

$$F(S, \mathbb{R}) = \{ f: S \rightarrow \mathbb{R} \} \quad f(s) = 0 \quad \forall s \in S. \quad f \in F(S, \mathbb{R})$$

row. e. form is unique where e. fors is not.

Lecture
16.11.06

$$\begin{aligned} 2x - 7y &= -3 \\ -3x + 6y &= -4 \end{aligned}$$

$$\left. \begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m \end{aligned} \right\} \begin{array}{l} \text{system of} \\ \text{lin. eq'ns} \end{array}$$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad b = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix} \quad A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}_{m \times n}$$

$$\boxed{Ax = b} \Leftrightarrow \text{our system}$$

$$\begin{aligned} x - y &= 7 \\ x + 3y &= 2 \end{aligned} \quad x \mapsto \begin{pmatrix} x \\ y \end{pmatrix} \quad b \mapsto \begin{pmatrix} 7 \\ 2 \end{pmatrix} \quad \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}$$

Lucky Case: A is square & invertible

our system

$$Ax = b \Leftrightarrow A^{-1}Ax = A^{-1}b$$

$$\Rightarrow \boxed{x = A^{-1}b} \text{ lucky case}$$

Theory:

$b=0$ "homogeneous system"

Claim: Consider $AX=0$ $A \in M_{m \times n}(F)$ also a lin. trans.

① $X=0$ is always a solution $A: F^n \rightarrow F^m$

② X is a solution iff $X \in$ null space (A)
 $= \text{kernel}(A) : \text{Ker}(A)$

$b \neq 0$ "non-homogeneous system"

Claim: Consider $AX=b$

① System has a solution iff $b \in \text{range}(A) = \text{Im} A$

② If X_0 solves the system ($AX_0=b$)

X_1 solves system iff $X_1 = X_0 + X$ where X solves the homogeneous part of the matrix. $\Rightarrow \boxed{AX=0}$

Proof: We know $AX_0=b$

$$AX_1=b \Leftrightarrow A(X_0+X)=b \Leftrightarrow AX_0+AX=b$$

$$X_1 = X_0 + \underbrace{X}_{\substack{\text{homogeneous} \\ \text{part of the matrix}}} \Leftrightarrow b + AX = b \Leftrightarrow AX=0$$

\downarrow
we know

row operations = multiplying elem. matrices on the left

with row reduction:

$$A \rightsquigarrow A' = E \cdot A \quad \text{"in r.r.e.f."}$$

a product of invert. matrices, hence invertible.

$$Ax = b \Leftrightarrow \underbrace{E A}_A x = \underbrace{E b}_b \Leftrightarrow A' x = b'$$

$$T(Ax) = T(b)$$

Mechanical Aside: To find A' & b' at the same time,

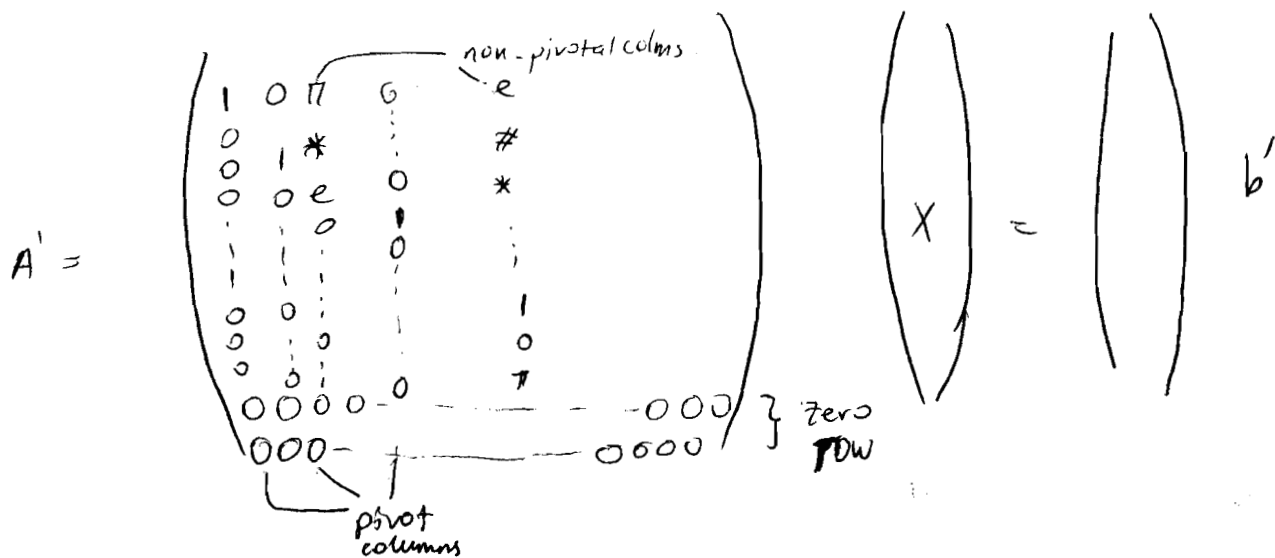
form $\tilde{A} = (A/b)$ row-reduce it

$$E\tilde{A} = (EA/Eb)$$

$A' \quad b'$

$$A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad b = \begin{pmatrix} 7 \\ 2 \end{pmatrix} \quad \tilde{A} = \left(\begin{array}{cc|c} 1 & 1 & 7 \\ 1 & -1 & 2 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 1 & 7 \\ 0 & -2 & -5 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{cc|c} 1 & 1 & 7 \\ 0 & 1 & 5/2 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 0 & 9/2 \\ 0 & 1 & 5/2 \end{array} \right)$$



Thm: ① If b' has a non-zero entry in one of the zero rows of A' ,
no solution.

② Otherwise all solutions are obtained by setting the entries of x
corresponding to the non-pivotal col's in an arbitrary way, and then the
rest is uniquely determined by solving single lin. eqn's.

Tutorial:

Defn: $Ax=b$, $b, x \in V^n$, $A \in M_{n,n}(V)$ if $b=0$, then this
system is called homogeneous.

Thm: If the system $T_A x = 0$ is ^{then} homog. then the dimension k of the
space of sol's. of that system

$$k = n - \text{rank } T_A = n - \text{rank } A$$

↓
dimension of the kernel of T_A (nullity of T_A)

• max # of lin. indep. columns in $A = \text{rank}(T_A) = \text{max \# of lin. indep. rows in } A$.

1) Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be given by

$$T(a, b, c) = (a+b, 2a-c)$$

Determine $T^{-1}(1, 1)$

i.e. the set of preimages of the point $(1, 1)$