

MAT 240 – Linear Algebra Lecture

Reminder: Choosing a basis, V is isomorphic to F^n

Goal:

1. The set $L(V, W)$ of all linear transformations $V \rightarrow W$ is a V.S.
2. Choosing bases, it is isomorphic to $M_{m \times n}(F)$ $m = \dim(V)$ $n = \dim(W)$

Extra Claim (from last class final example):

If two linear transformations $S, S': X \rightarrow Y$ agree on a basis of X , they are equal.

If (x_i) is a basis of X and $\forall i S(x_i) = S'(x_i) \in Y$ then $S = S'$

Proof: Pick some element $x \in X$, as (x_i) as a basis, find scalars a_i such that.

$$x = \sum a_i x_i$$

$$\begin{aligned} \text{Now: } S(x) &= S(\sum a_i x_i) = \sum a_i S(x_i) = \sum a_i S'(x_i) = \sum a_i S'(x_i) = S'(\sum a_i x_i) = S'(x) \\ &\rightarrow S = S' \blacksquare \end{aligned}$$

Let $\beta = (u_1, \dots, u_n)$ be a basis (**basis is ordered**) of a finite dimension vector space V . $x \in V$ $x = \sum a_i u_i$

$$\text{Let } [x]_\beta = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = T(x)$$

$\beta = (u_1, \dots, u_n)$ of V

$\gamma = (e_1 \dots e_n)$ of F^n

$T: V \rightarrow F^n$

Defined by:

$$u_i \rightarrow e_i$$

$$\text{Indeed, } T(x) = T(\sum a_i u_i) = \sum a_i T(u_i) = \sum a_i e_i = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = [x]_\beta$$

$T: V \rightarrow W$ is a linear transformation, $\beta = (v_1, \dots, v_n)$ is a basis for V , $\gamma = (w_1, \dots, w_n)$ is a basis for W

$$A = [T]_{\beta}^{\gamma} = \left[[T(v_1)]_{\gamma} \quad \cdots \quad [T(v_n)]_{\gamma} \right]$$

In $P_2(\mathbf{R})$:

$$[x^2 - 2x + 3]_{(x^2, x, 1)} = \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$$

$$[x^2 - 2x + 3]_{(1, x, x^2)} = \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix}$$

$$[x^2 - 2x + 3]_{(x^2, x, 3)} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

Coordinates depend on choice of basis!

$D: P_3(\mathbf{R}) \rightarrow P_2(\mathbf{R})$ (Differentiation)

$$\beta = (x^3, x^2, x, 1) \quad \gamma = (x^2, x, 1)$$

$$\begin{aligned} [D]_{\beta}^{\gamma} &= [D]_{(x^3, x^2, x, 1)}^{(x^2, x, 1)} = ([D(x^3)]_{\gamma} \quad [D(x^2)]_{\gamma} \quad [D(x)]_{\gamma} \quad [D(1)]_{\gamma}) \\ &= ([3x^2]_{\gamma} \quad [2x]_{\gamma} \quad [1]_{\gamma} \quad [0]_{\gamma}) \\ &= \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \end{aligned}$$

$T_{\theta}: \mathbf{R}_2 \rightarrow \mathbf{R}_2$

$$[T_{\theta}]_{e_1, e_2}^{e_1, e_2} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$