (1 - T) g_{i,i} g_{j,i} g_{k,k} + g_{i,j} g_{j,i} g_{k,k} + (-1 + T) g_{j,i}^2 g_{k,k} + g_{i,i} g_{j,j} g_{k,k} - 2 g_{j,i} g_{j,j} g_{k,k} \end{aligned}$$

$$\text{In[*]:= } \mathbf{F[X_{i,j} [1] C_{R_} [-1]] = px2g[r_1[1, i, j] \gamma_1[-1, k]]}$$

$$\begin{aligned} \text{Out[*]=} & \frac{1}{4} - \frac{g_{i,i}}{2} + \frac{g_{j,i}}{2} + \frac{1}{2} (1 - T) g_{i,i} g_{j,i} + \frac{1}{2} g_{i,j} g_{j,i} + \frac{1}{2} (-1 + T) g_{j,i}^2 + \\ & \frac{1}{2} g_{i,i} g_{j,j} - g_{j,i} g_{j,j} + g_{i,k} g_{k,i} + (-1 + T) g_{i,k} g_{j,i} g_{k,i} - g_{i,k} g_{j,j} g_{k,i} - g_{j,k} g_{k,i} + \\ & (-1 + T) g_{i,i} g_{j,k} g_{k,i} - g_{i,j} g_{j,k} g_{k,i} - 2 (-1 + T) g_{j,i} g_{j,k} g_{k,i} + 2 g_{j,j} g_{j,k} g_{k,i} - \\ & g_{i,k} g_{j,i} g_{k,j} - g_{i,i} g_{j,k} g_{k,j} + 2 g_{j,i} g_{j,k} g_{k,j} - \frac{g_{k,k}}{2} + g_{i,i} g_{k,k} - g_{j,i} g_{k,k} + \\ & (-1 + T) g_{i,i} g_{j,i} g_{k,k} - g_{i,j} g_{j,i} g_{k,k} + (1 - T) g_{j,i}^2 g_{k,k} - g_{i,i} g_{j,j} g_{k,k} + 2 g_{j,i} g_{j,j} g_{k,k} \end{aligned}$$

$$\text{In[*]:= } \mathbf{F[X_{i,j} [-1] C_{R_} [1]] = px2g[r_1[-1, i, j] \gamma_1[1, k]]}$$

$$\begin{aligned} \text{Out[*]=} & \frac{1}{4} - \frac{g_{i,i}}{2} + \frac{g_{j,i}}{2} + \frac{(-1 + T) g_{i,i} g_{j,i}}{2 T} + \frac{1}{2} g_{i,j} g_{j,i} - \frac{(-1 + T) g_{j,i}^2}{2 T} + \\ & \frac{1}{2} g_{i,i} g_{j,j} - g_{j,i} g_{j,j} + g_{i,k} g_{k,i} - \frac{(-1 + T) g_{i,k} g_{j,i} g_{k,i}}{T} - g_{i,k} g_{j,j} g_{k,i} - g_{j,k} g_{k,i} - \\ & \frac{(-1 + T) g_{i,i} g_{j,k} g_{k,i}}{T} - g_{i,j} g_{j,k} g_{k,i} + \frac{2 (-1 + T) g_{j,i} g_{j,k} g_{k,i}}{T} + 2 g_{j,j} g_{j,k} g_{k,i} - \\ & g_{i,k} g_{j,i} g_{k,j} - g_{i,i} g_{j,k} g_{k,j} + 2 g_{j,i} g_{j,k} g_{k,j} - \frac{g_{k,k}}{2} + g_{i,i} g_{k,k} - g_{j,i} g_{k,k} - \\ & \frac{(-1 + T) g_{i,i} g_{j,i} g_{k,k}}{T} - g_{i,j} g_{j,i} g_{k,k} + \frac{(-1 + T) g_{j,i}^2 g_{k,k}}{T} - g_{i,i} g_{j,j} g_{k,k} + 2 g_{j,i} g_{j,j} g_{k,k} \end{aligned}$$

In[*]:= **F**[$X_{i,j}[-1]$ $C_{R_i}[-1]$] = px2g[r1[-1, i, j] $\gamma_1[-1, k]$]

Out[*]=

$$\begin{aligned}
 & -\frac{1}{4} + \frac{g_{i,i}}{2} - \frac{g_{j,i}}{2} - \frac{(-1 + T) g_{i,i} g_{j,i}}{2 T} - \frac{1}{2} g_{i,j} g_{j,i} + \frac{(-1 + T) g_{j,i}^2}{2 T} - \\
 & \frac{1}{2} g_{i,i} g_{j,j} + g_{j,i} g_{j,j} - g_{i,k} g_{k,i} + \frac{(-1 + T) g_{i,k} g_{j,i} g_{k,i}}{T} + g_{i,k} g_{j,j} g_{k,i} + g_{j,k} g_{k,i} + \\
 & \frac{(-1 + T) g_{i,i} g_{j,k} g_{k,i}}{T} + g_{i,j} g_{j,k} g_{k,i} - \frac{2 (-1 + T) g_{j,i} g_{j,k} g_{k,i}}{T} - 2 g_{j,j} g_{j,k} g_{k,i} + \\
 & g_{i,k} g_{j,i} g_{k,j} + g_{i,i} g_{j,k} g_{k,j} - 2 g_{j,i} g_{j,k} g_{k,j} + \frac{g_{k,k}}{2} - g_{i,i} g_{k,k} + g_{j,i} g_{k,k} + \\
 & \frac{(-1 + T) g_{i,i} g_{j,i} g_{k,k}}{T} + g_{i,j} g_{j,i} g_{k,k} - \frac{(-1 + T) g_{j,i}^2 g_{k,k}}{T} + g_{i,i} g_{j,j} g_{k,k} - 2 g_{j,i} g_{j,j} g_{k,k}
 \end{aligned}$$

In[*]:= **F**[$C_{R_{k0}}[1]$ $C_{k1}[1]$] = px2g[$\gamma_1[1, k0]$ $\gamma_1[1, k1]$]

Out[*]=

$$\frac{1}{4} - \frac{g_{k0,k0}}{2} + g_{k0,k1} g_{k1,k0} - \frac{g_{k1,k1}}{2} + g_{k0,k0} g_{k1,k1}$$

In[*]:= **F**[$C_{R_{k0}}[1]$ $C_{k1}[-1]$] = px2g[$\gamma_1[1, k0]$ $\gamma_1[-1, k1]$]

Out[*]=

$$-\frac{1}{4} + \frac{g_{k0,k0}}{2} - g_{k0,k1} g_{k1,k0} + \frac{g_{k1,k1}}{2} - g_{k0,k0} g_{k1,k1}$$

In[*]:= **F**[$C_{R_{k0}}[-1]$ $C_{k1}[-1]$] = px2g[$\gamma_1[-1, k0]$ $\gamma_1[-1, k1]$]

Out[*]=

$$\frac{1}{4} - \frac{g_{k0,k0}}{2} + g_{k0,k1} g_{k1,k0} - \frac{g_{k1,k1}}{2} + g_{k0,k0} g_{k1,k1}$$

A ρ_2 program

```

In[*]:=  $\rho_2[K_] := Module[{\{n, Fs, Xs, Cs, A, w, \phi, \Delta, G\},
  \{n, Fs\} = List @@ Features[K]; \{++n, Xs = Cases[Fs, X_][_], Cs = Cases[Fs, C_][_]\};
  A = IdentityMatrix[n]; w = \phi = 0;
  Xs /.  $X_{i,j}[s_] \Rightarrow (w += s; A[[\{i, j\}, \{i + 1, j + 1\}]] += \begin{pmatrix} -T^s & T^s - 1 \\ 0 & -1 \end{pmatrix});$ 
  Cs /.  $C_{R_\phi}[\phi_] \Rightarrow (\phi += \phi; A[[k, k + 1]] += -1);$ 
  \Delta =  $T^{-(\phi+w)/2} Det[A];$ 
  G = Inverse[A];
  Factor[ $2 \Delta^4 Total @ Factor[(F / @ Subsets[Fs, \{1, 2\}]) /. g_{\alpha,\beta} \Rightarrow G[\alpha, \beta]]]$ 
]$ 
```

```
In[*]:=  $\rho_2[\text{Knot}[3, 1]] // \text{T2z}$ 
```

```
Out[*]=  $2 - 4z^2 + 3z^4 + 4z^6 + z^8$ 
```

```
In[*]:= DunfieldKnots = ReadList["../../People/Dunfield/nmd_random_knots"] /. k_Integer -> k + 1;  
DK[n_] := DunfieldKnots[[n - 2]];
```

```
In[*]:=  $\rho_2[\text{DK}[3]] // \text{T2z}$ 
```

```
Out[*]=  $2 - 4z^2 + 3z^4 + 4z^6 + z^8$ 
```

```
In[*]:= AbsoluteTiming[ $\rho_2[\text{DK}[10]] // \text{T2z}$ ]
```

```
Out[*]= {0.72777,  
18 - 188 z^2 + 235 z^4 + 27 660 z^6 + 213 594 z^8 + 821 660 z^10 + 1 954 273 z^12 + 3 121 080 z^14 + 3 488 879 z^16 +  
2 791 080 z^18 + 1 613 408 z^20 + 673 212 z^22 + 200 257 z^24 + 41 304 z^26 + 5600 z^28 + 448 z^30 + 16 z^32}
```

```
In[*]:= AbsoluteTiming[ $\rho_2[\text{DK}[20]] // \text{T2z}$ ]
```

```
Out[*]= {9.0306, 6 - 36 z^2 + 137 z^4 + 684 z^6 - 1791 z^8 - 5096 z^10 + 1422 z^12 + 17 992 z^14 +  
27 682 z^16 - 18 008 z^18 - 57 311 z^20 - 37 936 z^22 + 21 378 z^24 + 70 060 z^26 + 44 443 z^28 -  
22 340 z^30 - 42 159 z^32 - 15 648 z^34 + 5483 z^36 + 7252 z^38 + 3030 z^40 + 672 z^42 + 80 z^44 + 4 z^46}
```

```
In[*]:= AbsoluteTiming[ $\rho_2[\text{DK}[30]] // \text{T2z}$ ]
```

```
Out[*]= {15.8729, 18 + 68 z^2 + 923 z^4 + 23 140 z^6 + 171 996 z^8 + 635 240 z^10 + 1 540 635 z^12 +  
2 631 544 z^14 + 4 066 922 z^16 + 9 460 936 z^18 + 27 345 191 z^20 + 64 880 584 z^22 + 126 266 074 z^24 +  
236 701 404 z^26 + 453 939 012 z^28 + 798 652 060 z^30 + 1 157 856 095 z^32 + 1 321 551 392 z^34 +  
1 168 261 597 z^36 + 790 184 656 z^38 + 401 546 393 z^40 + 148 778 040 z^42 + 38 549 286 z^44 +  
7 212 168 z^46 + 1 662 954 z^48 + 676 208 z^50 + 219 256 z^52 + 38 752 z^54 + 3360 z^56}
```

```
In[*]:= AbsoluteTiming[ $\rho_2$ [DK[100]] // T2z]
```

```
Out[*]=
```

$$\{1291.56, 34 - 1488 z^2 - 39548 z^4 + 10792 z^6 + 6833710 z^8 + 37437252 z^{10} - 658965945 z^{12} - 10119271592 z^{14} - 48325133574 z^{16} + 45188512768 z^{18} + 1623056339094 z^{20} + 8042542914076 z^{22} + 13862292743997 z^{24} - 42367394004452 z^{26} - 328639475841479 z^{28} - 882404199820520 z^{30} - 678734897597277 z^{32} + 2968778845001816 z^{34} + 13483687905184821 z^{36} + 53424952939386272 z^{38} + 261111433750380252 z^{40} + 893796479152524888 z^{42} + 908491620268861274 z^{44} - 7381286401581790692 z^{46} - 43829571230826922603 z^{48} - 116615001093219977808 z^{50} - 108551039981570119802 z^{52} + 429396631623058448676 z^{54} + 2300749537571497873155 z^{56} + 5834088556718901798572 z^{58} + 8742287978829460305042 z^{60} + 3993498361982634813196 z^{62} - 18080889302516101195176 z^{64} - 58803981399441041942560 z^{66} - 93703489310740333663047 z^{68} - 64798608219905577791124 z^{70} + 93311684654539439636594 z^{72} + 386441395637408144772028 z^{74} + 691311967013150282998277 z^{76} + 764621852353528805859752 z^{78} + 393981892304860346898846 z^{80} - 356737777026879287459532 z^{82} - 1002587760029621732082622 z^{84} - 821992142044076482857404 z^{86} + 610517509924259061381641 z^{88} + 2897927772963644056170416 z^{90} + 4844952255264945708133288 z^{92} + 5239595014022424564638868 z^{94} + 3864641961945495817201657 z^{96} + 1789584147863217802183116 z^{98} + 515312585443744008803160 z^{100} + 680984153458413027019624 z^{102} + 1587604611214351611193742 z^{104} + 1999078542660880921427784 z^{106} + 1345741423688618967472227 z^{108} + 112054426675992909636980 z^{110} - 809180314402316085439650 z^{112} - 949860317832176961547548 z^{114} - 497638085180674510602584 z^{116} + 49719287470682048547672 z^{118} + 315174300298616952503039 z^{120} + 238365667911770956838224 z^{122} + 11903825805629930779277 z^{124} - 133908640060649997199828 z^{126} - 120584724683583260100659 z^{128} - 30573577986680147242056 z^{130} + 29787342776252248291008 z^{132} + 33316926602725257170992 z^{134} + 13249578355492116209280 z^{136} - 466389804957125331968 z^{138} - 3474520182461126135009 z^{140} - 2199495177129275098632 z^{142} - 732062729882109656245 z^{144} + 60908557973391345752 z^{146} + 264443411436407131086 z^{148} + 150905870551228610632 z^{150} + 8263949831072721160 z^{152} - 40077705419978461732 z^{154} - 24796560868735382995 z^{156} - 3354736603841509844 z^{158} + 3789620594671053397 z^{160} + 2344996074617217784 z^{162} + 308247572187169218 z^{164} - 191143606999749796 z^{166} - 52763721834069815 z^{168} + 27781158896637420 z^{170} + 14714777332724951 z^{172} - 520843538566648 z^{174} - 1754643449107029 z^{176} - 247179575500996 z^{178} + 127730443998943 z^{180} + 52708567383940 z^{182} + 6213607654940 z^{184} - 250636503912 z^{186} - 83287401093 z^{188} + 3970217700 z^{190} + 1076058594 z^{192}\}$$

The Run

```
In[*]:= Table[n → NumberOfKnots[n], {n, 3, 15}]
```

```
Out[*]=
```

```
{3 → 1, 4 → 1, 5 → 2, 6 → 3, 7 → 7, 8 → 21, 9 → 49,
10 → 165, 11 → 552, 12 → 2176, 13 → 9988, 14 → 46972, 15 → 253293}
```

```
AbsoluteTiming[  
  Table[Echo[K] → T2z[ $\rho_2$ [K]], {K, AllKnots[{15, 15}}] >> "Rho2_15.m"  
]
```

```
Quit[]
```