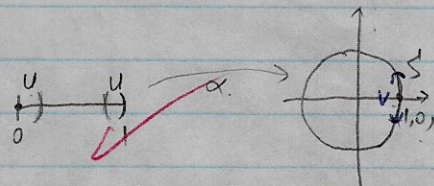


Section 23.

3. a) We can parametrize the set $(x,y) \in S'$ on the upper semicircle, i.e. $y > 0$.
 Set $\phi_1(x) = (x, \sqrt{1-x^2})$ for $x \in (-1, 1)$. s.t. ϕ_1 is a smooth map. takes $(-1, 1)$ to the upper semicircle. The inverse $\phi_1^{-1}(x,y) = x$ is also smooth. ϕ_1 is diffeomorphism.
 For the lower semicircle, take $\phi_2(x) = (x, -\sqrt{1-x^2})$. s.t. $\phi_2(x)$ is a smooth map takes $(-1, 1)$ to the lower semicircle. Also, the inverse ϕ_2^{-1} is smooth.
 This parametrizes all of S' except for two points $(\pm 1, 0)$.
 we take $\phi_3 = (\sqrt{1-y^2}, y)$ & $\phi_4 = (-\sqrt{1-y^2}, y)$ to parametrize the two points.
 These four parametrizations cover S' & for each point at least one of those gives a local parametrization.

- b) Consider the point $(1, 0)$ in S' .
 Let V be the open nbd of S' containing $(1, 0)$.

the function α^{-1} is not continuous, because there does not exist a open set U near point 0



in $[0, 1)$ under α to V . [i.e. the points near $(1, 0)$ in S' need not map under α^{-1} to points near 0 in $[0, 1)$]. It will divide into 2 parts, one is near 0 in $[0, 1)$ & the other is near 1 in $[0, 1)$].

6. a) Set $\phi_1(x) = x$ on $(0, 1)$. s.t. ϕ_1 is an identity function. takes points in $(0, 1)$ to $(0, 1)$ in I .
 ϕ_1 is \mathcal{H}^{-1} onto, & of C^1 . α^{-1} is cont. & $D\phi_1(\phi)$ has rank 1 for each $x \in U$ where U is a open set in \mathcal{H}^1 , s.t. $\phi_1: U \rightarrow V$ (a open nbd of p , $p \in (0, 1)$).
 Moreover, for point 0, & 1, we take $\phi_2(x) = x$, $\phi_3(x) = 1-x$ where $U = [0, \delta]$ in \mathbb{R} .
 $\phi_2: U \rightarrow V_2 = [0, \delta]$, $\phi_3: U \rightarrow V_3 = [1-\delta, 1]$ where V_2 & V_3 are open in $[0, 1]$. So we parametrize the points.
 Therefore, these 2 parametrizations covers $I = [0, 1]$ & for each point at least one of these gives a local parametrization.

- b) $[x, I]$ is NOT a 2-manifold in \mathbb{R}^2 .

Because when we consider about corners, e.g. $(0, 0)$.

Assume there exists a coordinate patch $i: [0, 1]^2 \rightarrow [0, 1]^2$.

The differential of i when restricted to $\{0\} \times (0, \epsilon)$ would be proportional to a vertical tangent vector in the tangent space of \mathbb{R}^2 , whereas the differential when restricted to $(0, \epsilon) \times \{0\}$ would be proportional to a horizontal vector. Since the differential has to be cont. this is a contradiction as the differential at $(0, 0)$.

5. a) let $A \in O(3)$, then $A^T A = I$, let $A = [x, y, z]$, then $A^T A = \begin{bmatrix} \|x\|^2 & \langle x, y \rangle & \langle x, z \rangle \\ \langle y, x \rangle & \|y\|^2 & \langle y, z \rangle \\ \langle z, x \rangle & \langle z, y \rangle & \|z\|^2 \end{bmatrix} = I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

So $A = [x, y, z]$ where x, y, z are orthonormal vectors in \mathbb{R}^3 , s.t. $\|x\| = \|y\| = \|z\| = 1$.

let $f(x, y, z) = (\|x\|^2 - 1, \|y\|^2 - 1, \|z\|^2 - 1, x \cdot y, x \cdot z, y \cdot z)$

So $f(x, y, z) = 0 \Leftrightarrow \|x\|^2 - 1 = \|y\|^2 - 1 = \|z\|^2 - 1 = 0, \langle x, y \rangle = \langle x, z \rangle = \langle y, z \rangle = 0$.

$\Leftrightarrow x, y, z$ are orthonormal vectors.

$\Leftrightarrow A = [x, y, z], A \in O(3)$.

So $f(A) = 0 \Leftrightarrow A \in O(3)$.

b) claim: (Exercise #2 TMM): let $f: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^n$ be of class C^r . Let M be the set of all x s.t. $f(x) = 0$. Assume that M is non-empty & that $Df(x)$ has rank n for $x \in M$.

Then M is a k -manifold without boundary in \mathbb{R}^{n+k} .

proof: define $g: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^{n+k}$ s.t. $g(x_1, \dots, x_{n+k}) = (x_1, \dots, x_k, f_1(x), \dots, f_n(x))$ has rank $n+k$ then $\text{Det}(Dg(x)) \neq 0$ for $x \in M$. So, by the IFT (inverse function TMM), g is a

diffeomorphism between a nbd V containing p & an open nbd U in \mathbb{R}^{n+k} .

Moreover, g carries $V \cap M$ in a 1-1 fashion onto the set $U_0 = U \cap \mathbb{R}^k \times \{0\}^n$.

Then we define the projection $\Pi: U_0 \rightarrow W$ as the projection of U_0 onto its first k coordinates.

This is 1-1 & onto since the last n coordinates of elements in U_0 are 0.

Then let $\alpha = g^{-1} \circ \Pi^{-1}$, where α takes W to $V \cap M$.

α is of class C^r because Π^{-1} is C^∞ & g^{-1} is C^r (since g is C^r)

α^{-1} is cont. since g & Π are cont.

$D\alpha(x)$ has rank k for $x \in M$, since the first k rows of $D\alpha$ are independent.

So M is a k -manifold without boundary in \mathbb{R}^{n+k} .

Now back to the question & consider $Df(A)$ where $A \in O(3)$, $A = [x \ y \ z]$

$$Df = \begin{bmatrix} \frac{\partial f}{\partial x} & 0 & 0 \\ 0 & \frac{\partial f}{\partial y} & 0 \\ 0 & 0 & \frac{\partial f}{\partial z} \\ \frac{\partial \langle x, y \rangle}{\partial x} & \frac{\partial \langle x, y \rangle}{\partial y} & 0 \\ \frac{\partial \langle x, z \rangle}{\partial x} & 0 & \frac{\partial \langle x, z \rangle}{\partial z} \\ 0 & \frac{\partial \langle y, z \rangle}{\partial y} & \frac{\partial \langle y, z \rangle}{\partial z} \end{bmatrix}$$

since $\frac{\partial f}{\partial x} = \frac{\partial(\|x\|^2 - 1)}{\partial x} = [2x_1 \ 2x_2 \ 2x_3] = 2x$ where $x = (x_1, x_2, x_3)$

because $\|x\|^2 - 1 = x_1^2 + x_2^2 + x_3^2 - 1$

$\frac{\partial \langle x, y \rangle}{\partial x} = [y_1 \ y_2 \ y_3] = y$ where $y = (y_1, y_2, y_3)$

because $\langle x, y \rangle = x_1 y_1 + x_2 y_2 + x_3 y_3$

Similarly, we can get other partial derivatives.

So $Df(x, y, z) \begin{bmatrix} 2x & 0 & 0 \\ 0 & 2y & 0 \\ 0 & 0 & 2z \\ y & x & 0 \\ z & 0 & x \\ 0 & z & y \end{bmatrix}$

Hence, the rows of $Df(A)$ are independent.

& since $f(A) = 0$, for $A \in O(3)$ ^{not empty} by the claim, we get

$O(3)$ is a compact 3-manifold in \mathbb{R}^9 without boundary.