

```
In[]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Talks\\ICERM-2305"];
<< Signatures`
```

```
In[]:= { ( (2 u - ω + 3 ω⁻¹) ℙ₁ ℙ₂ ) * , ( ℙ₁ → ω ℙ₂ ) + }
```

```
Out[]=
```

$$\left\{ \left(2 u - \omega + 3 \omega^{-1} \right) \bar{\eta}_1 \bar{\eta}_2, \left\{ \eta_1 \rightarrow \omega \eta_2, \bar{\eta}_1 \rightarrow \frac{\bar{\eta}_2}{\omega} \right\} \right\}$$

```
In[]:= CF[ {η₁ - η₂, η₁ - η₃} ]
```

```
Out[]=
```

$$\{ \eta_1 - \eta_3, \eta_2 - \eta_3 \}$$

```
In[]:= RulesOf[η₁ + η₂ + η₃]
```

```
Out[]=
```

$$\{ \eta_1 \rightarrow -\eta_2 - \eta_3, \bar{\eta}_1 \rightarrow -\bar{\eta}_2 - \bar{\eta}_3 \}$$

```
In[]:= Σ_{B[{-1,2}]}[0, PQ[], 0] ∪ Σ_{B[{-3,4}]}[0, PQ[], 0] // FM_{-1,4}
```

```
Out[]=
```

$$\begin{matrix} & & 0 \\ & 0 & 1 & 0 & -1 \\ (\eta_{-3} & \eta_{-1} & \eta_2 & \eta_4) \\ \bar{\eta}_{-3} & 0 & 0 & 0 \\ \bar{\eta}_{-1} & 0 & 0 & 0 \\ \bar{\eta}_2 & 0 & 0 & 0 \\ \bar{\eta}_4 & 0 & 0 & 0 \end{matrix}$$

```
In[]:= Kas /@ {X+[1, 2, 3, 4], X-[1, 4, 3, 2]}
```

```
Out[]=
```

$$\left\{ \begin{matrix} & & -1 & & & & 1 & & \\ (\eta_1 & \eta_2 & \eta_3 & \eta_4) & & & & (\eta_1 & \eta_4 & \eta_3 & \eta_2) \\ \frac{\bar{\eta}_1}{\bar{\eta}_2} & 2 u^2 - 1 & u & 1 & u & \bar{\eta}_1 & 1 - 2 u^2 & -u & -1 & -u \\ u & 1 & u & u & 1 & \bar{\eta}_4 & -u & -1 & -u & -1 \\ \bar{\eta}_3 & 1 & u & 2 u^2 - 1 & u & \bar{\eta}_3 & -1 & -u & 1 - 2 u^2 & -u \\ \bar{\eta}_4 & u & 1 & u & 1 & \bar{\eta}_2 & -u & -1 & -u & -1 \end{matrix} \right\}$$

```
In[]:= TL /@ {X[1, 2, 3, 4], X[1, 4, 3, 2]}
```

```
Out[]=
```

$$\left\{ \begin{matrix} & & 0 & & & & 0 & & \\ (\eta_{-4} & \eta_{-1} & \eta_2 & \eta_3) & & & & (\eta_{-4} & \eta_3 & \eta_2 & \eta_{-1}) \\ \bar{\eta}_{-4} & 0 & 1 - \omega & 0 & \omega - 1 & \bar{\eta}_{-4} & -\frac{(\omega-1)^2}{\omega} & \omega - 1 & -\frac{2(\omega-1)}{\omega} & \frac{\omega-1}{\omega} \\ \frac{\bar{\eta}_{-1}}{\bar{\eta}_1} & \frac{\omega-1}{\omega} & \frac{(\omega-1)^2}{\omega} & \omega - 1 & -2(\omega - 1), & \bar{\eta}_3 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & 0 \\ \bar{\eta}_2 & 0 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & \bar{\eta}_2 & 2(\omega - 1) & 1 - \omega & -\frac{(\omega-1)^2}{\omega} & -\frac{\omega-1}{\omega} \\ \bar{\eta}_3 & -\frac{\omega-1}{\omega} & \frac{2(\omega-1)}{\omega} & 1 - \omega & \frac{(\omega-1)^2}{\omega} & \bar{\eta}_{-1} & 1 - \omega & 0 & \omega - 1 & 0 \end{matrix} \right\}$$

In[1]:= **Kas**[**Knot**[3, 1]]

Out[1]=

$$4 \Theta\left(u + \frac{\sqrt{3}}{2}\right) - 4 \Theta\left(u - \frac{\sqrt{3}}{2}\right)$$

In[2]:= **KasSig**[**Knot**[3, 1]]

Out[2]=

$$-2 \Theta\left[-\frac{\sqrt{3}}{2} + u\right] + 2 \Theta\left[\frac{\sqrt{3}}{2} + u\right]$$

In[3]:= **TLSig**[**Knot**[3, 1]]

Out[3]=

$$-2 \Theta\left[-\frac{\sqrt{3}}{2} + u\right] + 2 \Theta\left[\frac{\sqrt{3}}{2} + u\right]$$

In[4]:= **Kas**[**X**[1, 5, 2, 4]] \cup **Kas**[**X**[2, 5, 3, 6]]

Out[4]=

θ								
	$(\eta_{-5}$	η_3	η_6	$\eta_{-2})$	$(\eta_{-4}$	η_{-1}	η_5	$\eta_2)$
$\bar{\eta}_{-5}$	$1 - 2 u^2$	$-u$	-1	$-u$	0	0	0	0
$\bar{\eta}_3$	$-u$	-1	$-u$	-1	0	0	0	0
$\bar{\eta}_6$	-1	$-u$	$1 - 2 u^2$	$-u$	0	0	0	0
$\bar{\eta}_{-2}$	$-u$	-1	$-u$	-1	0	0	0	0
$\bar{\eta}_{-4}$	0	0	0	0	1	u	1	u
$\bar{\eta}_{-1}$	0	0	0	0	u	$2 u^2 - 1$	u	1
$\bar{\eta}_5$	0	0	0	0	1	u	1	u
$\bar{\eta}_2$	0	0	0	0	u	1	u	$2 u^2 - 1$

In[5]:= **Kas**[**X**[1, 5, 2, 4]] \cup **Kas**[**X**[2, 5, 3, 6]] // **FM**_{5, -2}

Out[5]=

θ								
	0	0	0	-1	0	0	0	1
	$(\eta_{-5}$	η_3	η_6	η_5	η_2	η_{-4}	η_{-1}	$\eta_{-2})$
$\bar{\eta}_{-5}$	$1 - 2 u^2$	$-u$	-1	$-u$	0	0	0	0
$\bar{\eta}_3$	$-u$	-1	$-u$	-1	0	0	0	0
$\bar{\eta}_6$	-1	$-u$	$1 - 2 u^2$	$-u$	0	0	0	0
$\bar{\eta}_5$	$-u$	-1	$-u$	0	u	1	u	0
$\bar{\eta}_2$	0	0	0	u	$2 u^2 - 1$	u	1	0
$\bar{\eta}_{-4}$	0	0	0	1	u	1	u	0
$\bar{\eta}_{-1}$	0	0	0	u	1	u	$2 u^2 - 1$	0
$\bar{\eta}_{-2}$	0	0	0	0	0	0	0	0

In[]:= **Kas[X[1, 5, 2, 4]]** \cup **Kas[X[2, 5, 3, 6]]** // **FM_{5,-2}** // **Cordon₋₂**

Out[]:=

θ					
η_{-5}	η_3	η_6	η_5	η_2	η_{-4}
$\bar{\eta}_{-5}$	θ	$-u$	-1	0	1
$\bar{\eta}_3$	$-u$	-1	$-u$	-1	0
$\bar{\eta}_6$	-1	$-u$	$1 - 2u^2$	$-u$	0
$\bar{\eta}_5$	0	-1	$-u$	0	u
$\bar{\eta}_2$	1	0	0	u	$2u^2 - 1$
$\bar{\eta}_{-4}$	u	0	0	1	u

In[]:= **Kas[X[1, 5, 2, 4]]** \cup **Kas[X[2, 5, 3, 6]]** // **FM_{-2,5}** // **Cordon₅** // **Cordon₋₂**

Out[]:=

θ			
η_{-5}	η_3	η_2	η_{-4}
$\bar{\eta}_{-5}$	0	0	0
$\bar{\eta}_3$	0	0	0
$\bar{\eta}_2$	0	0	0
$\bar{\eta}_{-4}$	0	0	0

In[]:= **lhs = Kas[X[4, 2, 5, 1]]** \cup **Kas[X[7, 3, 8, 2]]** \cup **Kas[X[8, 6, 9, 5]]** // **mc**;
rhs = Kas[X[7, 5, 8, 4]] \cup **Kas[X[8, 2, 9, 1]]** \cup **Kas[X[5, 3, 6, 2]]** // **mc**
{**lhs[[1]], rhs[[1]]**}
Simplify[lhs[[2, 2]] == rhs[[2, 2]]]

Out[]:=

$$\begin{array}{cccccc} & & 2\theta\left(u - \frac{1}{2}\right) - 2\theta\left(u + \frac{1}{2}\right) - 2 & & & \\ \bar{\eta}_{-7} & \frac{(\eta_{-7})}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & -\frac{2u}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} \\ \bar{\eta}_3 & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & \frac{2(2u^2-1)}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & -\frac{2u}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} \\ \bar{\eta}_6 & -\frac{1}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & \frac{2u^2(4u^2-3)}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & -\frac{2}{(2u-1)(2u+1)} \\ \bar{\eta}_9 & -\frac{2u}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & \frac{2u^2(4u^2-3)}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} \\ \bar{\eta}_{-1} & -\frac{1}{(2u-1)(2u+1)} & -\frac{2u}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & \frac{2(2u^2-1)}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} \\ \bar{\eta}_{-4} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & -\frac{2u}{(2u-1)(2u+1)} & -\frac{1}{(2u-1)(2u+1)} & \frac{u(4u^2-3)}{(2u-1)(2u+1)} & \frac{2u^2(4u^2-3)}{(2u-1)(2u+1)} \end{array}$$

Out[]:=

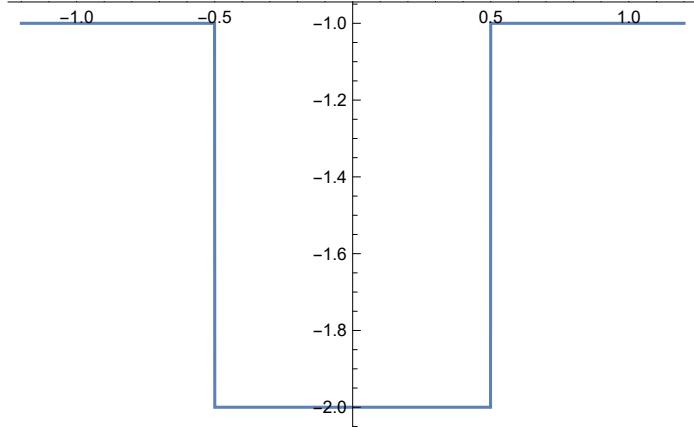
$$\left\{ -2 + 2\theta\left(-\frac{1}{2} + u\right) - 2\theta\left(\frac{1}{2} + u\right), -2 + 2\theta\left(-\frac{1}{2} + u\right) - 2\theta\left(\frac{1}{2} + u\right) \right\}$$

Out[]:=

True

```
In[=]:= f = KasSig@PD[X[4, 2, 5, 1], X[7, 3, 8, 2], X[8, 6, 9, 5]];
Plot[f, {u, -1.2, 1.2}]
```

Out[=]=



```
In[=]:= lhs = TL[X[4, 2, 5, 1]] \[Union] TL[X[7, 3, 8, 2]] \[Union] TL[X[8, 6, 9, 5]] // mc;
rhs = TL[X[7, 5, 8, 4]] \[Union] TL[X[8, 2, 9, 1]] \[Union] TL[X[5, 3, 6, 2]] // mc
{lhs[[1]], rhs[[1]]}
lhs[[2, 2]] == rhs[[2, 2]]
```

Out[=]=

$$\begin{array}{ccccccc} & 2\theta(u-1) - 2\theta(u+1) + 1 & & & & & \\ (\eta_7) & \eta_3 & \eta_6 & \eta_9 & \eta_{-1} & \eta_{-4}) & \\ \overline{\eta}_{-7} & \frac{\omega^2+1}{\omega} & \omega-1 & -2\omega & 2 & 0 & -\frac{\omega+1}{\omega} \\ \overline{\eta}_3 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & 0 & 0 & 0 \\ \overline{\eta}_6 & -\frac{2}{\omega} & 1-\omega & \frac{\omega^2+1}{\omega} & -\frac{\omega+1}{\omega} & 0 & \frac{2}{\omega} \\ \overline{\eta}_9 & 2 & 0 & -\omega-1 & \frac{\omega^2+1}{\omega} & -\frac{\omega-1}{\omega} & -\frac{2}{\omega} \\ \overline{\eta}_{-1} & 0 & 0 & 0 & \omega-1 & 0 & 1-\omega \\ \overline{\eta}_{-4} & -\omega-1 & 0 & 2\omega & -2\omega & \frac{\omega-1}{\omega} & \frac{\omega^2+1}{\omega} \end{array}$$

Out[=]=

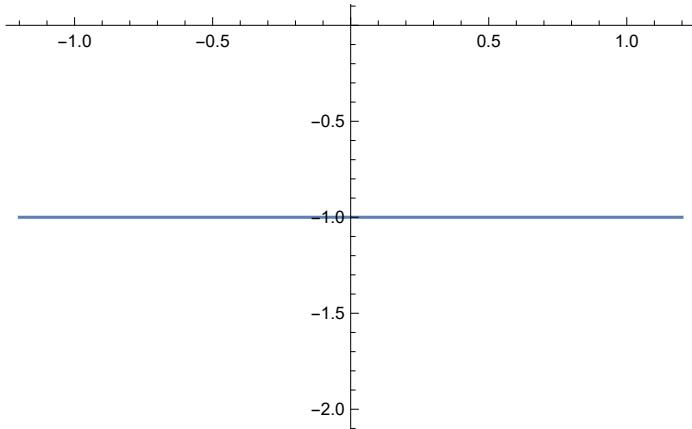
$$\{1 + 2\theta[-1+u] - 2\theta[1+u], 1 + 2\theta[-1+u] - 2\theta[1+u]\}$$

Out[=]=

True

```
In[]:= f = TLSig@PD[X[4, 2, 5, 1], X[7, 3, 8, 2], X[8, 6, 9, 5]];
Plot[f, {u, -1.2, 1.2}]
```

Out[]=



Kashaev for Knots

```
In[]:= -KnotSignature @ AllKnots[{3, 8}]
```

KnotTheory: Loading precomputed data in PD4Knots`.

Out[]=

```
{2, 0, 4, 2, 0, 2, 0, 6, 2, -4, -2, 4, 2, 0, 0, 4,
0, 2, -4, 2, -2, 0, 0, -2, 2, 0, 0, 2, 4, 2, 0, 0, -6, 0, 2}
```

```
In[]:= (*u=0; *)

```

```
Kas[Knot[3, 1]]
```

```
Clear[u]
```

Out[]=

$$4 \Theta\left(u + \frac{\sqrt{3}}{2}\right) - 4 \Theta\left(u - \frac{\sqrt{3}}{2}\right)$$

```
In[]:= \Sigma_B[] \left[ \text{sign} \left[ \frac{1}{2} (3 - 4 u^2) \right] + \text{sign} \left[ -2 (-1 + 2 u^2) \right] + \text{sign} \left[ -\frac{-3 + 4 u^2}{-1 + 2 u^2} \right], \text{PQ}[\{\}, 0] \right]
```

Out[]=

$$-4 \Theta\left(u - \frac{\sqrt{3}}{2}\right) + 4 \Theta\left(u + \frac{\sqrt{3}}{2}\right) - 3$$

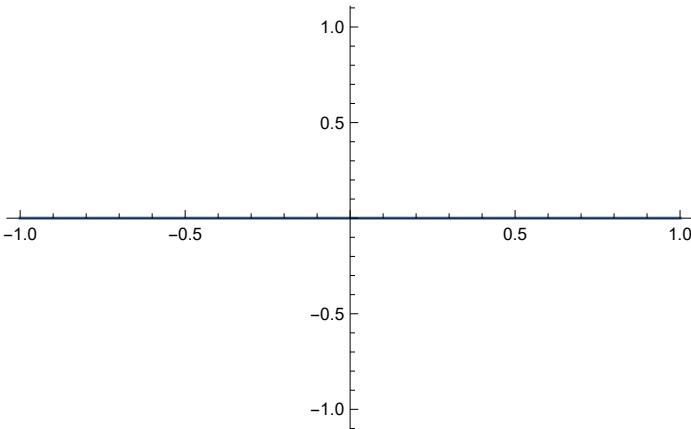
```
In[]:= Table[K → 2 KasSig[K], {K, AllKnots[{3, 7}]}] // Column
Out[]=
Knot[3, 1] → 2 (-2 θ[- $\frac{\sqrt{3}}{2}$  + u] + 2 θ[ $\frac{\sqrt{3}}{2}$  + u])
Knot[4, 1] → 0
Knot[5, 1] →
2 (2 θ[u -  $\sqrt{-0.951\dots}$ ] + 2 θ[u -  $\sqrt{-0.588\dots}$ ] - 2 θ[u -  $\sqrt{0.588\dots}$ ] - 2 θ[u -  $\sqrt{0.951\dots}$ ])
Knot[5, 2] → 2 (-2 θ[- $\frac{\sqrt{\frac{7}{2}}}{2}$  + u] + 2 θ[ $\frac{\sqrt{\frac{7}{2}}}{2}$  + u])
Knot[6, 1] → 0
Knot[6, 2] → 2 (2 θ[u -  $\sqrt{-0.772\dots}$ ] - 2 θ[u -  $\sqrt{0.772\dots}$ ])
Knot[6, 3] → 0
Knot[7, 1] → 2 (2 θ[u -  $\sqrt{-0.975\dots}$ ] + 2 θ[u -  $\sqrt{-0.782\dots}$ ] +
2 θ[u -  $\sqrt{-0.434\dots}$ ] - 2 θ[u -  $\sqrt{0.434\dots}$ ] - 2 θ[u -  $\sqrt{0.782\dots}$ ] - 2 θ[u -  $\sqrt{0.975\dots}$ ])
Knot[7, 2] → 2 (-2 θ[- $\frac{\sqrt{\frac{11}{3}}}{2}$  + u] + 2 θ[ $\frac{\sqrt{\frac{11}{3}}}{2}$  + u])
Knot[7, 3] →
2 (-2 θ[u -  $\sqrt{-0.972\dots}$ ] - 2 θ[u -  $\sqrt{-0.656\dots}$ ] + 2 θ[u -  $\sqrt{0.656\dots}$ ] + 2 θ[u -  $\sqrt{0.972\dots}$ ])
Knot[7, 4] → 2 (2 θ[- $\frac{\sqrt{15}}{4}$  + u] - 2 θ[ $\frac{\sqrt{15}}{4}$  + u])
Knot[7, 5] →
2 (2 θ[u -  $\sqrt{-0.963\dots}$ ] + 2 θ[u -  $\sqrt{-0.757\dots}$ ] - 2 θ[u -  $\sqrt{0.757\dots}$ ] - 2 θ[u -  $\sqrt{0.963\dots}$ ])
Knot[7, 6] → 2 (2 θ[u -  $\sqrt{-0.920\dots}$ ] - 2 θ[u -  $\sqrt{0.920\dots}$ ])
Knot[7, 7] → 0
```

```
In[]:= f = KasSig[Knot[10, 1]]
Plot[f, {u, -1, 1}]
```

Out[]=

0

Out[]=

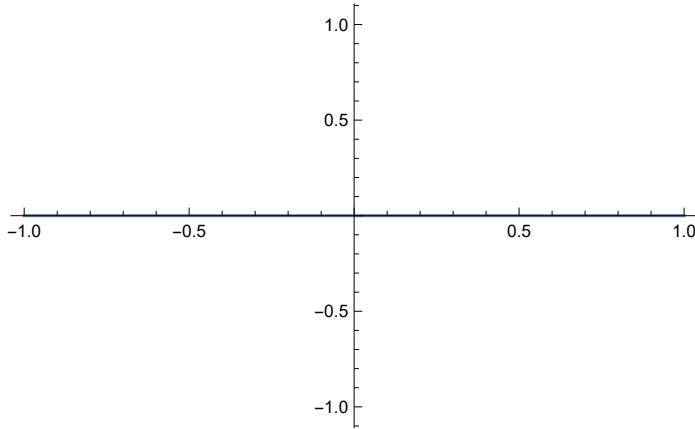


```
In[]:= f = TLSig[Knot[10, 1]]
Plot[f, {u, -1, 1}]
```

Out[]=

0

Out[]=



```
In[]:= (KasSig /@ AllKnots[{3, 8}]) /. u → 1/2
```

Out[]=

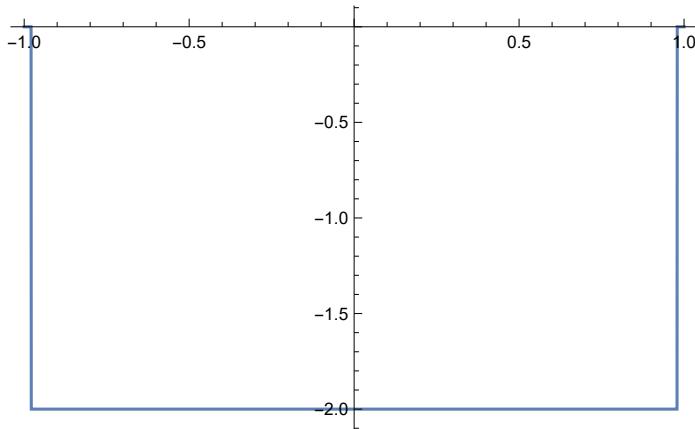
```
{2, 0, 4, 2, 0, 2, 0, 4, 2, -4, -2, 4, 2, 0, 0, 4,
0, 2, -4, 2, -2, 0, 0, -2, 2, 0, 0, 2, 4, 2, 0, 0, -4, 0, 2}
```

```
In[]:= f = KasSig[Knot[9, 5]]
Plot[f, {u, -1, 1}]
```

Out[]=

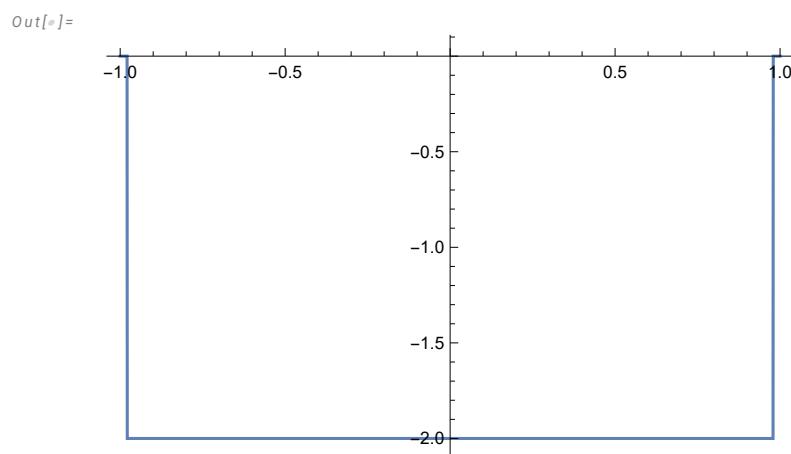
$$2 \Theta\left[-\frac{\sqrt{\frac{23}{6}}}{2} + u\right] - 2 \Theta\left[\frac{\sqrt{\frac{23}{6}}}{2} + u\right]$$

Out[]=



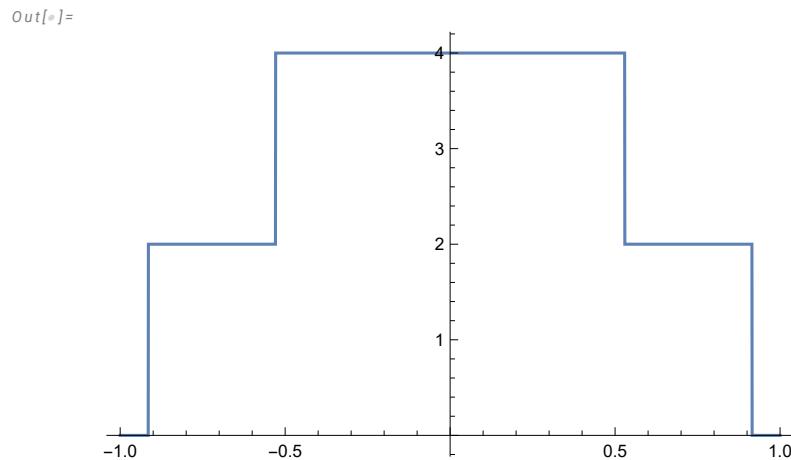
```
In[]:= f = TLSig[Knot[9, 5]]
Plot[f, {u, -1, 1}]

Out[]=
```

$$2 \Theta\left[-\frac{\sqrt{\frac{23}{6}}}{2} + u\right] - 2 \Theta\left[\frac{\sqrt{\frac{23}{6}}}{2} + u\right]$$


```
In[]:= f = KasSig[Knot[8, 2]]
Plot[f, {u, -1, 1}]

Out[=]
```

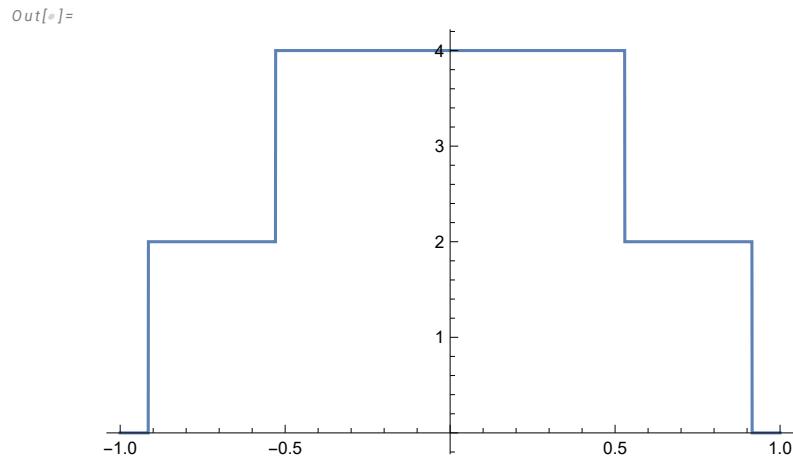
$$2 \Theta\left[u - (-0.915\dots)\right] + 2 \Theta\left[u - (-0.529\dots)\right] - 2 \Theta\left[u - (0.529\dots)\right] - 2 \Theta\left[u - (0.915\dots)\right]$$


```
In[=]:= f = TLSig[Knot[8, 2]]
Plot[f, {u, -1, 1}]

Out[=]=

$$2 \Theta[u - (-0.915\ldots)] + 2 \Theta[u - (-0.529\ldots)] - 2 \Theta[u - (0.529\ldots)] - 2 \Theta[u - (0.915\ldots)]$$

```



```
In[=]:= f = KasSig[Knot[12, Alternating, 422]]
Plot[f, {u, -1, 1}]
```

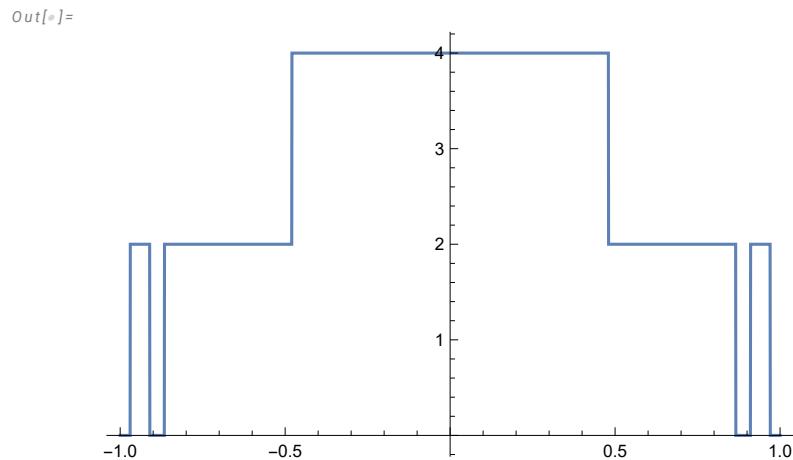
KnotTheory: Loading precomputed data in KnotTheory/12A.dts.

KnotTheory: The GaussCode to PD conversion was written by Siddarth Sankaran at the University of Toronto in the summer of 2005.

```
Out[=]=

$$-2 \Theta\left[-\frac{\sqrt{3}}{2} + u\right] + 2 \Theta\left[\frac{\sqrt{3}}{2} + u\right] + 2 \Theta[u - (-0.970\ldots)] - 2 \Theta[u - (-0.910\ldots)] + \\ 2 \Theta[u - (-0.480\ldots)] - 2 \Theta[u - (0.480\ldots)] + 2 \Theta[u - (0.910\ldots)] - 2 \Theta[u - (0.970\ldots)]$$

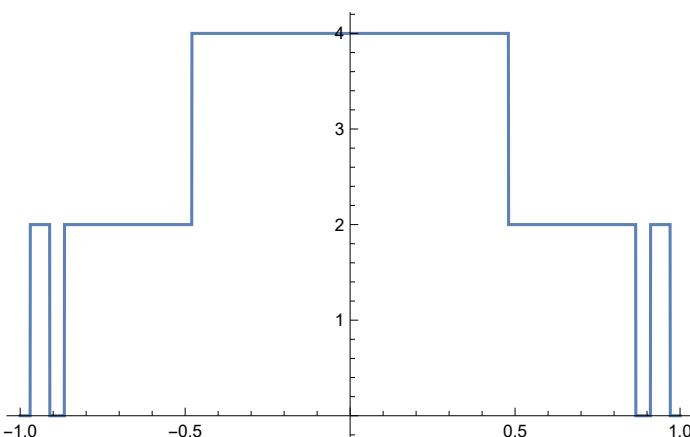
```



```
In[8]:= f = TLSig[Knot[12, Alternating, 422]]
Plot[f, {u, -1, 1}]

Out[8]=
```

$$-2 \theta \left[-\frac{\sqrt{3}}{2} + u\right] + 2 \theta \left[\frac{\sqrt{3}}{2} + u\right] + 2 \theta \left[u - \text{Root}\left(-0.970... + \sqrt{u^2 - 1}, 1\right)\right] - 2 \theta \left[u - \text{Root}\left(-0.910... + \sqrt{u^2 - 1}, 1\right)\right] + 2 \theta \left[u - \text{Root}\left(-0.480... + \sqrt{u^2 - 1}, 1\right)\right] - 2 \theta \left[u - \text{Root}\left(0.480... + \sqrt{u^2 - 1}, 1\right)\right] + 2 \theta \left[u - \text{Root}\left(0.910... + \sqrt{u^2 - 1}, 1\right)\right] - 2 \theta \left[u - \text{Root}\left(0.970... + \sqrt{u^2 - 1}, 1\right)\right]$$



Tristram-Levine for Knots

```
In[1]:= -KnotSignature /@ AllKnots[{3, 8}]
Out[1]= {2, 0, 4, 2, 0, 2, 0, 6, 2, -4, -2, 4, 2, 0, 0, 4,
0, 2, -4, 2, -2, 0, 0, -2, 2, 0, 0, 2, 4, 2, 0, 0, -6, 0, 2}
```

`|n[•]:= TL[Knot[3, 1]]`

Out[•] =

$$2\theta\left(u + \frac{\sqrt{3}}{2}\right) - 2\theta\left(u - \frac{\sqrt{3}}{2}\right)$$

```
In[•]:= TLSig /@ AllKnots[{3, 8}] /. u → 0
```

Out[•] =

$$\{2, 0, 4, 2, 0, 2, 0, 6, 2, -4, -2, 4, 2, 0, 0, 4, 0, 2, -4, 2, -2, 0, 0, -2, 2, 0, 0, 2, 4, 2, 0, 0, -6, 0, 2\}$$

```
In[•]:= TLSig /@ AllKnots[{3, 8}] /. u → 0.9999
```

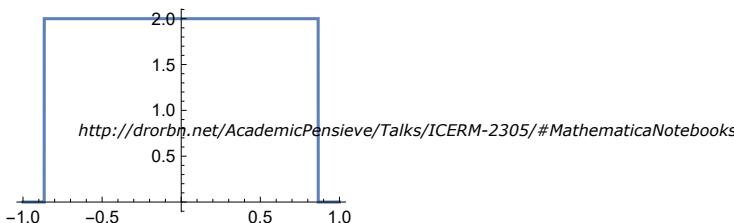
Out[•]=

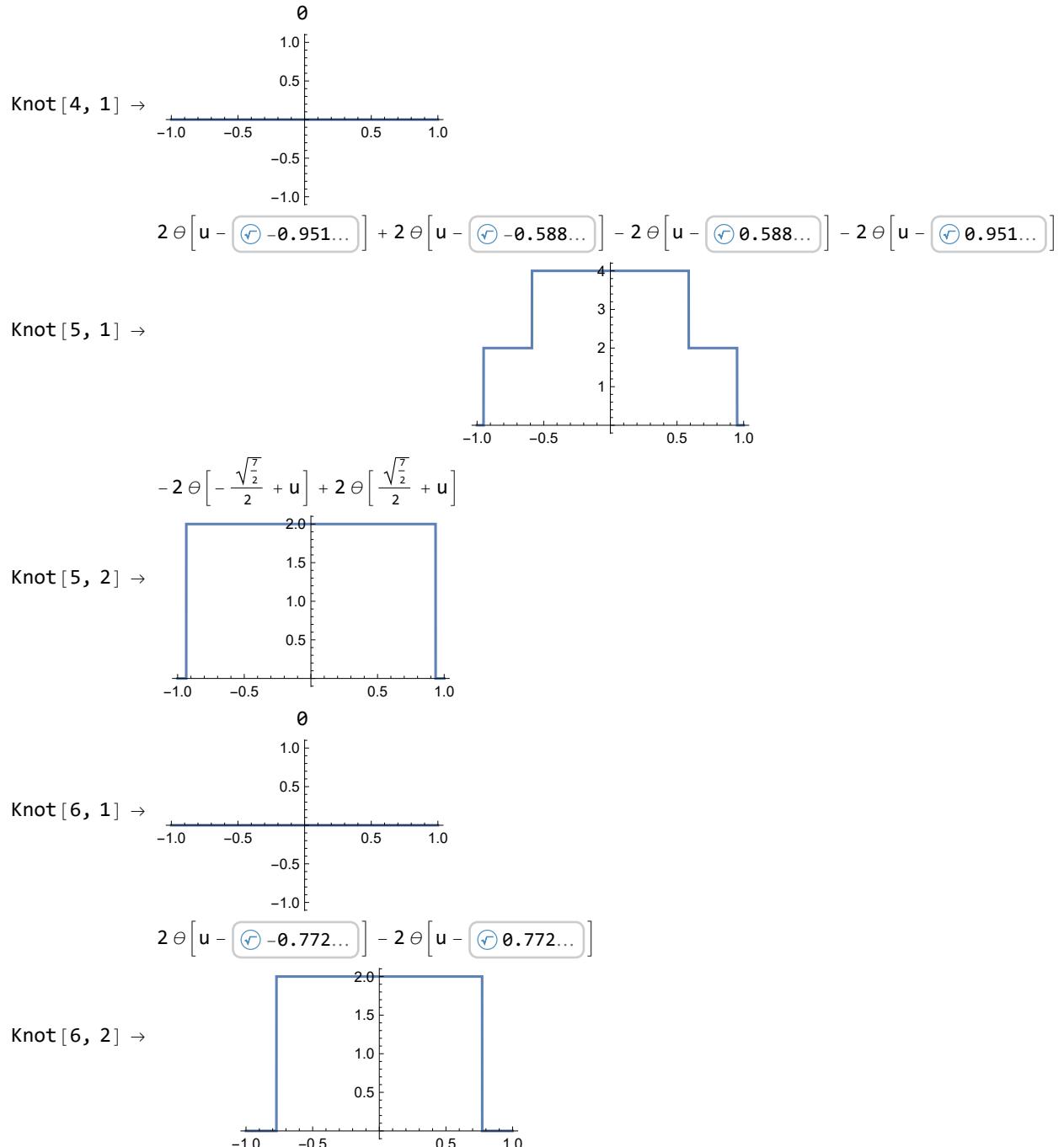
```
In[8]:= Table[K \[Rule] Column[{f = TLSig[K], Plot[f, {u, -1, 1}]}, Center], {K, AllKnots[{3, 8}]}] // Column
```

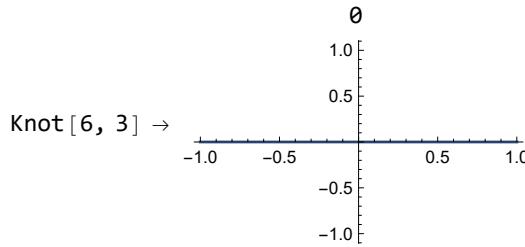
Out[•] =

$$-2\theta \left[-\frac{\sqrt{3}}{2} + u \right] + 2\theta \left[\frac{\sqrt{3}}{2} + u \right]$$

Knot [3 1] →





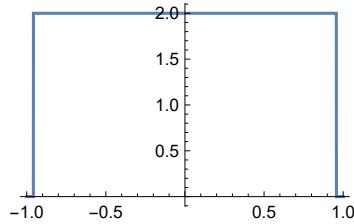


Knot [7, 1] →

$$2 \theta \left[u - (\sqrt{-0.975\dots}) \right] + 2 \theta \left[u - (\sqrt{-0.782\dots}) \right] + 2 \theta \left[u - (\sqrt{-0.434\dots}) \right] - \\ 2 \theta \left[u - (\sqrt{0.434\dots}) \right] - 2 \theta \left[u - (\sqrt{0.782\dots}) \right] - 2 \theta \left[u - (\sqrt{0.975\dots}) \right]$$

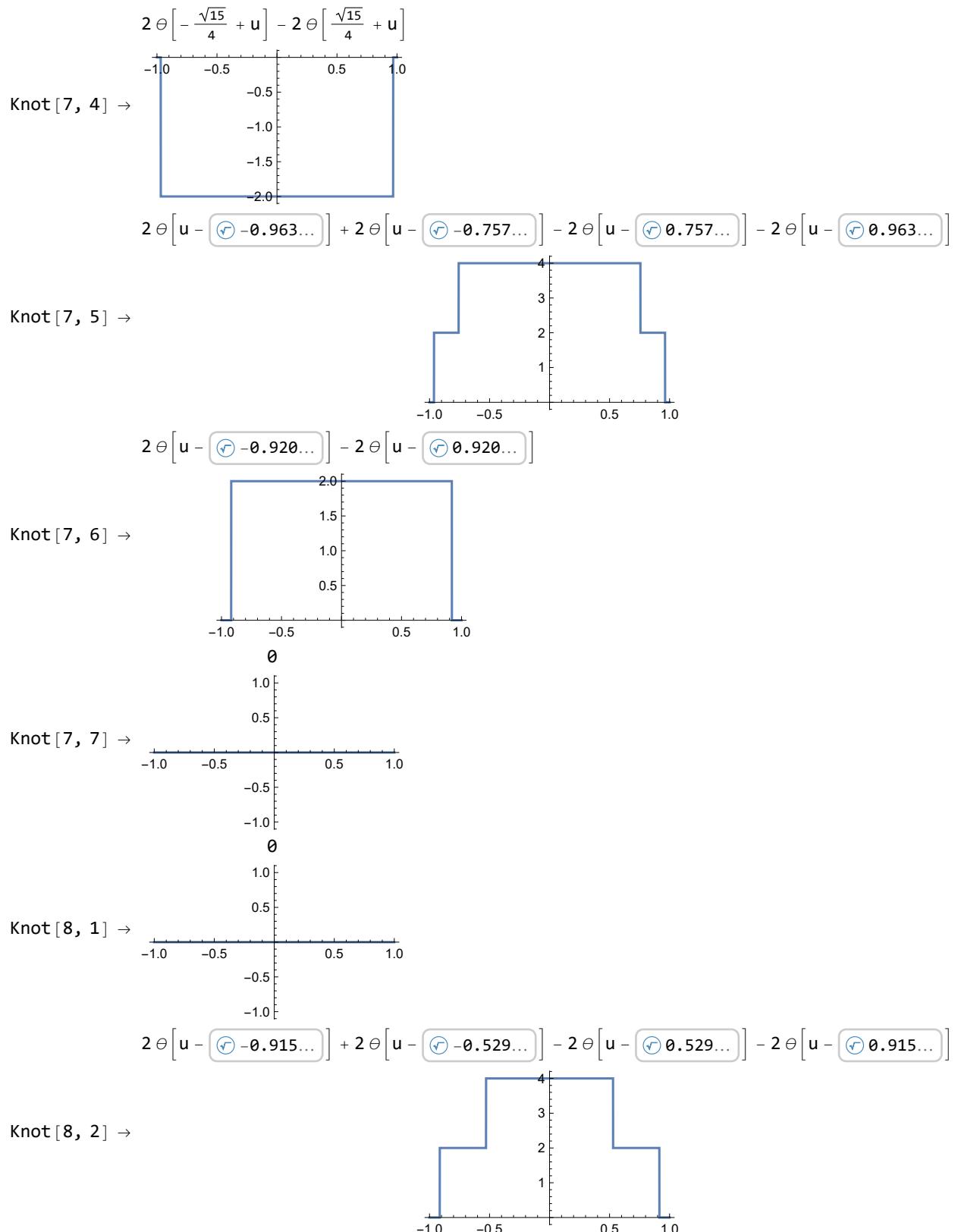
$$-2 \theta \left[-\frac{\sqrt{\frac{11}{3}}}{2} + u \right] + 2 \theta \left[\frac{\sqrt{\frac{11}{3}}}{2} + u \right]$$

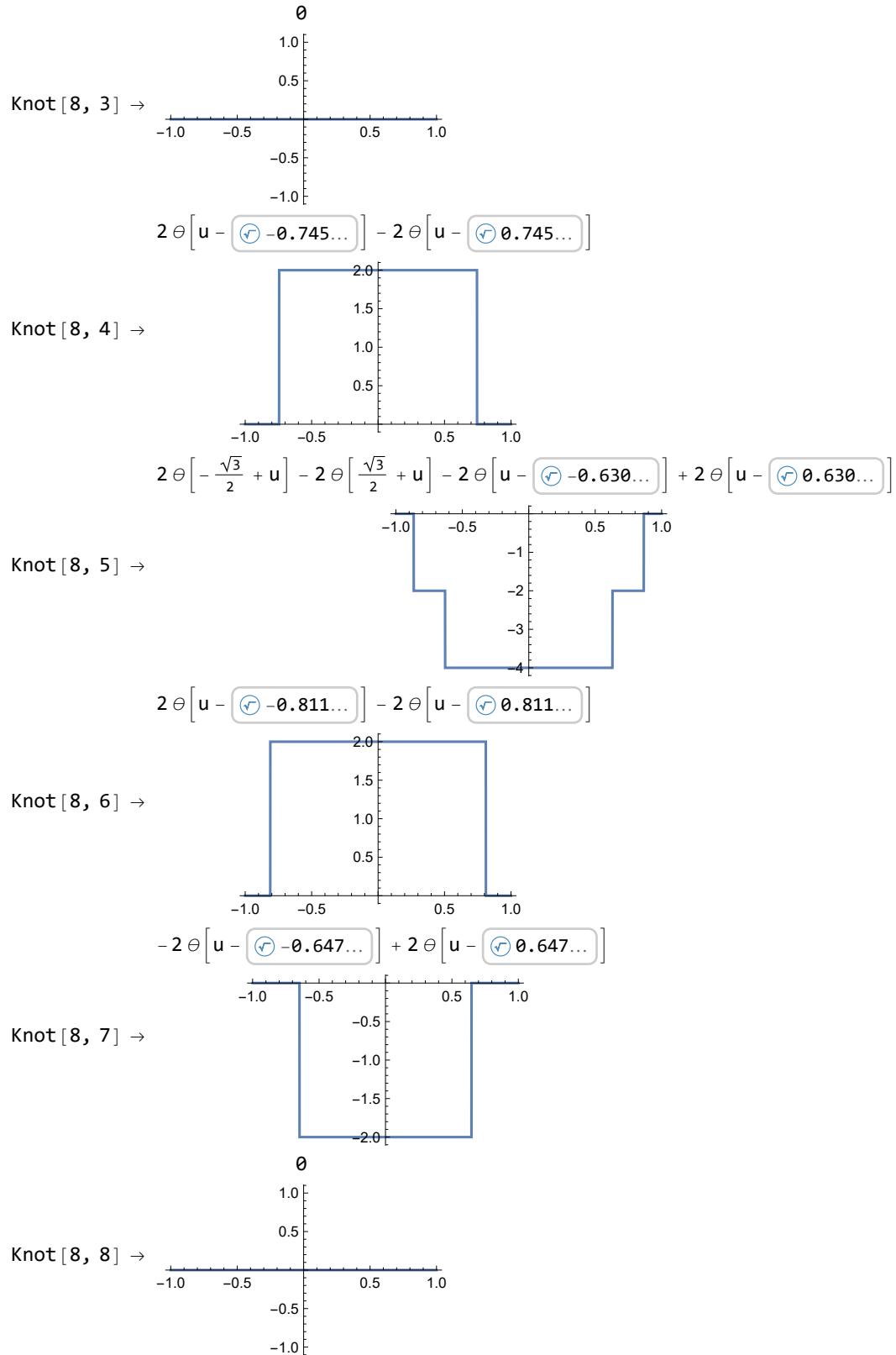
Knot [7, 2] →

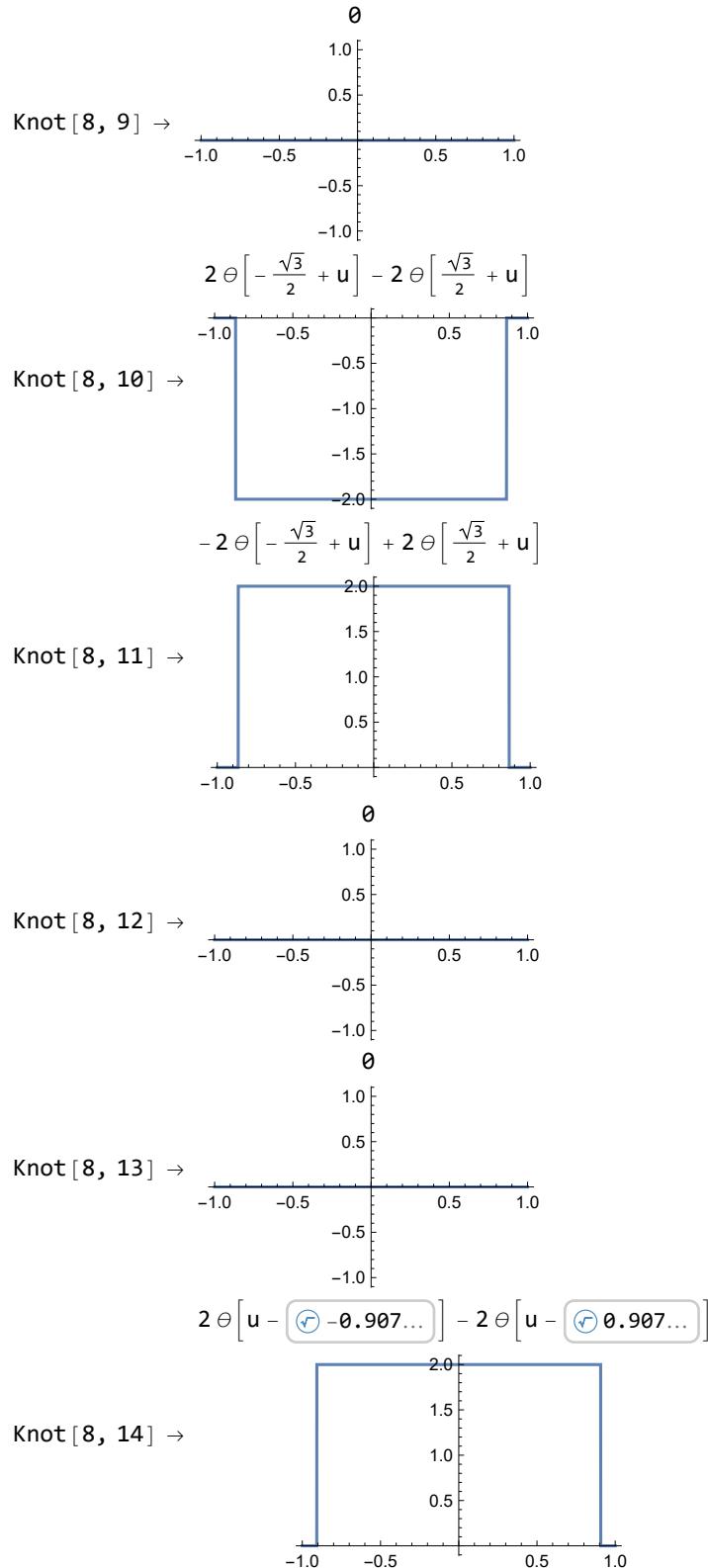


Knot [7, 3] →

$$-2 \theta \left[u - (\sqrt{-0.972\dots}) \right] - 2 \theta \left[u - (\sqrt{-0.656\dots}) \right] + 2 \theta \left[u - (\sqrt{0.656\dots}) \right] + 2 \theta \left[u - (\sqrt{0.972\dots}) \right]$$

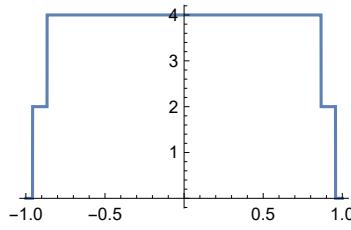






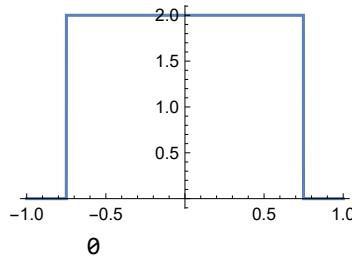
$$-2 \Theta\left[-\frac{\sqrt{3}}{2} + u\right] + 2 \Theta\left[\frac{\sqrt{3}}{2} + u\right] - 2 \Theta\left[-\frac{\sqrt{\frac{11}{3}}}{2} + u\right] + 2 \Theta\left[\frac{\sqrt{\frac{11}{3}}}{2} + u\right]$$

Knot [8, 15] →

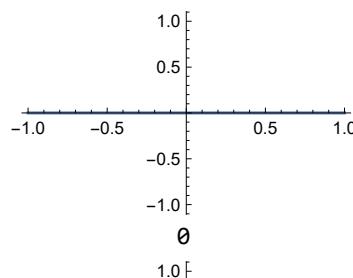


$$2 \Theta\left[u - \text{(checkmark)} -0.749\dots\right] - 2 \Theta\left[u - \text{(checkmark)} 0.749\dots\right]$$

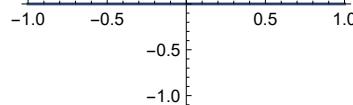
Knot [8, 16] →



Knot [8, 17] →

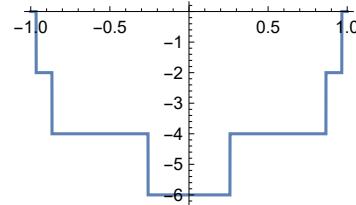


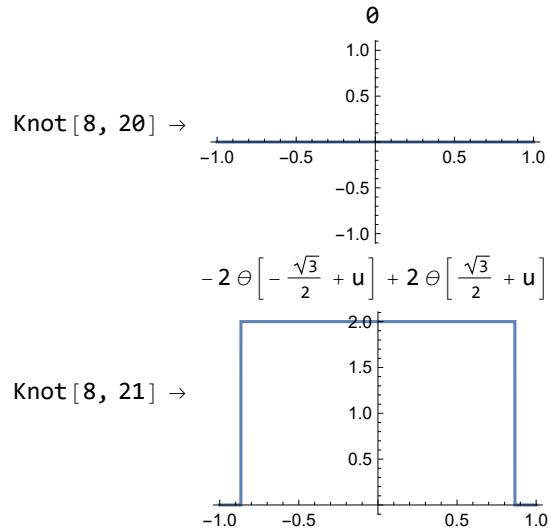
Knot [8, 18] →



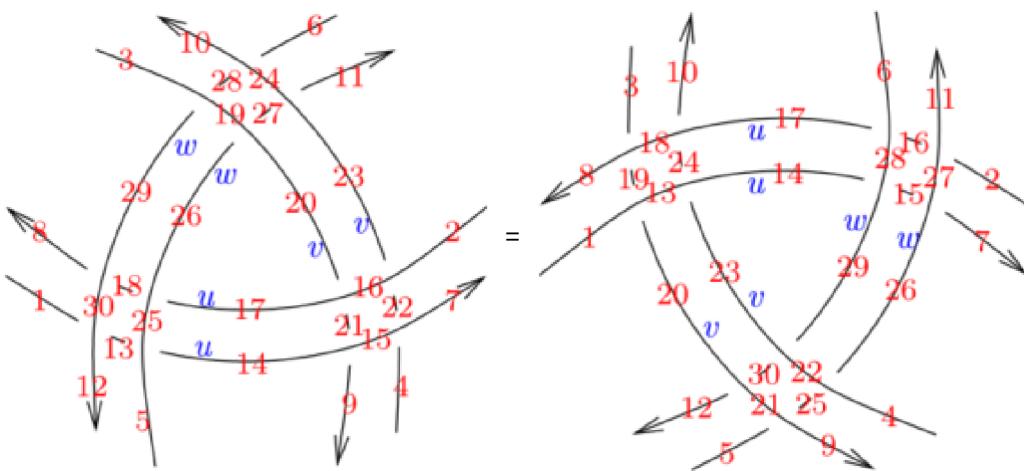
Knot [8, 19] →

$$2 \Theta\left[-\frac{\sqrt{3}}{2} + u\right] - 2 \Theta\left[\frac{\sqrt{3}}{2} + u\right] - 2 \Theta\left[u - \text{(checkmark)} -0.966\dots\right] - \\ 2 \Theta\left[u - \text{(checkmark)} -0.259\dots\right] + 2 \Theta\left[u - \text{(checkmark)} 0.259\dots\right] + 2 \Theta\left[u - \text{(checkmark)} 0.966\dots\right]$$





The Naik-Stanford Double Delta Move



In[=]:= $\text{pd} = \text{PD}[\text{X}_{6,10,28,24}, \bar{\text{X}}_{28,3,29,19}, \text{X}_{26,20,27,19}, \bar{\text{X}}_{27,23,11,24}, \text{X}_{1,12,13,30}, \bar{\text{X}}_{13,5,14,25}, \text{X}_{17,26,18,25}, \bar{\text{X}}_{18,29,8,30}, \text{X}_{4,7,22,15}, \bar{\text{X}}_{22,2,23,16}, \text{X}_{20,17,21,16}, \bar{\text{X}}_{21,14,9,15}] / . \{ \text{X}_{i_-, j_-, k_-, l_-} \rightarrow \text{X}_{-i, j, k, -l}, \bar{\text{X}}_{i_-, j_-, k_-, l_-} \rightarrow \bar{\text{X}}_{-j, k, l, -i} \}$

lhs = TL[pd]

Out[=]=

$$\text{PD}[\text{X}_{-6,10,28,-24}, \bar{\text{X}}_{-3,29,19,-28}, \text{X}_{-26,20,27,-19}, \bar{\text{X}}_{-23,11,24,-27}, \text{X}_{-1,12,13,-30}, \bar{\text{X}}_{-5,14,25,-13}, \text{X}_{-17,26,18,-25}, \bar{\text{X}}_{-29,8,30,-18}, \text{X}_{-4,7,22,-15}, \bar{\text{X}}_{-2,23,16,-22}, \text{X}_{-20,17,21,-16}, \bar{\text{X}}_{-14,9,15,-21}]$$

Out[=]=

$$\begin{array}{cccccccccc} & & & & 2\Theta\left(u - \frac{1}{2}\right) - 2\Theta\left(u + \frac{1}{2}\right) + 1 & & & & & \\ \eta_{-6} & -\frac{2\omega}{\omega^2+\omega+1} & \omega-1 & \frac{2}{\omega^2+\omega+1} & 0 & -\frac{2\omega^2}{\omega^2+\omega+1} & 0 & \frac{2\omega}{\omega^2+\omega+1} & 0 & -\frac{2}{\omega^2+\omega+1} \\ \bar{\eta}_{10} & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & 0 & 0 & 0 & 0 & 0 & 0 \\ \bar{\eta}_{-3} & \frac{2\omega^2}{\omega^2+\omega+1} & 1-\omega & -\frac{2\omega}{\omega^2+\omega+1} & \omega-1 & \frac{2}{\omega^2+\omega+1} & 0 & -\frac{2\omega^2}{\omega^2+\omega+1} & 0 & \frac{2\omega}{\omega^2+\omega+1} \\ \bar{\eta}_8 & 0 & 0 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & 0 & 0 & 0 & 0 \\ \bar{\eta}_{-1} & -\frac{2}{\omega^2+\omega+1} & 0 & \frac{2\omega^2}{\omega^2+\omega+1} & 1-\omega & -\frac{2\omega}{\omega^2+\omega+1} & \omega-1 & \frac{2}{\omega^2+\omega+1} & 0 & -\frac{2\omega^2}{\omega^2+\omega+1} \\ \bar{\eta}_{12} & 0 & 0 & 0 & 0 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} & 0 & 0 \\ \bar{\eta}_{-5} & \frac{2\omega}{\omega^2+\omega+1} & 0 & -\frac{2}{\omega^2+\omega+1} & 0 & \frac{2\omega^2}{\omega^2+\omega+1} & 1-\omega & -\frac{2\omega}{\omega^2+\omega+1} & \omega-1 & \frac{2}{\omega^2+\omega+1} \\ \bar{\eta}_9 & 0 & 0 & 0 & 0 & 0 & 0 & -\frac{\omega-1}{\omega} & 0 & \frac{\omega-1}{\omega} \\ \bar{\eta}_{-4} & -\frac{2\omega^2}{\omega^2+\omega+1} & 0 & \frac{2\omega}{\omega^2+\omega+1} & 0 & -\frac{2}{\omega^2+\omega+1} & 0 & \frac{2\omega^2}{\omega^2+\omega+1} & 1-\omega & -\frac{2\omega}{\omega^2+\omega+1} \\ \bar{\eta}_7 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -\frac{\omega-1}{\omega} \\ \bar{\eta}_{-2} & \frac{2}{\omega^2+\omega+1} & 0 & -\frac{2\omega^2}{\omega^2+\omega+1} & 0 & \frac{2\omega}{\omega^2+\omega+1} & 0 & -\frac{2}{\omega^2+\omega+1} & 0 & \frac{2\omega^2}{\omega^2+\omega+1} \\ \bar{\eta}_{11} & \frac{\omega-1}{\omega} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array}$$

```
In[5]:= pd = PD[X5,9,25,21, X̄25,4,26,22, X29,23,30,22, X̄30,20,12,21, X2,11,16,27, X̄16,6,17,28, X14,29,15,28, X̄15,26,7,27, X3,8,19,18, X̄19,1,20,13, X23,14,24,13, X̄24,17,10,18] /. {Xi_,j_,k_,l_ :> X-i,j,k,-l, X̄i_,j_,k_,l_ :> X̄-j,k,l,-i}
```

Out[•] =

$$\text{PD}\left[\bar{X}_{-5,9,25,-21}, \bar{X}_{-4,26,22,-25}, \bar{X}_{-29,23,30,-22}, \bar{X}_{-20,12,21,-30}, \bar{X}_{-2,11,16,-27}, \bar{X}_{-6,17,28,-16}, \bar{X}_{-14,29,15,-28}, \bar{X}_{-26,7,27,-15}, \bar{X}_{-3,8,19,-18}, \bar{X}_{-1,20,13,-19}, X_{-23,14,24,-13}, \bar{X}_{-17,10,18,-24}\right]$$

Out[•]=

In[•]:= **lhs** == **rhs**

Out[•]=

True

In[=]:= $\text{pd} = \text{PD}[\text{X}_{6,10,28,24}, \bar{\text{X}}_{28,3,29,19}, \text{X}_{26,20,27,19}, \bar{\text{X}}_{27,23,11,24}, \text{X}_{1,12,13,30}, \bar{\text{X}}_{13,5,14,25}, \text{X}_{17,26,18,25}, \bar{\text{X}}_{18,29,8,30}, \text{X}_{4,7,22,15}, \bar{\text{X}}_{22,2,23,16}, \text{X}_{20,17,21,16}, \bar{\text{X}}_{21,14,9,15}] / . \{ \text{X}_{i_-,j_-,k_-,l_-} \rightarrow \text{X}_{-i,j,k,-l}, \bar{\text{X}}_{i_-,j_-,k_-,l_-} \rightarrow \bar{\text{X}}_{-j,k,l,-i} \}$
lhs = Kas [pd]

Out[=]=

$$\text{PD}[\text{X}_{-6,10,28,-24}, \bar{\text{X}}_{-3,29,19,-28}, \text{X}_{-26,20,27,-19}, \bar{\text{X}}_{-23,11,24,-27}, \text{X}_{-1,12,13,-30}, \bar{\text{X}}_{-5,14,25,-13}, \text{X}_{-17,26,18,-25}, \bar{\text{X}}_{-29,8,30,-18}, \text{X}_{-4,7,22,-15}, \bar{\text{X}}_{-2,23,16,-22}, \text{X}_{-20,17,21,-16}, \bar{\text{X}}_{-14,9,15,-21}]$$

Out[=]=

-1									
0	0	0	1	0	-1	0	0	0	:
0	1	0	0	0	-1	0	1	0	l
(η_{-6})	η_{10}	η_{-3}	η_8	η_{-1}	η_{12}	η_{-5}	η_9	η_{-4}	r_i
$\bar{\eta}_{-6}$	$\frac{1}{2}u$	$\frac{1}{2}u$	0	$-\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	0	$-\frac{1}{2}u$	l
$\bar{\eta}_{10}$	u	2	u	$4u^2 - 3$	0	$-2(2u^2 - 1)$	$-u$	$-u$	l
$\bar{\eta}_{-3}$	$\frac{1}{2}u$	$\frac{1}{2}u$	u	$\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	0	$-\frac{1}{2}u$	l
$\bar{\eta}_8$	0	$4u^2 - 3$	u	2	u	-1	0	0	u
$\bar{\eta}_{-1}$	$-\frac{1}{2}u$	0	$\frac{1}{2}u$	u	$\frac{1}{2}u$	0	$\frac{1}{2}u$	$-\frac{1}{2}u$	l
$\bar{\eta}_{12}$	$-u$	$-2(2u^2 - 1)$	$-u$	-1	0	$2u^2$	0	u	l
$\bar{\eta}_{-5}$	$-\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	0	$\frac{1}{2}u$	u	$\frac{1}{2}u$	0	$\frac{1}{2}u$
$\bar{\eta}_9$	0	0	0	0	0	0	0	0	0
$\bar{\eta}_{-4}$	$-\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	u	$\frac{1}{2}u$	0	$\frac{1}{2}u$
$\bar{\eta}_7$	0	0	0	0	0	0	0	0	0
$\bar{\eta}_{-2}$	$\frac{1}{2}u$	0	$-\frac{1}{2}u$	$-u$	$-\frac{1}{2}u$	0	$-\frac{1}{2}u$	0	$\frac{1}{2}u$
$\bar{\eta}_{11}$	0	-1	$-u$	$-2(2u^2 - 1)$	$-u$	$2u^2 - 1$	0	0	u

In[=]:= **pd** = PD[X_{5,9,25,21}, X̄_{25,4,26,22}, X_{29,23,30,22}, X̄_{30,20,12,21}, X_{2,11,16,27}, X̄_{16,6,17,28}, X_{14,29,15,28}, X̄_{15,26,7,27}, X_{3,8,19,18}, X̄_{19,1,20,13}, X_{23,14,24,13}, X̄_{24,17,10,18}] /. {X_{i_,j_,k_,l_} :> X_{-i,j,k,-l}, X̄_{i_,j_,k_,l_} :> X̄_{-j,k,l,-i}}

rhs = Kas[pd]

Out[=]=

$$\text{PD}[X_{-5,9,25,-21}, \bar{X}_{-4,26,22,-25}, X_{-29,23,30,-22}, \bar{X}_{-20,12,21,-30}, X_{-2,11,16,-27}, \bar{X}_{-6,17,28,-16}, X_{-14,29,15,-28}, \bar{X}_{-26,7,27,-15}, X_{-3,8,19,-18}, \bar{X}_{-1,20,13,-19}, X_{-23,14,24,-13}, \bar{X}_{-17,10,18,-24}]$$

Out[=]=

$$\begin{array}{ccccccccc} & & & & & -1 & & & \\ 0 & 0 & 0 & 1 & 0 & -1 & 0 & 0 & \vdots \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ (\eta_{-6} & \eta_{10} & \eta_{-3} & \eta_8 & \eta_{-1} & \eta_{12} & \eta_{-5} & \eta_9 & \eta_{-4} \\ \bar{\eta}_{-6} & \frac{1}{2} & u & \frac{1}{2} & 0 & -\frac{1}{2} & -u & \frac{1}{2} & 0 & -\frac{1}{2} \\ \bar{\eta}_{10} & u & 2 & u & 4u^2 - 3 & 0 & -2(2u^2 - 1) & -u & 0 & -u \\ \bar{\eta}_{-3} & \frac{1}{2} & u & \frac{1}{2} & u & \frac{1}{2} & -u & \frac{1}{2} & 0 & -\frac{1}{2} \\ \bar{\eta}_8 & 0 & 4u^2 - 3 & u & 2 & u & -1 & 0 & 0 & -u \\ \bar{\eta}_{-1} & -\frac{1}{2} & 0 & \frac{1}{2} & u & \frac{1}{2} & 0 & \frac{1}{2} & 0 & -\frac{1}{2} \\ \bar{\eta}_{12} & -u & -2(2u^2 - 1) & -u & -1 & 0 & 2u^2 & u & 0 & u \\ \bar{\eta}_{-5} & -\frac{1}{2} & -u & -\frac{1}{2} & 0 & \frac{1}{2} & u & \frac{1}{2} & 0 & \frac{1}{2} \\ \bar{\eta}_9 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \bar{\eta}_{-4} & -\frac{1}{2} & -u & -\frac{1}{2} & -u & -\frac{1}{2} & u & \frac{1}{2} & 0 & \frac{1}{2} \\ \bar{\eta}_7 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \bar{\eta}_{-2} & \frac{1}{2} & 0 & -\frac{1}{2} & -u & -\frac{1}{2} & 0 & -\frac{1}{2} & 0 & \frac{1}{2} \\ \bar{\eta}_{11} & 0 & -1 & -u & -2(2u^2 - 1) & -u & 2u^2 - 1 & 0 & 0 & u \end{array}$$

In[=]:= **lhs** == **rhs**

Out[=]=

True