

Pensieve header: Will it work with an imaginary integrand? (Maybe, but not here).

```
In[1]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Talks\\Groningen-240530"];
```

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## Preliminaries

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```
In[2]:= Once[<< KnotTheory` ; << Rot.m];
```

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Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.  
Read more at <http://katlas.org/wiki/KnotTheory>.

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Loading Rot.m from <http://drorbn.net/AP/Talks/Groningen-240530> to compute rotation numbers.

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```
In[3]:= CF[w_. \[Epsilon]_E] := CF[w] CF /@ \[Epsilon];
CF[\[Epsilon]_List] := CF /@ \[Epsilon];
CF[\[Epsilon]_] := Module[{vs, ps, c},
  vs = Cases[\[Epsilon], (x | p | \[Epsilon] | \[Pi])_, \[Infinity]] \[Union] {x, p, \[Epsilon]};
  Total[CoefficientRules[Expand[\[Epsilon]], vs] /. (ps_ \[Rule] c_) \[Rule] Factor[c] (Times @@ vs^ps)] ]];
```

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## Integration

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```
In[4]:= E /: E[A_] E[B_] := E[A + B];
```

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```
In[5]:= $\[Pi] = Identity; (* hacks in pink *)
```

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```
In[=]:= Unprotect[Integrate];

$$\int \omega_{\_} \cdot \mathbb{E}[L_{\_}] d(vs\_List) := \text{Module}\left[\{n, L0, Q, \Delta, G, Z0, Z, \lambda, DZ, FZ, a, b\},$$

  
$$n = \text{Length}@vs; L0 = L /. \epsilon \rightarrow 0;$$

  
$$Q = \text{Table}\left[(-\partial_{vs[[a]], vs[[b]]} L0) /. \text{Thread}[vs \rightarrow 0] /. (p | x) \rightarrow 0, \{a, n\}, \{b, n\}\right];$$

  
$$\text{If}[(\Delta = \text{Det}[Q]) == 0, \text{Return}@\text{"Degenerate Q!"};$$

  
$$Z = Z0 = \text{CF}@\$ \pi [L + vs.Q.vs / 2]; G = \text{Inverse}[Q];$$

  
$$DZ_{a\_} := \partial_{vs[[a]]} Z; DZ_{a\_, b\_] := \partial_{vs[[b]]} DZ_a;$$

  
$$FZ := \text{CF}@\$ \pi \left[ \frac{1}{2} \sum_{a=1}^n \sum_{b=1}^n G[[a, b]] (DZ_{a,b} + DZ_a DZ_b) \right];$$

  
$$\text{FixedPoint}\left[\left(Z = Z0 + \int_0^\lambda FZ d\lambda\right) \&, Z\right];$$

  
$$\text{PowerExpand}@\text{Factor}\left[\omega \Delta^{-1/2}\right] \mathbb{E}[\text{CF}[Z /. \lambda \rightarrow 1 /. \text{Thread}[vs \rightarrow 0]]];$$

Protect[Integrate];
```

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## The Right-Handed Trefoil

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```
In[=]:= K = Mirror@Knot[3, 1]; Features[K]
```

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**KnotTheory**: Loading precomputed data in PD4Knots`.

```
Out[=]=
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```

```
Features[7, C4[-1] X1,5[1] X3,7[1] X6,2[1]]
```

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```
In[=]:=  $\mathcal{L}[X_{i\_, j\_] [s\_]] := T^{s/2} \mathbb{E} \left[$ 
  
$$x_i (p_{i+1} - p_i) + x_j (p_{j+1} - p_j) + (T^s - 1) x_i (p_{i+1} - p_{j+1}) +$$

  
$$(\epsilon s / 2) \times (x_i (p_i - p_j) ((T^s - 1) x_i p_j + 2 (-x_j p_i)) + 1) \right]$$

 $\mathcal{L}[C_i[0]] := \mathbb{E}[x_i (p_{i+1} - p_i)];$ 
 $\mathcal{L}[C_i[1]] := T^{1/2} \mathbb{E}[x_i (p_{i+1} - p_i) + \epsilon (c_1 + c_2 x_i^2 p_i^2)];$ 
 $\mathcal{L}[C_i[-1]] := T^{-1/2} \mathbb{E}[x_i (p_{i+1} - p_i) + \epsilon (c_3 + c_4 x_i^2 p_i^2)];$ 
 $\mathcal{L}[K\_] := \text{CF}[\mathcal{L} /@ \text{Features}[K][2]]$ 
 $vs[K\_] := \text{Join} @@ \text{Table}[\{p_i, x_i\}, \{i, \text{Features}[K][1]\}]$ 
```

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In[ $\#$ ]:= {vs[K], L[K]}Out[ $\#$ ]= pdf

$$\left\{ \{p_1, x_1, p_2, x_2, p_3, x_3, p_4, x_4, p_5, x_5, p_6, x_6, p_7, x_7\}, \right. \\ T \mathbb{E} \left[ \frac{1}{2} \in (3 + 2 c_3) - p_1 x_1 + T p_2 x_1 + (1 - T) p_6 x_1 + \frac{1}{2} (-1 + T) \in p_1 p_5 x_1^2 + \frac{1}{2} (1 - T) \in p_5^2 x_1^2 - p_2 x_2 + \right. \\ p_3 x_2 - p_3 x_3 + T p_4 x_3 + (1 - T) p_8 x_3 + \frac{1}{2} (-1 + T) \in p_3 p_7 x_3^2 + \frac{1}{2} (1 - T) \in p_7^2 x_3^2 - p_4 x_4 + p_5 x_4 + \\ \in c_4 p_4^2 x_4^2 - p_5 x_5 + p_6 x_5 - \in p_1 p_5 x_1 x_5 + \in p_5^2 x_1 x_5 + (1 - T) p_3 x_6 - p_6 x_6 + T p_7 x_6 + \in p_2^2 x_2 x_6 - \\ \in p_2 p_6 x_2 x_6 + \frac{1}{2} (1 - T) \in p_2^2 x_6^2 + \frac{1}{2} (-1 + T) \in p_2 p_6 x_6^2 - p_7 x_7 + p_8 x_7 - \in p_3 p_7 x_3 x_7 + \in p_7^2 x_3 x_7 \left. \right]$$

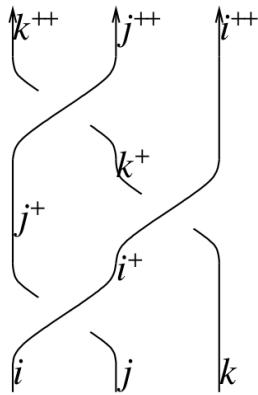
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In[ $\#$ ]:= \$π = Normal[\# + O[ε]^2] &; ∫ L[K] d(vs@K)Out[ $\#$ ]= pdf

$$- \frac{\frac{1}{2} T \mathbb{E} \left[ \frac{\in (-3 + 2 T + 3 T^2 - 4 T^3 + 3 T^4 + 2 c_3 - 4 T c_3 + 6 T^2 c_3 - 4 T^3 c_3 + 2 T^4 c_3 + 4 c_4)}{2 (1 - T + T^2)^2} \right]}{1 - T + T^2}$$

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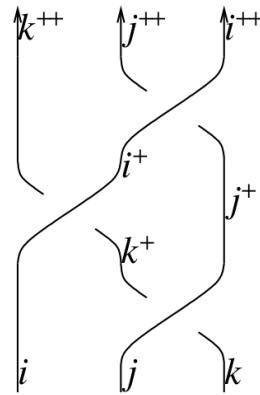
## Invariance Under Reidemeister 3



top variables

middle variables

bottom variables



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lhs = ∫ (E [i π\_i p\_i + i π\_j p\_j + i π\_k p\_k] L /@ (X\_{i,j}[1] X\_{i+1,k}[1] X\_{j+1,k+1}[1]))

d{p\_i, p\_j, p\_k, x\_i, x\_j, x\_k, p\_{i+1}, p\_{j+1}, p\_{k+1}, x\_{i+1}, x\_{j+1}, x\_{k+1}};

rhs = ∫ (E [i π\_i p\_i + i π\_j p\_j + i π\_k p\_k] L /@ (X\_{j,k}[1] X\_{i,k+1}[1] X\_{i+1,j+1}[1]))

d{p\_i, p\_j, p\_k, x\_i, x\_j, x\_k, p\_{i+1}, p\_{j+1}, p\_{k+1}, x\_{i+1}, x\_{j+1}, x\_{k+1}};

lhs == rhs

Out[ $\#$ ]= pdf

True

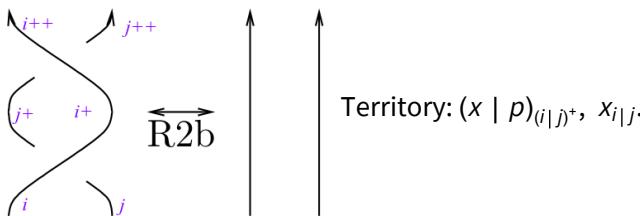
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In[1]:= lhs

Out[1]=

$$\begin{aligned}
& \mathbb{E} \left[ -\frac{3}{2} + \mathbb{1} T^2 p_{2+i} \pi_i - 2 \mathbb{1} T^2 \in p_{2+i} \pi_i - \mathbb{1} (-1+T) T p_{2+j} \pi_j + \mathbb{1} T (-1+3T) \in p_{2+j} \pi_j - \right. \\
& \mathbb{1} (-1+T) p_{2+k} \pi_k + 2 \mathbb{1} T \in p_{2+k} \pi_k - \frac{1}{2} (-1+T) T^3 \in p_{2+i} p_{2+j} \pi_i^2 + \frac{1}{2} (-1+T) T^3 \in p_{2+j}^2 \pi_i^2 - \\
& \frac{1}{2} (-1+T) T^2 \in p_{2+i} p_{2+k} \pi_i^2 + \frac{1}{2} (-1+T)^2 T \in p_{2+j} p_{2+k} \pi_i^2 + \frac{1}{2} (-1+T) T \in p_{2+k}^2 \pi_i^2 + \mathbb{1} T p_{2+j} \pi_j - \\
& 2 \mathbb{1} T \in p_{2+j} \pi_j - \mathbb{1} (-1+T) p_{2+k} \pi_j + \mathbb{1} (-1+3T) \in p_{2+k} \pi_j + T^3 \in p_{2+i} p_{2+j} \pi_i \pi_j - T^3 \in p_{2+j}^2 \pi_i \pi_j - \\
& (-1+T) T^2 \in p_{2+i} p_{2+k} \pi_i \pi_j + (-1+T)^2 T \in p_{2+j} p_{2+k} \pi_i \pi_j + (-1+T) T \in p_{2+k}^2 \pi_i \pi_j - \\
& \frac{1}{2} (-1+T) T \in p_{2+j} p_{2+k} \pi_j^2 + \frac{1}{2} (-1+T) T \in p_{2+k}^2 \pi_j^2 + \mathbb{1} p_{2+k} \pi_k - 2 \mathbb{1} \in p_{2+k} \pi_k + T^2 \in p_{2+i} p_{2+k} \pi_i \pi_k - \\
& (-1+T) T \in p_{2+j} p_{2+k} \pi_i \pi_k - T \in p_{2+k}^2 \pi_i \pi_k + T \in p_{2+j} p_{2+k} \pi_j \pi_k - T \in p_{2+k}^2 \pi_j \pi_k \left. \right]
\end{aligned}$$

## Invariance Under Reidemeister 2b

In[1]:= lhs =  $\int \mathbb{E} [\mathbb{1} \pi_i p_i + \mathbb{1} \pi_j p_j] \mathcal{L} /@ (\mathbf{x}_{i,j}[1] \mathbf{x}_{i+1,j+1}[-1]) \text{d}\{\mathbf{x}_i, \mathbf{x}_j, p_i, p_j, \mathbf{x}_{i+1}, \mathbf{x}_{j+1}, p_{i+1}, p_{j+1}\}$ 

rhs =

$$\int \mathbb{E} [\mathbb{1} \pi_i p_i + \mathbb{1} \pi_j p_j] \mathcal{L} /@ (\mathbf{c}_i[0] \mathbf{c}_{i+1}[0] \mathbf{c}_j[0] \mathbf{c}_{j+1}[0]) \text{d}\{\mathbf{x}_i, \mathbf{x}_j, p_i, p_j, \mathbf{x}_{i+1}, \mathbf{x}_{j+1}, p_{i+1}, p_{j+1}\};$$

lhs == rhs

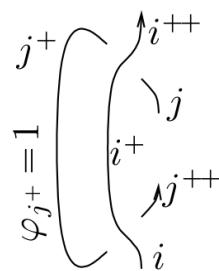
Out[1]=

$$\mathbb{E} [\mathbb{1} p_{2+i} \pi_i + \mathbb{1} p_{2+j} \pi_j]$$

Out[1]=

True

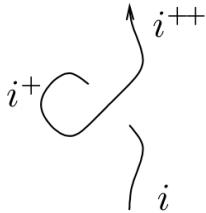
## Invariance Under R2c



```
In[1]:= lhs = Integrate[Expectation[Pi[i] p_i + Pi[j] p_j], {L /. {X_{i+1,j}[1] -> X_{i,j+2}[-1], C_{i+1}[1] -> C_{j+2}[1]}], {x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{j+2}, p_{j+2}}]
rhs = Integrate[Expectation[Pi[i] p_i + Pi[j] p_j], {L /. {C_i[0] -> C_{i+1}[0], C_j[0] -> C_{j+1}[1], C_{j+2}[0] -> C_{j+2}[1]}], {x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{j+2}, p_{j+2}}];
lhs == rhs

Out[1]=
- I Sqrt[T] Expectation[(c_1 + 2 c_2) + I p_{2+i} \pi_i - (I (-1 + T) (1 + 4 c_2) p_{3+j} \pi_i)/T - ((-1 + T)^2 c_2 p_{3+j}^2 \pi_i^2)/(T^2) + I p_{3+j} \pi_j + 4 I (c_2 p_{3+j} \pi_j + (2 (-1 + T) c_2 p_{3+j}^2 \pi_i \pi_j)/T) - c_2 p_{3+j}^2 \pi_j^2] == - I Sqrt[T] (c_1 + 2 c_2) + I p_{2+i} \pi_i - (I (-1 + T) (1 + 4 c_2) p_{3+j} \pi_i)/T - ((-1 + T)^2 c_2 p_{3+j}^2 \pi_i^2)/(T^2) + I p_{3+j} \pi_j + 4 I (c_2 p_{3+j} \pi_j + (2 (-1 + T) c_2 p_{3+j}^2 \pi_i \pi_j)/T) - c_2 p_{3+j}^2 \pi_j^2
```

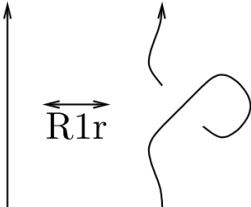
## Invariance Under R1



```
In[2]:= lhs = Integrate[Expectation[Pi[i] p_i], {L /. {X_{i+2,i}[1] -> C_{i+1}[1]}], {x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}}]
rhs = Integrate[Expectation[Pi[i] p_i], {L /. {C_i[0] -> C_{i+1}[0], C_{i+2}[0] -> C_{i+2}[0]}], {x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}}];
lhs == rhs

Out[2]=
- I E[(2 T + T^2 + 2 T^2 c_1 + 4 c_2)/2 T^2] + I p_{3+i} \pi_i + (I (T + 4 c_2) p_{3+i} \pi_i)/T^2 - (c_2 p_{3+i}^2 \pi_i^2)/T^2 == - I E[(2 T + T^2 + 2 T^2 c_1 + 4 c_2)/2 T^2] + I p_{3+i} \pi_i + (I (T + 4 c_2) p_{3+i} \pi_i)/T^2 - (c_2 p_{3+i}^2 \pi_i^2)/T^2 == - I E[I p_{3+i} \pi_i]
```

## Invariance Under R1r



```
In[1]:= lhs = Integrate[E^(I π i p_i) L /@ (x_{i,i+2}[1] C_{i+1}[-1]), {x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}}]
rhs = Integrate[E^(I π i p_i) L /@ (C_i[0] C_{i+1}[0] C_{i+2}[0]), {x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}}];
lhs == rhs
```

Out[1]=

$$-\frac{1}{2} \mathbb{E}\left[\frac{1}{2} \in (-1 + 2 c_3 + 4 c_4) + I p_{3+i} \pi_i + I T \in (-1 + 4 c_4) p_{3+i} \pi_i - T^2 \in c_4 p_{3+i}^2 \pi_i^2\right]$$

Out[2]=

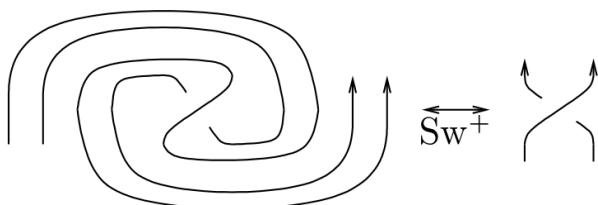
$$-\frac{1}{2} \mathbb{E}\left[\frac{1}{2} \in (-1 + 2 c_3 + 4 c_4) + I p_{3+i} \pi_i + I T \in (-1 + 4 c_4) p_{3+i} \pi_i - T^2 \in c_4 p_{3+i}^2 \pi_i^2\right] == -I \mathbb{E}[I p_{3+i} \pi_i]$$

```
In[3]:= (lhs == rhs) /. {c_5 -> 0}
```

Out[3]=

$$-\frac{1}{2} \mathbb{E}\left[\frac{1}{2} \in (-1 + 2 c_3 + 4 c_4) + I p_{3+i} \pi_i + I T \in (-1 + 4 c_4) p_{3+i} \pi_i - T^2 \in c_4 p_{3+i}^2 \pi_i^2\right] == -I \mathbb{E}[I p_{3+i} \pi_i]$$

## Invariance Under Sw



```
In[*]:= lhs = Integrate[Expectation[Im[πi pi + Im[πj pj]] L /@ (xi+1,j+1[1] ci[-1] cj[-1] ci+2[1] cj+2[1])], {xi, xj, pi, pj, xi+1, xj+1, pi+1, pj+1, xi+2, pi+2, xj+2, pj+2}]

rhs = Integrate[Expectation[Im[πi pi + Im[πj pj]] L /@ (xi+1,j+1[1] ci[0] cj[0] ci+2[0] cj+2[0])], {xi, xj, pi, pj, xi+1, xj+1, pi+1, pj+1, xi+2, pi+2, xj+2, pj+2}];

lhs == rhs

Out[*]=
```

$$\begin{aligned} & \sqrt{T} \mathbb{E} \left[ \frac{1}{2} \in (-1 + 4 c_1 + 8 c_2 + 4 c_3 + 8 c_4) + i T p_{3+i} \pi_i + i T \in (-1 + 4 c_2 + 4 c_4) p_{3+i} \pi_i - \right. \\ & \quad i (-1 + T) p_{3+j} \pi_i - 2 i \in (-T - 2 c_2 + 2 T c_2 - 2 c_4 + 2 T c_4) p_{3+j} \pi_i - \\ & \quad T^2 \in (c_2 + c_4) p_{3+i}^2 \pi_i^2 + \frac{1}{2} (-1 + T) T \in (-1 + 4 c_4) p_{3+i} p_{3+j} \pi_i^2 - \\ & \quad \frac{1}{2} (-1 + T) \in (-T - 2 c_2 + 2 T c_2 - 2 c_4 + 2 T c_4) p_{3+j}^2 \pi_i^2 + i p_{3+j} \pi_j + i \in (-1 + 4 c_2 + 4 c_4) p_{3+j} \pi_j + \\ & \quad T \in p_{3+i} p_{3+j} \pi_i \pi_j + \in (-T - 2 c_2 + 2 T c_2) p_{3+j}^2 \pi_i \pi_j + \in (-c_2 - c_4) p_{3+j}^2 \pi_j^2 \Big] \end{aligned}$$

```
Out[*]=
```

$$\begin{aligned} & \sqrt{T} \mathbb{E} \left[ \frac{1}{2} \in (-1 + 4 c_1 + 8 c_2 + 4 c_3 + 8 c_4) + i T p_{3+i} \pi_i + i T \in (-1 + 4 c_2 + 4 c_4) p_{3+i} \pi_i - \right. \\ & \quad i (-1 + T) p_{3+j} \pi_i - 2 i \in (-T - 2 c_2 + 2 T c_2 - 2 c_4 + 2 T c_4) p_{3+j} \pi_i - \\ & \quad T^2 \in (c_2 + c_4) p_{3+i}^2 \pi_i^2 + \frac{1}{2} (-1 + T) T \in (-1 + 4 c_4) p_{3+i} p_{3+j} \pi_i^2 - \\ & \quad \frac{1}{2} (-1 + T) \in (-T - 2 c_2 + 2 T c_2 - 2 c_4 + 2 T c_4) p_{3+j}^2 \pi_i^2 + i p_{3+j} \pi_j + i \in (-1 + 4 c_2 + 4 c_4) p_{3+j} \pi_j + \\ & \quad T \in p_{3+i} p_{3+j} \pi_i \pi_j + \in (-T - 2 c_2 + 2 T c_2) p_{3+j}^2 \pi_i \pi_j + \in (-c_2 - c_4) p_{3+j}^2 \pi_j^2 \Big] == \\ & \sqrt{T} \mathbb{E} \left[ -\frac{\epsilon}{2} + i T p_{3+i} \pi_i - i T \in p_{3+i} \pi_i - i (-1 + T) p_{3+j} \pi_i + 2 i T \in p_{3+j} \pi_i - \frac{1}{2} (-1 + T) T \in p_{3+i} p_{3+j} \pi_i^2 + \right. \\ & \quad \frac{1}{2} (-1 + T) T \in p_{3+j}^2 \pi_i^2 + i p_{3+j} \pi_j - i \in p_{3+j} \pi_j + T \in p_{3+i} p_{3+j} \pi_i \pi_j - T \in p_{3+j}^2 \pi_i \pi_j \Big] \end{aligned}$$