

Lecture 2 Clippings

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Clippings from <http://www.math.toronto.edu/drorbn/LOP.html#pcs>

$$\mathcal{Z} = \int_{\mathbf{R}^n} d\vec{x} e^{it(\frac{1}{2}\lambda_{ij}x^i x^j + \lambda_{ijk}x^i x^j x^k)} \delta^l(F(\vec{x})) \det\left(\frac{\partial F^a}{\partial G_b}\right)(\vec{x}).$$

$$\delta^l(F(\vec{x})) = \frac{1}{(2\pi)^l} \int_{\mathbf{R}^l} d^l \phi e^{iF^a(\vec{x})\phi_a}$$

$$\det\left(J_0 + \frac{1}{\sqrt{t}}J_1(\vec{x})\right) = \det(J_0) \sum_m \left(\frac{1}{\sqrt{t}}\right)^m \text{Tr}(\Lambda^m J_0^{-1})(\Lambda^m J_1(\vec{x})).$$

$$\int d^l \bar{c} d^l c e^{i\bar{c}_a J^a_b c^b} \propto \det(J).$$

$$\mathcal{Z} \propto \int_{\mathbf{R}^n} d\vec{x} \frac{1}{(2\pi)^l} \int_{\mathbf{R}^l} d^l \phi \int d^l \bar{c} d^l c e^{i(t(\frac{1}{2}\lambda_{ij}x^i x^j + \lambda_{ijk}x^i x^j x^k) + F^a(\vec{x})\phi_a + \bar{c}_a (\frac{\partial F^a}{\partial G_b})c^b)}$$

$$[A = -D^A C = -(\partial C + [A, C])$$

$$\frac{k}{4\pi} D_i^A B^i = 0$$

$$\begin{aligned} \mathcal{L}_{tot}(B, \phi, c, \bar{c}) &= \mathcal{L} + \mathcal{L}_{gauge-fixing} + \mathcal{L}_{ghosts} = \\ &= \frac{k}{4\pi} \int_{M^3} \text{tr}(B \wedge D^A B + \frac{2}{3} B \wedge B \wedge B) + \\ &\quad + \frac{k}{4\pi} \int_{M^3} \text{tr}(\phi D_i^A B^i) + \\ &\quad + \frac{k}{4\pi} \int_{M^3} \text{tr} \bar{c} D_i^A (D_A^i + \text{ad } B^i) c \end{aligned}$$

Clippings from my Thesis,

<http://www.math.toronto.edu/drorbn/LOP.html#thesis>

$$\begin{aligned} \mathcal{O}_{X,R}(A) &= \text{tr}_R \mathcal{P} \exp \left(\int ds \dot{X}^i(s) A_i(X(s)) \right) = \dim R - \int ds \dot{X}^i(s) A_i^a(X(s)) R_{a\alpha}^\alpha \\ &\quad + \int_{s_1 < s_2} ds_{1,2} \dot{X}^{i_1}(s_1) \dot{X}^{i_2}(s_2) A_{i_1}^{a_1}(X(s_1)) A_{i_2}^{a_2}(X(s_2)) R_{a_1\alpha_2}^{\alpha_1} R_{a_2\alpha_1}^{\alpha_2} - \dots \end{aligned} \quad (1.3)$$

$$\int_{\mathbf{R}^N} d^N x e^{ik\mathcal{L}} \underset{k \rightarrow \infty}{\sim} \sum_{i=1}^I \frac{e^{\frac{i\pi}{4} \text{sign } L(x_i)}}{\sqrt{(4\pi k)^N |\det L(x_i)|}} e^{ik\mathcal{L}(x_i)}$$

(a) For each gauge propagator in D , marked, say, as $\frac{i,a}{x} - \frac{i',a'}{y}$ take the term

$$V_{ii'}^{aa'}(x, y). \quad (2.1)$$

$V_{IJ}^{ab}(x, y)$ is defined to be the inverse of the bosonic free part of the Lagrangian \mathcal{L} . The symbols “ I ” and “ J ” are either numbers i, j in the range $1 - 3$, or the symbol ϕ , and with this understood V is defined by the relations: (the differentiations⁴ are all with respect to x .)

$$t_{ab} D_i \sqrt{g} g^{ij} V_{j\phi}^{bc}(x, y) = 2\pi i \delta_a^c \delta(x, y),$$

$$t_{ab} D_i \sqrt{g} g^{ij} V_{jk}^{bc}(x, y) = 0,$$

$$t_{ab} \left(\epsilon^{ijk} D_j V_{kl}^{bc}(x, y) + D^i V_{\phi l}^{bc}(x, y) \right) = 2\pi i \delta_a^c \delta_l^i \delta(x, y),$$

$$t_{ab} \left(\epsilon^{ijk} D_j V_{k\phi}^{bc}(x, y) + D^i V_{\phi\phi}^{bc}(x, y) \right) = 0.$$

(b) For each ghost propagator in D , marked, say, as $\frac{d'}{y} \text{---} \frac{d}{z}$ take the term

$$G^{d'd}(y, z).$$

G is defined to be the inverse of the ghost free part of the Lagrangian \mathcal{L} — that is to say, it is defined by the relation: (the differentiations are all with respect to x .)

$$t_{ab} D_i D^i G^{bc} = -2\pi \delta_a^c \delta(x, y).$$

(c) For each marked A^3 vertex in D use the rule

$$\begin{array}{c} \backslash \text{b} \text{ j} \\ \text{x} \\ / \text{c} \text{ k} \end{array} \frac{1}{\text{a}} \rightarrow \frac{i}{2\pi} \int_{M^3} dx t_{abc} \epsilon^{ijk}. \quad (2.2)$$

(d) For each $\bar{c}Ac$ vertex in D use the rule

$$\begin{array}{c} \nearrow \text{e} \\ \text{z} \\ \searrow \text{d} \end{array} \frac{1}{\text{f}} \rightarrow \frac{1}{2\pi} \int_{M^3} dz t_{dfe} D_z^l. \quad (2.3)$$

Here D_z^l denotes differentiation with respect to z^l ,

$$D_z^l = \sqrt{g} g^{lm} \frac{D}{Dz^m}$$

acting only on the z -dependence of the term coming from the ghost propagator leaving the vertex. For a better understanding, let us look at this term

$$\text{---} \left. \begin{array}{c} l' \\ \text{f}' \\ \beta \end{array} \right\} s_1 \rightarrow -R_{f'\gamma}^\beta \dot{X}^{l'}(s_1).$$

$$G_{\Delta}^{ab}(x, y) = \frac{t^{ab}}{4\pi|x-y|}$$

$$\frac{x}{a, i} \text{---} \frac{y}{b, j} V_{ij}^{ab}(x, y) = \langle A_i^a(x) A_j^b(y) \rangle = 2\pi i \epsilon_{ikj} \partial_x^k \frac{t^{ab}}{4\pi|x-y|} = \epsilon_{ijk} t^{ab} \frac{i(x-y)^k}{2|x-y|^3}.$$