

Pensieve header: The Objects. Continues pensieve://Projects/SL2Portfolio2/Objects.nb.

The Objects

“Define” Code

```
SetAttributes[Define, HoldAll];
Define[def_, defs__] := (Define[def]; Define[defs]);
Define[op_is_ = ε_] := Module[{SD, ii, jj, kk, isp, nis, nisp, sis}, Block[{i, j, k},
  ReleaseHold[Hold[
    SD[op_nisp, $k_Integer, PPBoot@Block[{i, j, k}, op_isp, $k = ε; op_nis, $k]];
    SD[op_isp, op_{is}, $k]; SD[op_sis_, op_{sis}];
  ] /. {SD → SetDelayed,
    isp → {is} /. {i → ii, j → jj, k → kk},
    nis → {is} /. {i → ii, j → jj, k → kk},
    nisp → {is} /. {i → ii, j → jj, k → kk}
  } ] ]]
```

Symmetric Algebra Objects

```
sm_{i_→j_→k_} := Δ2E_{i,j}→{k} [b_k (β_i + β_j) + t_k (τ_i + τ_j) + a_k (α_i + α_j) + y_k (η_i + η_j) + x_k (ξ_i + ξ_j)];
sΔ_{i_→j_→k_} := Δ2E_{i}→{j,k} [β_i (b_j + b_k) + τ_i (t_j + t_k) + α_i (a_j + a_k) + η_i (y_j + y_k) + ξ_i (x_j + x_k)];
sS_{i_} := Δ2E_{i}→{i} [-β_i b_i - τ_i t_i - α_i a_i - η_i y_i - ξ_i x_i];
sη_{i_} := Δ2E_{i}→{i} [0];
sε_{i_} := Δ2E_{i}→{i} [0];
```

```
sσ_{i_→j_} := Δ2E_{i}→{j} [β_i b_j + τ_i t_j + α_i a_j + η_i y_j + ξ_i x_j];
sY_{i_→j_→k_→l_→m_} := Δ2E_{i}→{j,k,l,m} [β_i b_k + τ_i t_k + α_i a_l + η_i y_j + ξ_i x_m];
```

The CU Definitions

$$c\Lambda = \left(\eta_i + \frac{e^{-\alpha_i - \epsilon \beta_i} \eta_j}{1 + \epsilon \eta_j \xi_i} \right) y_k + \left(\beta_i + \beta_j + \frac{\text{Log}[1 + \epsilon \eta_j \xi_i]}{\epsilon} \right) b_k +$$

$$(\alpha_i + \alpha_j + \text{Log}[1 + \epsilon \eta_j \xi_i]) a_k + \left(\frac{e^{-\alpha_j - \epsilon \beta_j} \xi_i}{1 + \epsilon \eta_j \xi_i} + \xi_j \right) x_k;$$

$$\text{Define}[cm_{i,j \rightarrow k} = \Delta 2E_{\{i,j\} \rightarrow \{k\}} \left[\left(\eta_i + \frac{e^{-\alpha_i - \epsilon \beta_i} \eta_j}{1 + \epsilon \eta_j \xi_i} \right) y_k + \left(\beta_i + \beta_j + \frac{\text{Log}[1 + \epsilon \eta_j \xi_i]}{\epsilon} \right) b_k + \right.$$

$$\left. (\alpha_i + \alpha_j + \text{Log}[1 + \epsilon \eta_j \xi_i]) a_k + \left(\frac{e^{-\alpha_j - \epsilon \beta_j} \xi_i}{1 + \epsilon \eta_j \xi_i} + \xi_j \right) x_k \right]$$

```
Define [cσi→j = sσi,j /. τi → 0, cεi = sεi, cηi = sηi, cΔi→j,k = sΔi→j,k,
  cSi = sSi // sΥi→1,2,3,4 // cm4,3→i // cmi,2→i // cmi,1→i];
```

Booting Up QU

```
Define [aσi→j = Δ2E{i}→{j} [aj αi + xj ξi], bσi→j = Δ2E{i}→{j} [bj βi + yj ηi]]
```

```
Define [ami,j→k = Δ2E{i,j}→{k} [(αi + αj) ak + (Aj-1 ξi + ξj) xk],
  bmi,j→k = Δ2E{i,j}→{k} [(βi + βj) bk + (ηi + e-ε βi ηj) yk]]
```

```
Define [Ri,j = Module[{k}, Δ2E{i}→{i,j} [ħ aj bi + ∑k=1$k+1  $\frac{(1 - e^{\epsilon \hbar})^k (\hbar y_i x_j)^k}{k (1 - e^{k \epsilon \hbar})}$ ]]]
```

Three types of inverses appear below!

\bar{R} is the inverse of R in the algebra $\mathbb{B} \otimes \mathbb{A}$.

P is the inverse of R as a quadratic form, like how an element of $V^* \otimes V^*$ can be the inverse of an element of $V \otimes V$.

\overline{aS} is the inverse of aS as an operator form, like how an element of $V^* \otimes V$ can be the inverse of another element of $V^* \otimes V$.

In[]:=

```
Define [R̄i,j = If[$k == 0, E{i}→{i,j} [-ħ aj bi - ħ xj yi / Bi],
  Append[R̄{i,j},$k-1, -Last[PadRight[R̄{i,j},0,$k+1] R1,2 PadRight[R̄{3,4},$k-1,$k+1] //
    (bmi,1→i amj,2→j) // (bmi,3→i amj,4→j)]]]
]
```

```
Define [Pi,j = If[$k == 0, E{i,j}→{i} [βi αj / ħ + ηi ξj / ħ], Append[P{i,j},$k-1,
  -Last[R1,2 // (PadRight[P{1,j},0,$k+1] * PadRight[P{i,2},$k-1,$k+1]]]]]
```

```
Define [aSi = (aσi→2 R̄1,i) // P1,2]
```

```
Define [aS̄i = If[$k == 0, E{i}→{i} [-ai αi - xi Ai ξi],
  Append[aS̄{i},$k-1, -Last[PadRight[aS̄{i},0,$k+1] // aSi // PadRight[aS̄{i},$k-1,$k+1]]]
]
```

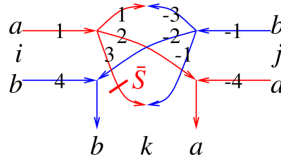
Booting Up QU

```

Define [bSi = bσi→1 Ri,2 // aS2 // P1,2,
        bSi = bσi→1 Ri,2 // aS2 // P1,2,
        aΔi→j,k = (R1,j R2,k) // bm1,2→3 // P3,i,
        bΔi→j,k = (Rj,1 Rk,2) // am1,2→3 // Pi,3]

```

The Drinfel'd double:



```

Define [
    dmi,j→k = ((sYi→4,4,1,1 // aΔ1→1,2 // aΔ2→2,3 // aS3) (sYj→-1,-1,-4,-4 // bΔ-1→-1,-2 // bΔ-2→-2,-3)) //
    (P-1,3 P-3,1 am2,-4→k bm4,-2→k) ]

```

```

Define [dσi→j = aσi→j bσi→j,
        dεi = sεi, dηi = sηi,
        dSi = sYi→1,1,2,2 // (bS1 aS2) // dm2,1→i,
        dSi = sYi→1,1,2,2 // (bS1 aS2) // dm2,1→i,
        dΔi→j,k = (bΔi→3,1 aΔi→2,4) // (dm3,4→k dm1,2→j) ]

```

```

Define [Ci = Λ2E{i}→{i} [-ħ/2 (bi + ε ai) ],
        Ci = Λ2E{i}→{i} [ħ/2 (bi + ε ai) ],
        Kinki = (R1,3 C2) // dm1,2→1 // dm1,3→i,
        Kinki = (R1,3 C2) // dm1,2→1 // dm1,3→i]

```

Not yet verified

Note. $t == \epsilon a - b$ and $b == -t + \epsilon a$.

```

Define [b2ti = Λ2E{i}→{i} [αi ai + βi (ε ai - ti) + ξi xi + ηi yi ],
        t2bi = Λ2E{i}→{i} [αi ai + τi (ε ai - bi) + ξi xi + ηi yi ] ]

```

The Knot Tensors

```

Define [kRi,j = (Ri,j // (b2ti b2tj)) /. ti|j → t,
      kR̄i,j = (R̄i,j // (b2ti b2tj)) /. {ti|j → t, Ti|j → T},
      kmi,j→k = ((t2bi t2bj) // dmi,j→k // b2tk) /. {tk → t, Tk → T, τi|j → 0},
      kCi = (Ci // b2ti) /. ti → t,
      kC̄i = (C̄i // b2ti) /. ti → t,
      kKinki = (Kinki // b2ti) /. {ti → t, Ti → T},
      kKink̄i = (Kink̄i // b2ti) /. {ti → t, Ti → T}]

```