

Pensieve header: Testing suite for the FullDoPeGDO project.

```
In[*]:= Date []
SetDirectory ["C:\\Users\\T15Roland\\Wiskunde\\Bn\\ProgramFullDoPegDO"];
Once [ << KnotTheory` ];
(*Once [Get@"/Profile/Profile.m"]; *)
PP_ = Identity;
$k = 1;
<< Engine.m
<< ObjectsR.m
```

```
Out[*]:= {2021, 9, 10, 1, 29, 57.0775723}
```

ParentDirectory: Argument File should be a positive machine-size integer, a nonempty string, or a File specification.

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ToFileName: String or list of strings expected at position 1 in ToFileName[{File, WikiLink, mathematica}].

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Loading KnotTheory` version of September 6, 2014, 13:37:37.2841.

Read more at <http://katlas.org/wiki/KnotTheory>.

```
In[*]:= HL[ε_] := Style[ε, Background → If[TrueQ@ε, Green, Red]];
```

Testing

co-associativity

```
In[*]:= (dΔ1→1,2 // dΔ2→2,3) ≡ (dΔ1→2,3 // dΔ2→1,2)
```

```
Out[*]:= True
```

algebra morphism

```
In[*]:= (dΔi→1,2 dΔj→3,4 // dm1,3→i // dm2,4→j) ≡ (dmi,j→k // dΔk→i,j)
```

```
Out[*]:= True
```

associativity

```
In[*]:= (dm1,2→k // dmk,3→k) ≡ (dm2,3→k // dm1,k→k)
```

```
Out[*]:= True
```

antipode

```
In[*]:= dΔi→1,2 // dS1 // dm1,2→1
dΔi→1,2 // dS2 // dm1,2→1
```

```
Out[*]:= E{i}→{1} [0, 0]
```

```
Out[*]:= E{i}→{1} [0, 0]
```

quasi-triangular axioms

$$\begin{aligned} \text{In}[*]:= & (R_{1,3} // d\Delta_{1\rightarrow 1,2}) \equiv (R_{1,3} R_{2,4} // dm_{3,4\rightarrow 3}) \\ & (R_{1,3} // d\Delta_{3\rightarrow 2,3}) \equiv (R_{1,3} R_{\emptyset,2} // dm_{1,\emptyset\rightarrow 1}) \\ & (d\Delta_{i\rightarrow k,j} R_{1,2} // dm_{j,1\rightarrow 1} // dm_{k,2\rightarrow 2}) \equiv (R_{1,2} d\Delta_{i\rightarrow j,k} // dm_{1,j\rightarrow 1} // dm_{2,k\rightarrow 2}) \end{aligned}$$

Out[*]= True

Out[*]= True

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$$\text{In}[*]:= (R_{1,2} // aS_2) \equiv (\bar{R}_{1,2})$$

Out[*]= True

$$\begin{aligned} \text{In}[*]:= & \{ (*\text{Rotational Reidemeister moves} *) \\ & (\bar{C}_1 \bar{C}_2 R_{3,4} C_5 C_6 // dm_{1,3\rightarrow 1} // dm_{1,5\rightarrow 1} // dm_{2,4\rightarrow 2} // dm_{2,6\rightarrow 2}) \equiv R_{1,2}, \\ & (\bar{C}_1 \bar{C}_2 \bar{R}_{4,3} C_5 C_6 // dm_{1,3\rightarrow 1} // dm_{1,5\rightarrow i} // dm_{2,4\rightarrow 2} // dm_{2,6\rightarrow j}) \equiv \bar{R}_{j,i}, \\ & (R_{3,1} C_2 // dm_{1,2\rightarrow 1} // dm_{1,3\rightarrow i}) \equiv (R_{1,3} \bar{C}_2 // dm_{1,2\rightarrow 1} // dm_{1,3\rightarrow i}), \\ & (\bar{R}_{1,2} R_{3,4} // dm_{1,3\rightarrow j} // dm_{2,4\rightarrow i}) \equiv d\eta_i d\eta_j, \\ & (\bar{R}_{1,6} R_{3,2} C_4 // dm_{1,3\rightarrow i} // dm_{2,4\rightarrow 2} // dm_{2,6\rightarrow j}) \equiv d\eta_i C_j, \\ & (R_{1,2} R_{4,3} R_{5,6} // dm_{1,4\rightarrow i} // dm_{2,5\rightarrow j} // dm_{3,6\rightarrow k}) \equiv (R_{1,6} R_{2,3} R_{4,5} // dm_{1,4\rightarrow i} // dm_{2,5\rightarrow j} // dm_{3,6\rightarrow k}) \} \end{aligned}$$

Out[*]= { True, {i, j} == {j, i},

$$\hbar a_i b_i + \frac{1}{2} \left(\text{Log} \left[\frac{1}{B_i^2} \right] - \hbar b_i \right) + \hbar x_i y_i \equiv \frac{\hbar b_i}{2} + \hbar a_i b_i + \hbar x_i y_i, \text{ True, True, True} \}$$

$$\begin{aligned} \text{In}[*]:= & (R_{3,1} C_2 // dm_{1,2\rightarrow 1} // dm_{1,3\rightarrow i}) \\ & (R_{1,3} \bar{C}_2 // dm_{1,2\rightarrow 1} // dm_{1,3\rightarrow i}) \end{aligned}$$

$$\text{Out}[*]= E_{\{\} \rightarrow \{i\}} \left[\hbar a_i b_i + \frac{1}{2} \left(\text{Log} \left[\frac{1}{B_i^2} \right] - \hbar b_i \right) + \hbar x_i y_i, \frac{\hbar a_i}{2} - \frac{1}{4} \hbar^3 x_i^2 y_i^2 \right]$$

$$\text{Out}[*]= E_{\{\} \rightarrow \{i\}} \left[\frac{\hbar b_i}{2} + \hbar a_i b_i + \hbar x_i y_i, \frac{\hbar a_i}{2} - \frac{1}{4} \hbar^3 x_i^2 y_i^2 \right]$$

$$\text{In}[*]:= R_{1,2}$$

$$\text{Out}[*]= E_{\{\} \rightarrow \{1,2\}} \left[\hbar a_2 b_1 + \hbar x_2 y_1, -\frac{1}{4} \hbar^3 x_2^2 y_1^2 \right]$$

$$\text{In}[*]:= \$k = 2; cm_{1,2\rightarrow 1} // cm_{1,3\rightarrow 1}$$

$$\text{In}[*]:= \text{Timing@Block} [\{ \$k = 2 \}, \text{HL} [(cm_{1,2\rightarrow 1} // cm_{1,3\rightarrow 1}) \equiv (cm_{2,3\rightarrow 2} // cm_{1,2\rightarrow 1})]]$$

Out[*]= { 0.125, True }

$$\text{In}[*]:= \text{Timing@Block} [\{ \$k = 3 \}, \text{HL} [(cm_{1,2\rightarrow 1} // cm_{1,3\rightarrow 1}) \equiv (cm_{2,3\rightarrow 2} // cm_{1,2\rightarrow 1})]]$$

Out[*]= { 0.265625, True }

$$\text{In}[*]:= \text{Timing@Block} [\{ \$k = 4 \}, \text{HL} [(cm_{1,2\rightarrow 1} // cm_{1,3\rightarrow 1}) \equiv (cm_{2,3\rightarrow 2} // cm_{1,2\rightarrow 1})]]$$

Out[*]= { 0.640625, True }

In[]:= **Timing@Block**[{**\$k** = 5}, **HL**[(**cm**_{1,2→1} // **cm**_{1,3→1}) ≡ (**cm**_{2,3→2} // **cm**_{1,2→1})]]

Out[]:= {6.21875, **True**}

In[]:= **Timing@Block**[{**\$k** = 6}, **HL**[(**cm**_{1,2→1} // **cm**_{1,3→1}) ≡ (**cm**_{2,3→2} // **cm**_{1,2→1})]]

Out[]:= {11.8125, **True**}

In[]:= **Timing@Block**[{**\$k** = 7}, **HL**[(**cm**_{1,2→1} // **cm**_{1,3→1}) ≡ (**cm**_{2,3→2} // **cm**_{1,2→1})]]

Out[]:= {3.20313, **True**}

In[]:= **Timing@Block**[{**\$k** = 8}, **HL**[(**cm**_{1,2→1} // **cm**_{1,3→1}) ≡ (**cm**_{2,3→2} // **cm**_{1,2→1})]]

Out[]:= {5.53125, **True**}

In[]:= **aσ**_{1→2}

Out[]:= $\mathbb{E}_{\{1\} \rightarrow \{2\}} [a_2 \alpha_1 + x_2 \xi_1, \theta, \theta]$

In[]:= **am**_{1,2→3}

Out[]:= $\mathbb{E}_{\{1,2\} \rightarrow \{3\}} \left[a_3 (\alpha_1 + \alpha_2) + x_3 \left(\frac{\xi_1}{\mathcal{A}_2} + \xi_2 \right), \theta, \theta \right]$

In[]:= **bm**_{1,2→3}

Out[]:= $\mathbb{E}_{\{1,2\} \rightarrow \{3\}} \left[b_3 (\beta_1 + \beta_2) + y_3 (\eta_1 + \eta_2), -y_3 \beta_1 \eta_2, \frac{1}{2} y_3 \beta_1^2 \eta_2 \right]$

In[]:= **Block**[{**\$k** = 8}, **R**_{1,2}]

Out[]:= $\mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\hbar a_2 b_1 + \hbar x_2 y_1, -\frac{1}{4} \hbar^3 x_2^2 y_1^2, \frac{1}{9} \hbar^5 x_2^3 y_1^3, \frac{1}{48} (\hbar^5 x_2^2 y_1^2 - 3 \hbar^7 x_2^4 y_1^4), \right.$
 $-\frac{1}{36} \hbar^7 x_2^3 y_1^3 + \frac{1}{25} \hbar^9 x_2^5 y_1^5, -\frac{1}{480} \hbar^7 x_2^2 y_1^2 + \frac{1}{32} \hbar^9 x_2^4 y_1^4 - \frac{1}{36} \hbar^{11} x_2^6 y_1^6,$
 $\frac{7 \hbar^9 x_2^3 y_1^3}{1080} - \frac{1}{30} \hbar^{11} x_2^5 y_1^5 + \frac{1}{49} \hbar^{13} x_2^7 y_1^7, \frac{17 \hbar^9 x_2^2 y_1^2}{80640} - \frac{17 \hbar^{11} x_2^4 y_1^4}{1280} + \frac{5}{144} \hbar^{13} x_2^6 y_1^6 - \frac{1}{64} \hbar^{15} x_2^8 y_1^8,$
 $\left. -\frac{809 \hbar^{11} x_2^3 y_1^3}{544320} + \frac{9}{400} \hbar^{13} x_2^5 y_1^5 - \frac{1}{28} \hbar^{15} x_2^7 y_1^7 + \frac{1}{81} \hbar^{17} x_2^9 y_1^9 \right]$

In[]:= **Timing@Block**[{**\$k** = 8},
HL /@ {(**am**_{1,2→1} // **am**_{1,3→1}) ≡ **Echo**@(**am**_{2,3→2} // **am**_{1,2→1}),
(**bm**_{1,2→1} // **bm**_{1,3→1}) ≡ **Echo**@(**bm**_{2,3→2} // **bm**_{1,2→1}) }
]

$$\begin{aligned}
 & \gg \mathbb{E}_{\{1,2,3\} \rightarrow \{1\}} \left[a_1 (\alpha_1 + \alpha_2 + \alpha_3) + \frac{x_1 \xi_1}{\mathcal{A}_2 \mathcal{A}_3} + \frac{x_1 \xi_2}{\mathcal{A}_3} + x_1 \xi_3, \theta, \theta, \theta, \theta, \theta, \theta, \theta, \theta \right] \\
 & \gg \mathbb{E}_{\{1,2,3\} \rightarrow \{1\}} \left[b_1 \beta_1 + b_1 \beta_2 + b_1 \beta_3 + y_1 \eta_1 + y_1 \eta_2 + y_1 \eta_3, \right. \\
 & \quad -y_1 \beta_1 \eta_2 - y_1 \beta_1 \eta_3 - y_1 \beta_2 \eta_3, \frac{1}{2} y_1 \beta_1^2 \eta_2 + \frac{1}{2} y_1 \beta_1^2 \eta_3 + y_1 \beta_1 \beta_2 \eta_3 + \frac{1}{2} y_1 \beta_2^2 \eta_3, \\
 & \quad -\frac{1}{6} y_1 \beta_1^3 \eta_2 - \frac{1}{6} y_1 \beta_1^3 \eta_3 - \frac{1}{2} y_1 \beta_1^2 \beta_2 \eta_3 - \frac{1}{2} y_1 \beta_1 \beta_2^2 \eta_3 - \frac{1}{6} y_1 \beta_2^3 \eta_3, \\
 & \quad \frac{1}{24} y_1 \beta_1^4 \eta_2 + \frac{1}{24} y_1 \beta_1^4 \eta_3 + \frac{1}{6} y_1 \beta_1^3 \beta_2 \eta_3 + \frac{1}{4} y_1 \beta_1^2 \beta_2^2 \eta_3 + \frac{1}{6} y_1 \beta_1 \beta_2^3 \eta_3 + \frac{1}{24} y_1 \beta_2^4 \eta_3, \\
 & \quad -\frac{1}{120} y_1 \beta_1^5 \eta_2 - \frac{1}{120} y_1 \beta_1^5 \eta_3 - \frac{1}{24} y_1 \beta_1^4 \beta_2 \eta_3 - \frac{1}{12} y_1 \beta_1^3 \beta_2^2 \eta_3 - \frac{1}{12} y_1 \beta_1^2 \beta_2^3 \eta_3 - \frac{1}{24} y_1 \beta_1 \beta_2^4 \eta_3 - \frac{1}{120} y_1 \beta_2^5 \eta_3, \\
 & \quad \frac{1}{720} y_1 \beta_1^6 \eta_2 + \frac{1}{720} y_1 \beta_1^6 \eta_3 + \frac{1}{120} y_1 \beta_1^5 \beta_2 \eta_3 + \frac{1}{48} y_1 \beta_1^4 \beta_2^2 \eta_3 + \frac{1}{36} y_1 \beta_1^3 \beta_2^3 \eta_3 + \frac{1}{48} y_1 \beta_1^2 \beta_2^4 \eta_3 + \\
 & \quad \frac{1}{120} y_1 \beta_1 \beta_2^5 \eta_3 + \frac{1}{720} y_1 \beta_2^6 \eta_3, -\frac{y_1 \beta_1^7 \eta_2}{5040} - \frac{y_1 \beta_1^7 \eta_3}{5040} - \frac{1}{720} y_1 \beta_1^6 \beta_2 \eta_3 - \frac{1}{240} y_1 \beta_1^5 \beta_2^2 \eta_3 - \frac{1}{144} y_1 \beta_1^4 \beta_2^3 \eta_3 - \\
 & \quad \frac{1}{144} y_1 \beta_1^3 \beta_2^4 \eta_3 - \frac{1}{240} y_1 \beta_1^2 \beta_2^5 \eta_3 - \frac{1}{720} y_1 \beta_1 \beta_2^6 \eta_3 - \frac{y_1 \beta_2^7 \eta_3}{5040}, \frac{y_1 \beta_1^8 \eta_2}{40320} + \frac{y_1 \beta_1^8 \eta_3}{40320} + \frac{y_1 \beta_1^7 \beta_2 \eta_3}{5040} + \\
 & \quad \left. \frac{y_1 \beta_1^6 \beta_2^2 \eta_3}{1440} + \frac{1}{720} y_1 \beta_1^5 \beta_2^3 \eta_3 + \frac{1}{576} y_1 \beta_1^4 \beta_2^4 \eta_3 + \frac{1}{720} y_1 \beta_1^3 \beta_2^5 \eta_3 + \frac{y_1 \beta_1^2 \beta_2^6 \eta_3}{1440} + \frac{y_1 \beta_1 \beta_2^7 \eta_3}{5040} + \frac{y_1 \beta_2^8 \eta_3}{40320} \right]
 \end{aligned}$$

Out[*]= {0.25, {True, True}}

In[*]= \$k = 1; R_{i,j}\$

$$\text{Out[*]} = \mathbb{E}_{\{i\} \rightarrow \{i,j\}} \left[\hbar a_j b_i + \hbar x_j y_i, -\frac{1}{4} \hbar^3 x_j^2 y_i^2 \right]$$

In[*]= \$k = 3; \bar{R}_{i,j}\$

$$\begin{aligned}
 \text{Out[*]} = \mathbb{E}_{\{i\} \rightarrow \{i,j\}} \left[-\hbar a_j b_i - \frac{\hbar x_j y_i}{B_i}, -\frac{\hbar^2 a_j x_j y_i}{B_i} - \frac{3 \hbar^3 x_j^2 y_i^2}{4 B_i^2}, \right. \\
 \left. -\frac{\hbar^3 a_j^2 x_j y_i}{2 B_i} + \frac{\hbar^4 x_j^2 y_i^2}{2 B_i^2} - \frac{3 \hbar^4 a_j x_j^2 y_i^2}{2 B_i^2} - \frac{10 \hbar^5 x_j^3 y_i^3}{9 B_i^3}, \right. \\
 \left. -\frac{\hbar^4 a_j^3 x_j y_i}{6 B_i} - \frac{3 \hbar^5 x_j^2 y_i^2}{16 B_i^2} + \frac{\hbar^5 a_j x_j^2 y_i^2}{B_i^2} - \frac{3 \hbar^5 a_j^2 x_j^2 y_i^2}{2 B_i^2} + \frac{2 \hbar^6 x_j^3 y_i^3}{B_i^3} - \frac{10 \hbar^6 a_j x_j^3 y_i^3}{3 B_i^3} - \frac{35 \hbar^7 x_j^4 y_i^4}{16 B_i^4} \right]
 \end{aligned}$$

In[*]= \$k = 3; P_{i,j}\$

$$\text{Out[*]} = \mathbb{E}_{\{i,j\} \rightarrow \{i\}} \left[\frac{\alpha_j \beta_i}{\hbar} + \frac{\eta_i \xi_j}{\hbar}, \frac{\eta_i^2 \xi_j^2}{4 \hbar}, \frac{1}{8} \eta_i^2 \xi_j^2 + \frac{5 \eta_i^3 \xi_j^3}{36 \hbar}, \frac{1}{24} \hbar \eta_i^2 \xi_j^2 + \frac{1}{6} \eta_i^3 \xi_j^3 + \frac{5 \eta_i^4 \xi_j^4}{48 \hbar} \right]$$

$ln[*]:= \$k = 3; aS_i$

$$Out[*]:= E_{\{i\} \rightarrow \{i\}} \left[-a_i \alpha_i - x_i \mathcal{A}_i \xi_i, -\hbar a_i x_i \mathcal{A}_i \xi_i - \frac{1}{2} \hbar x_i^2 \mathcal{A}_i^2 \xi_i^2, \right. \\ \left. -\frac{1}{2} \hbar^2 a_i^2 x_i \mathcal{A}_i \xi_i + \frac{1}{4} \hbar^2 x_i^2 \mathcal{A}_i^2 \xi_i^2 - \hbar^2 a_i x_i^2 \mathcal{A}_i^2 \xi_i^2 - \frac{1}{2} \hbar^2 x_i^3 \mathcal{A}_i^3 \xi_i^3, -\frac{1}{6} \hbar^3 a_i^3 x_i \mathcal{A}_i \xi_i - \right. \\ \left. \frac{1}{12} \hbar^3 x_i^2 \mathcal{A}_i^2 \xi_i^2 + \frac{1}{2} \hbar^3 a_i x_i^2 \mathcal{A}_i^2 \xi_i^2 - \hbar^3 a_i^2 x_i^2 \mathcal{A}_i^2 \xi_i^2 + \frac{2}{3} \hbar^3 x_i^3 \mathcal{A}_i^3 \xi_i^3 - \frac{3}{2} \hbar^3 a_i x_i^3 \mathcal{A}_i^3 \xi_i^3 - \frac{2}{3} \hbar^3 x_i^4 \mathcal{A}_i^4 \xi_i^4 \right]$$

$ln[*]:= \$k = 3; \overline{aS}_i$

$$Out[*]:= E_{\{i\} \rightarrow \{i\}} \left[-a_i \alpha_i - x_i \mathcal{A}_i \xi_i, \hbar x_i \mathcal{A}_i \xi_i - \hbar a_i x_i \mathcal{A}_i \xi_i - \frac{1}{2} \hbar x_i^2 \mathcal{A}_i^2 \xi_i^2, \right. \\ \left. -\frac{1}{2} \hbar^2 x_i \mathcal{A}_i \xi_i + \hbar^2 a_i x_i \mathcal{A}_i \xi_i - \frac{1}{2} \hbar^2 a_i^2 x_i \mathcal{A}_i \xi_i + \frac{5}{4} \hbar^2 x_i^2 \mathcal{A}_i^2 \xi_i^2 - \hbar^2 a_i x_i^2 \mathcal{A}_i^2 \xi_i^2 - \frac{1}{2} \hbar^2 x_i^3 \mathcal{A}_i^3 \xi_i^3, \right. \\ \left. \frac{1}{6} \hbar^3 x_i \mathcal{A}_i \xi_i - \frac{1}{2} \hbar^3 a_i x_i \mathcal{A}_i \xi_i + \frac{1}{2} \hbar^3 a_i^2 x_i \mathcal{A}_i \xi_i - \frac{1}{6} \hbar^3 a_i^3 x_i \mathcal{A}_i \xi_i - \frac{19}{12} \hbar^3 x_i^2 \mathcal{A}_i^2 \xi_i^2 + \right. \\ \left. \frac{5}{2} \hbar^3 a_i x_i^2 \mathcal{A}_i^2 \xi_i^2 - \hbar^3 a_i^2 x_i^2 \mathcal{A}_i^2 \xi_i^2 + \frac{13}{6} \hbar^3 x_i^3 \mathcal{A}_i^3 \xi_i^3 - \frac{3}{2} \hbar^3 a_i x_i^3 \mathcal{A}_i^3 \xi_i^3 - \frac{2}{3} \hbar^3 x_i^4 \mathcal{A}_i^4 \xi_i^4 \right]$$

$ln[*]:= (\overline{aS}_1 // aS_1)$

$$Out[*]:= E_{\{1\} \rightarrow \{1\}} [a_1 \alpha_1 + x_1 \xi_1, \theta, \theta, \theta]$$

$ln[*]:= (\overline{aS}_1 // aS_1)$

$$Out[*]:= E_{\{1\} \rightarrow \{1\}} [a_1 \alpha_1 + x_1 \xi_1, \theta, \theta, \theta]$$

$ln[*]:= (\overline{bS}_1 // bS_1)$

$$Out[*]:= E_{\{1\} \rightarrow \{1\}} [b_1 \beta_1 + y_1 \eta_1, \theta, \theta, \theta]$$

$ln[*]:= \$k = 1$

$$Out[*]:= 1$$

$ln[*]:= dS_1$

$$Out[*]:= E_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\ \left. \frac{\hbar y_1 \mathcal{A}_1 \eta_1}{B_1} - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \right. \\ \left. \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \right. \\ \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right]$$

$$\begin{aligned}
 \text{In[*]} = \mathbb{F} = \mathbb{E}; \quad \text{dS}_1 \equiv \mathbb{F}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\
 \frac{\hbar y_1 \mathcal{A}_1 \eta_1}{B_1} - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \\
 \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \\
 \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right]
 \end{aligned}$$

Out[*] = True

$$\begin{aligned}
 \text{In[*]} = \overline{\text{dS}}_1 \equiv \mathbb{F}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\
 - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} + \hbar x_1 \mathcal{A}_1 \xi_1 - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \\
 \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \\
 \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right]
 \end{aligned}$$

Out[*] = True

$$\text{In[*]} = \text{dS}_1 // \overline{\text{dS}}_1$$

$$\text{Out[*]} = \mathbb{E}_{\{1\} \rightarrow \{1\}} [a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1, \theta]$$

$$\begin{aligned} In[*]= & \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\ & \left(\frac{\hbar y_1 \mathcal{A}_1 \eta_1}{B_1} - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \right. \\ & \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \\ & \left. \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right) \right] // \end{aligned}$$

$$\begin{aligned} \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\ - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} + \hbar x_1 \mathcal{A}_1 \xi_1 - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \\ \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \\ \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right] \end{aligned}$$

$$\begin{aligned} Out[*]= & \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1 + \frac{(-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar}, \right. \\ & (-\hbar + \hbar) y_1 \eta_1 + (1 -) y_1 \beta_1 \eta_1 + \frac{1}{2} (-\hbar + \hbar) y_1^2 \eta_1^2 + (\hbar - \hbar) x_1 \xi_1 + (-\hbar + \hbar) a_1 x_1 \xi_1 + \\ & (1 -) x_1 \beta_1 \xi_1 + (-\hbar + \hbar) x_1 y_1 \eta_1 \xi_1 + a_1 (-\mathcal{A}_1 + \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1 + \\ & (\mathcal{A}_1 - \mathcal{A}_1 - \mathcal{A}_1 + \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1 + \\ & \frac{(-\mathcal{A}_1 + \mathcal{A}_1 + \mathcal{A}_1 - \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar} + \\ & \frac{1}{2} y_1 (\mathcal{A}_1 - 2 \mathcal{A}_1 + 2 \mathcal{A}_1 - 2 \mathcal{A}_1 - 2 \mathcal{A}_1 + 2 \mathcal{A}_1 - 3 B_1 \mathcal{A}_1 + \\ & 6 B_1 \mathcal{A}_1 - 2 B_1 \mathcal{A}_1 + 2 B_1 \mathcal{A}_1 - 2 B_1 \mathcal{A}_1 - 2 B_1 \mathcal{A}_1) \eta_1^2 \xi_1 + \\ & \frac{1}{2} (-\hbar + 2 \hbar - \hbar) x_1^2 \xi_1^2 + \frac{1}{2} x_1 (\mathcal{A}_1 - 2 \mathcal{A}_1 - 2 \mathcal{A}_1 + 4 \mathcal{A}_1 - \mathcal{A}_1 - \\ & 3 B_1 \mathcal{A}_1 + 2 B_1 \mathcal{A}_1 + 6 B_1 \mathcal{A}_1 - 4 B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1^2 + \\ & \frac{1}{4 \hbar} (-\mathcal{A}_1^2 + 2 \mathcal{A}_1^2 - 2 \mathcal{A}_1^2 + 2 \mathcal{A}_1^2 - 4 \mathcal{A}_1^2 + 4 \mathcal{A}_1^2 - 2 \mathcal{A}_1^2 - 3 B_1^2 \mathcal{A}_1^2 + 4 B_1^2 \mathcal{A}_1^2 + \\ & 4 B_1 \mathcal{A}_1^2 - 8 B_1 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - 8 B_1 \mathcal{A}_1^2 + 12 B_1 \mathcal{A}_1^2 - 8 B_1 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 + \\ & 4 B_1^2 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - 8 B_1 \mathcal{A}_1^2 - 3 B_1^2 \mathcal{A}_1^2 + 6 B_1 \mathcal{A}_1^2 - 2 B_1^2 \mathcal{A}_1^2 + 6 B_1^2 \mathcal{A}_1^2 - \\ & 8 B_1 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - 2 B_1^2 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2 - 4 B_1 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1^2 \left. \right] \end{aligned}$$

$$In[] := \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\ \left. \left(\frac{\hbar y_1 \mathcal{A}_1 \eta_1}{B_1} - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \right. \right. \\ \left. \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \right. \\ \left. \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right) \right] //$$

$$\mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \right. \\ \left. - \frac{y_1 \mathcal{A}_1 \beta_1 \eta_1}{B_1} - \frac{\hbar y_1^2 \mathcal{A}_1^2 \eta_1^2}{2 B_1^2} + \hbar x_1 \mathcal{A}_1 \xi_1 - \hbar a_1 x_1 \mathcal{A}_1 \xi_1 - x_1 \mathcal{A}_1 \beta_1 \xi_1 + \frac{a_1 \mathcal{A}_1 \eta_1 \xi_1}{B_1} - \right. \\ \left. \frac{\hbar x_1 y_1 \mathcal{A}_1^2 \eta_1 \xi_1}{B_1} + \frac{(-\mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1}{B_1} + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} + \frac{y_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1}{2 B_1^2} - \right. \\ \left. \frac{1}{2} \hbar x_1^2 \mathcal{A}_1^2 \xi_1^2 + \frac{x_1 (3 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1 \xi_1^2}{2 B_1} + \frac{(-3 \mathcal{A}_1^2 + 4 B_1 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{4 \hbar B_1^2} \right]$$

$$Out[] := \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1, \right. \\ (\hbar - \hbar) x_1 y_1 \eta_1 \xi_1 + (-\mathcal{A}_1 - \mathcal{A}_1 + \mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1 + \\ \frac{(\mathcal{A}_1 - \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar} + \\ y_1 (-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1^2 \xi_1 + x_1 (\mathcal{A}_1 - \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1^2 + \\ \left. \frac{(-\mathcal{A}_1^2 + \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2 + 2 B_1 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2 + B_1^2 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{\hbar} \right]$$

$$In[] := \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1, \right. \\ (\hbar - \hbar) x_1 y_1 \eta_1 \xi_1 + (-\mathcal{A}_1 + \mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1 - \mathcal{A}_1^2 + B_1 \mathcal{A}_1^2) \eta_1 \xi_1 + \\ \frac{(\mathcal{A}_1 - \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar} + \\ y_1 (-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1^2 \xi_1 + x_1 (\mathcal{A}_1 - \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \eta_1 \xi_1^2 + \\ \left. \frac{(-\mathcal{A}_1^2 + \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2 + 2 B_1 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2 + B_1^2 \mathcal{A}_1^2 - B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{\hbar} \right] /. \{Red | Green | Blue \rightarrow 1\}$$

$$Out[] := \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1, \right. \\ (\mathcal{A}_1 - B_1 \mathcal{A}_1 - \mathcal{A}_1^2 + B_1 \mathcal{A}_1^2) \eta_1 \xi_1 + \frac{(\mathcal{A}_1 - \mathcal{A}_1 - B_1 \mathcal{A}_1 + B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar} + \\ y_1 (-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1^2 \xi_1 + \frac{(-\mathcal{A}_1^2 + \mathcal{A}_1^2 + B_1 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{\hbar} \left. \right]$$

$$\begin{aligned}
 In[*] &:= \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \theta \right] // \\
 &\quad \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[-a_1 \alpha_1 - b_1 \beta_1 - \frac{y_1 \mathcal{A}_1 \eta_1}{B_1} - x_1 \mathcal{A}_1 \xi_1 + \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar B_1}, \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar B_1} \right] \\
 Out[*] &:= \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[a_1 \alpha_1 + b_1 \beta_1 + y_1 \eta_1 + x_1 \xi_1 + \frac{(-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1}{\hbar}, \right. \\
 &\quad \left. \frac{(\mathcal{A}_1 - B_1 \mathcal{A}_1) \eta_1 \xi_1 + \frac{(-\mathcal{A}_1 + \mathcal{A}_1 + B_1 \mathcal{A}_1) \beta_1 \eta_1 \xi_1}{\hbar}}{\hbar} + y_1 (\mathcal{A}_1^2 - B_1 \mathcal{A}_1^2) \eta_1^2 \xi_1 + \right. \\
 &\quad \left. \frac{(\mathcal{A}_1^2 + B_1 \mathcal{A}_1^2 - 2 \mathcal{A}_1^2 - B_1 \mathcal{A}_1^2 + B_1^2 \mathcal{A}_1^2) \eta_1^2 \xi_1^2}{\hbar} \right]
 \end{aligned}$$

$$In[*] := (\overline{kR}_{1,4} \overline{kR}_{5,2} \overline{kC}_3) // km_{2,4 \rightarrow 2} // km_{1,3 \rightarrow 1} // km_{1,5 \rightarrow 1}$$

$$Out[*] := \mathbb{E}_{\{\} \rightarrow \{1,2\}} [\theta, \hbar a_1, \theta]$$

$$In[*] := \overline{kC}_1 d\eta_2$$

$$Out[*] := \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[-\frac{\hbar t_1}{2}, \hbar a_1, \theta \right]$$

$$In[*] := (\mathbb{E}_{\{\} \rightarrow \{1,2\}} [\theta, a_2 x_1] // am_{1,2 \rightarrow 1})$$

$$Out[*] := \mathbb{E}_{\{\} \rightarrow \{1\}} [\theta, -x_1 + a_1 x_1]$$

$$In[*] := \$k = 2; \mathbb{E}2\Delta[\mathbb{E}_{\{\} \rightarrow \{1,2\}} [\theta, y_2 b_1] // bm_{1,2 \rightarrow 1}]$$

$$Out[*] := b_1 y_1$$

$$In[*] := \mathbb{E}_{\{\} \rightarrow \{1,2\}} [\theta, y_2 b_1]$$

$$Out[*] := \mathbb{E}_{\{\} \rightarrow \{1,2\}} [\theta, b_1 y_2]$$