

Why Tangles? - As common as knots!

- Faster computations!
- Conceptually clearer proofs of invariance (and of skein relations).
"Nautical Knots" Abstract. The zombies need to compute a quantity, the zombian, that pertains to some structure - say, a columbarium. But unfortunately (for them), a part of that structure will only be known in the future. What can they compute today with the parts they already have to hasten tomorrow's computation?
That's a common quest, and I will illustrate it with a few examples from knot theory and with two examples about matrices determinants and signatures. I will also mention two of my dreams (perhaps delusions): that one day I will be able to reproduce, and extend, the Rolfsen table of knots using code of the highest


Columbaria in an East Sydney Cemetery Jacobian, Hamiltonian, Zombian
Computing Zombians of Unfinished Columbaria.

- Future zombies must be able to complete the computation.
- Must be no slower than for finished ones.
- Future zombies must not even know the size of the task that today's zombies were facing.
- We must be able to extend to ZPUCs, Zombie Processed Unfinished Columbaria!
Exercise 1. Compute the sum of 1,000 numbers, the last 50 of which are still unknown.
Exercise 2. Compute the determinant of a Columbarium near Assen $1,000 \times 1,000$ matrix in which 50 entries are not yet given. Example 3. Same, for signatures of matrices / quadratic forms.
A quadratic form on a v.s. $V$ over $\mathbb{C}$ is a quadratic $Q: V \rightarrow \mathbb{C}$ or a sesquilinear Hermitian $\langle\cdot, \cdot\rangle$ on $V \times V$ (so $\langle x, y\rangle=\overline{\langle y, x\rangle}$ and Embarrassment 1 (personal). I don't know how to reproduce $Q(y)=\langle y, y\rangle$ ), or given a basis $\eta_{i}$ of $V^{*}$, a matrix $A=\left(a_{i j}\right)$ with the Rolfsen table of knots! Many others can, yet I still take it on $A=\bar{A}^{T}$ and $Q=\sum a_{i j} \bar{\eta}_{i} \eta_{j}$. The signature $\sigma$ of $Q$ is $\sigma_{+}-\sigma_{-}$, faith, contradicting one of the tenets of our practice, "thou shalt where for some $P, \bar{P}^{T} A P=\operatorname{diag}\left(1, \stackrel{\sigma}{+}^{\circ}, 1,-1, \stackrel{\sigma-}{\sigma},-1,0, \ldots\right)$.

A Partial Quadratic ( $P Q$ ) on $V$ is a quadratic $Q$ defined only on a subspace $\mathcal{D}_{Q} \subset V$. We add PQs with $\mathcal{D}_{Q_{1}+Q_{2}}:=\mathcal{D}_{Q_{1}} \cap \mathcal{D}_{Q_{2}}$. Given a linear $\psi: V \rightarrow W$ and a PQ $Q$ on $W$, there is an obvious pullback $\psi^{*} Q$, a PQ on $V$.
Theorem 1 (with Jessica Liu). Given a linear $\phi: V \rightarrow$ $W$ and a PQ $Q$ on $V$, there is a unique pushforward PQ $\phi_{*} Q$ on $W$ such that for every $P Q U$ on $W$,

$$
\sigma_{V}\left(Q+\phi^{*} U\right)=\sigma_{\operatorname{ker} \phi}\left(\left.Q\right|_{\operatorname{ker} \phi}\right)+\sigma_{W}\left(U+\phi_{*} Q\right)
$$

Gist of the Proof. $\quad$ Jessica Liu

. and the quadratic $F=: \phi_{*} Q$ is well-defined only on $D:=\operatorname{ker} C$.
(more at $\omega \varepsilon \beta /$ icerm.)
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 not use what thou canst not prove".
It's harder than it seems! Producing all knot diagrams is a mess, identifying all available Reidemeister moves is a mess, and you sometimes have to go up in crossing number before you can go down again.
Embarrassment 2 (communal). There isn't anywhere a tabulation of tangles! When you want to test your new discoveries, where do you go?
Dream. Conquer both embarrassments at once. Reproduce the Rolfsen table, and extend it to tangles, using code of the highest level of beauty. The algorithm should be so clear and simple that anyone should be able to easily implement it in an afternoon without messing with any technicalities.


We don't even need to look at all knot diagrams!


The dreaded slide moves, which go up in crossing number, are parametrized by tangles!


R-moves are tangle equalities!

