

# Problem Set 18 — MAT257

March 29, 2017

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Disclaimer—This page has been typeset by a student as a *convenient* consolidation of the homework problems. There inevitably will be mistakes; always defer to the official handout!

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## 1 “Ponder . . .”

1. Exercises in Munkres §34.
2. Exercises in Munkres §35.

## 2 Solve and submit!

- A. Consider  $S^{n-1}$  at the boundary of  $D^n \subset \mathbb{R}^n$ , taken with its standard orientation, and let  $\iota : S^{n-1} \rightarrow \mathbb{R}^n$  be the inclusion map. Let

$$\omega = \iota^* \left( \sum_i x_i dx_1 \wedge \cdots \wedge \widehat{dx}_i \wedge \cdots \wedge dx_n \right) \in \Omega^{\text{top}}(S^{n-1}).$$

Prove that if  $(\mathbf{v}_1, \dots, \mathbf{v}_{n-1})$  is a positively oriented basis of  $T_x S^{n-1}$  for some  $\mathbf{x} \in S^{n-1}$ , then  $\omega(\mathbf{v}_1, \dots, \mathbf{v}_{n-1})$  is the volume of the  $(n-1)$ -dimensional parallelepiped spanned by  $\mathbf{v}_1, \dots, \mathbf{v}_{n-1}$ , and hence for any smooth function  $f$  on  $S^{n-1}$ ,  $\int_{S^{n-1}} f \omega = \int_{S^{n-1}} f dV$ , where the latter integral is integration relative to the volume, as defined a long time ago.

- B. *An alternative definition for “orientation”.*

Define a **norientation** (“new orientation”) of a vector space  $V$  to be a function

$$\nu : \{\text{ordered bases of } V\} \rightarrow \{\pm 1\}$$

which satisfies

$$\nu(v) = \text{sign}(\det(C_v^u)) \nu(u)$$

whenever  $u$  and  $v$  are ordered bases of  $V$  and  $C_v^u$  is the change-of-basis matrix between them.

1. Explain how if  $\dim(V) > 1$ , a norientation is equivalent to an orientation.
2. Come up with a reasonable definition of a norientation of a  $k$ -dimensional manifold.
3. Explain how a norientation of  $M$  induces a norientation of  $\partial M$ .
4. What is a 0-dimensional manifold? What is a norientation of a 0-dimensional manifold?

5. What is the integral of a 0-form on a 0-dimensional oriented manifold?
  6. What is  $\partial[0, 1]$  as a oriented 0-manifold? (Assume that  $[0, 1]$  is endowed with its “positive” or “standard” orientation/orientation).
- C. Let  $\omega = y dx \in \Omega^1(\mathbb{R}_{x,y}^2)$ .
1. Let  $\Gamma$  be the graph in  $\mathbb{R}_{x,y}^2$  of some smooth function  $f: [a, b] \rightarrow \mathbb{R}$ . Using the inclusion of  $\Gamma$  to  $\mathbb{R}_{x,y}^2$ , consider  $\omega$  also as a 1-form on  $\Gamma$ . What is  $\int_{\Gamma} \omega$ ?
  2. Prove that if  $E$  is an ellipse in  $\mathbb{R}_{x,y}^2$  (of whatever major and minor axes, placed anywhere and tilted as you please), then  $\int_{\partial E} \omega$  is the area of  $E$ .
  3. Compute also  $d\omega$  and  $\int_E d\omega$ .