

Pensieve header: Improving the Z Program.

Startup

```
In[1]:= Date[]
SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\FullDoPeGDO"];
Once[<< KnotTheory`];
Once[Get@"../Profile/Profile.m"];
BeginProfile[];
$K = 1;
<< Engine.m
<< Objects.m
<< KT.m
HL[ε_] := Style[ε, Background \[Rule] If[TrueQ@ε, Green, Red]];
LogCF[ε_] :=
  ε //.{c_ Log[a_] \[Rule] Log[a^c], Log[a_] + Log[b_] \[Rule] Log[a b], Log[a_] \[Rule] Log[CF[a]]}
```

```
Out[1]= {2021, 7, 13, 21, 27, 46.7615360}
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

This is Profile.m of <http://www.drorbn.net/AcademicPensieve/Projects/Profile/>.

This version: April 2020. Original version: July 1994.

```
In[2]:= tab5Z = Timing[Table[K \[Rule] LogCF@Z[K], {K, AllKnots[{3, 5}]}]]
```

KnotTheory: Loading precomputed data in PD4Knots`.

$$\begin{aligned} \text{Out[2]= } & \left\{ 35.4375, \left\{ \text{Knot}[3, 1] \rightarrow \mathbb{E}_{\{\}} \rightarrow_{\{0\}} \left[-2t \frac{\ln(-1+T)}{1-T+T^2} + \log\left(\frac{T^3}{1-T+T^2}\right), \right. \right. \right. \\ & \left. \left. \left. \frac{2a(-1+T)(1+T)\ln(-1+T)}{1-T+T^2} + \frac{(-1+T)(2-T+T^2)\ln(-1+T)}{(1-T+T^2)^2} - \frac{2(1+T)x\ln(-1+T)}{1-T+T^2} \right], \text{Knot}[4, 1] \rightarrow \mathbb{E}_{\{\}} \rightarrow_{\{0\}} \right. \right. \\ & \left. \left. \left. -t \ln(-1+T) + \log\left(-\frac{T^2}{1-3T+T^2}\right), \frac{(-1+T)(1+T)\ln(-1+T)}{1-3T+T^2} + \frac{2a(-1+T)(1+T)\ln(-1+T)}{1-3T+T^2} - \frac{2(1+T)x\ln(-1+T)}{1-3T+T^2} \right], \right. \right. \\ & \left. \left. \left. \text{Knot}[5, 1] \rightarrow \mathbb{E}_{\{\}} \rightarrow_{\{0\}} \left[-3t \ln(-1+T) + \log\left(\frac{T^5}{1-T+T^2-T^3+T^4}\right), \frac{2a(-1+T)(1+T)(2-T+2T^2)\ln(-1+T)}{1-T+T^2-T^3+T^4} + \right. \right. \right. \right. \\ & \left. \left. \left. \left. \frac{(-1+T)(4-3T+5T^2-3T^3+3T^4-T^5+T^6)\ln(-1+T)}{(1-T+T^2-T^3+T^4)^2} - \frac{2(1+T)(2-T+2T^2)x\ln(-1+T)}{1-T+T^2-T^3+T^4} \right], \right. \right. \\ & \left. \left. \left. \left. \text{Knot}[5, 2] \rightarrow \mathbb{E}_{\{\}} \rightarrow_{\{0\}} \left[-3t \ln(-1+T) + \log\left(\frac{T^4}{2-3T+2T^2}\right), \right. \right. \right. \right. \\ & \left. \left. \left. \left. \frac{4a(-1+T)(1+T)\ln(-1+T)}{2-3T+2T^2} - \frac{(-1+T)(-9+11T-7T^2+T^3)\ln(-1+T)}{(2-3T+2T^2)^2} - \frac{4(1+T)x\ln(-1+T)}{2-3T+2T^2} \right] \right] \right\} \right\} \end{aligned}$$

```

Z[K_] := Z[RVK@K];
Z[rvk_RVK] := (*Z[rvk] =*)
Monitor[ PP["Z"]@Module[{todo, n, rrots, g, done, st, cx, g1, i, j, k, k1, k2, k3},
{todo, rrots} = List @@ rvk;
AppendTo[rots, 0];
n = Length[todo];
g = dη₀;
done = {0};
st = Range[0, 2 n + 1];
While[{} != ($M = todo),
{cx} = MaximalBy[todo, Length[done ∩ {#[[1]], #[[2]], #[[1]] - 1, #[[2]] - 1}] &, 1];
{i, j} = List @@ cx;
g1 = Switch[Head[cx],
Xp, (kRi,j kKinkk) // kmj,k→j,
Xm, (kRi,j kKinkk) // kmj,k→j
];
g1 = (rot[k, rrots[[i]]] g1) // kmk,i→i; rrots[[i]] = 0;
g1 = (g1 rot[k, rrots[[i + 1]]]) // kmi,k→i; rrots[[i + 1]] = 0;
g1 = (rot[k, rrots[[j]]] g1) // kmk,j→j; rrots[[j]] = 0;
g1 = (g1 rot[k, rrots[[j + 1]]]) // kmj,k→j; rrots[[j + 1]] = 0;
g *= g1;
If[MemberQ[done, i], g = g // kmi,i+1→i; st = st /. st[[i + 2]] → st[[i + 1]]];
If[MemberQ[done, i - 1], g = g // kmst[[i]],i→st[[i]]; st = st /. st[[i + 1]] → st[[i]]];
If[MemberQ[done, j], g = g // kmj,j+1→j; st = st /. st[[j + 2]] → st[[j + 1]]];
If[MemberQ[done, j - 1], g = g // kmst[[j]],j→st[[j]]; st = st /. st[[j + 1]] → st[[j]]];
done = done ∪ {i - 1, i, j - 1, j};
todo = DeleteCases[todo, cx]
];
CF /@ (g /. {x₀ → x, y₀ → y, a₀ → a})
], $M]

```

```

Z1[K_] := Z1[RVK@K];
Z1[rvk_RVK] := Monitor[ PP["Z"]@Module[{todo, rrots, g, done, st, cx, g1, i, j, k},
  {todo, rrots} = List @@ rvk;
  g = dn0;
  done = {0};
  st = Range[0, 2 Length[todo]];
  While[{} != ($M = todo),
    cx =
      RandomChoice@MaximalBy[todo, Length[done] ∩ {#[[1]], #[[2]], #[[1]] - 1, #[[2]] - 1}] &];
    {i, j} = List @@ cx;
    g1 = (cx /. {_xP :> kR[i,j] kKink0, _xm :> kR[i,j] kKink0}) // kmj,0→j;
    Do[g1 = (rot[0, rrots[[k]]] g1) // km0,k→k, {k, {i, j}}];
    g *= g1;
    Do[
      If[MemberQ[done, k], g = g // kmst[[k+1]], k+1→st[[k+1]]; st = st /. st[[k+2]] → st[[k+1]],
        {k, {i, i-1, j, j-1}}];
      done = done ∪ {i-1, i, j-1, j};
      todo = DeleteCases[todo, cx]
    ];
    CF /@ (g /. {x0 → x, y0 → y, a0 → a})
  ], $M]

```

In[=]:= tab5Z1 = Timing[Table[K → LogCF@Z1[K], {K, AllKnots[{3, 5}]}]]

$$\begin{aligned}
 \text{Out[=]} = & \left\{ 23.0469, \left\{ \text{Knot}[3, 1] \rightarrow \mathbb{E}_{\{\} \rightarrow \{\theta\}} \left[-2t \frac{\hbar}{T} + \log \left[\frac{T^3}{1 - T + T^2} \right], \right. \right. \right. \\
 & \frac{2a(-1 + T) \times (1 + T) \frac{\hbar}{T}}{1 - T + T^2} + \frac{(-1 + T) \times (2 - T + T^2) \frac{\hbar}{T}}{(1 - T + T^2)^2} - \frac{2 \times (1 + T) \times y \frac{\hbar^2}{T}}{1 - T + T^2}, \text{Knot}[4, 1] \rightarrow \mathbb{E}_{\{\} \rightarrow \{\theta\}} \left[\right. \\
 & \left. \left. \left. -t \frac{\hbar}{T} + \log \left[-\frac{T^2}{1 - 3T + T^2} \right], \frac{(-1 + T) \times (1 + T) \frac{\hbar}{T}}{1 - 3T + T^2} + \frac{2a(-1 + T) \times (1 + T) \frac{\hbar}{T}}{1 - 3T + T^2} - \frac{2 \times (1 + T) \times y \frac{\hbar^2}{T}}{1 - 3T + T^2} \right], \right. \right. \\
 & \text{Knot}[5, 1] \rightarrow \mathbb{E}_{\{\} \rightarrow \{\theta\}} \left[-3t \frac{\hbar}{T} + \log \left[\frac{T^5}{1 - T + T^2 - T^3 + T^4} \right], \frac{2a(-1 + T) \times (1 + T) \times (2 - T + 2T^2) \frac{\hbar}{T}}{1 - T + T^2 - T^3 + T^4} + \right. \\
 & \left. \left. \left. \frac{(-1 + T) \times (4 - 3T + 5T^2 - 3T^3 + 3T^4 - T^5 + T^6) \frac{\hbar}{T}}{(1 - T + T^2 - T^3 + T^4)^2} - \frac{2 \times (1 + T) \times (2 - T + 2T^2) \times y \frac{\hbar^2}{T}}{1 - T + T^2 - T^3 + T^4} \right], \right. \right. \\
 & \text{Knot}[5, 2] \rightarrow \mathbb{E}_{\{\} \rightarrow \{\theta\}} \left[-3t \frac{\hbar}{T} + \log \left[\frac{T^4}{2 - 3T + 2T^2} \right], \right. \\
 & \left. \left. \left. \frac{4a(-1 + T) \times (1 + T) \frac{\hbar}{T}}{2 - 3T + 2T^2} - \frac{(-1 + T) \times (-9 + 11T - 7T^2 + T^3) \frac{\hbar}{T}}{(2 - 3T + 2T^2)^2} - \frac{4 \times (1 + T) \times y \frac{\hbar^2}{T}}{2 - 3T + 2T^2} \right] \right\} \right\}
 \end{aligned}$$

In[=]:= HL[tab5Z1[[2]] == tab5Z1[[2]]]

Out[=]= True

```
In[=]:= tab7Z = Timing[Table[K \[Rule] LogCF@Z[K], {K, AllKnots[{3, 7}]}]];
In[=]:= tab7Z1 = Timing[Table[K \[Rule] LogCF@Z1[K], {K, AllKnots[{3, 7}]}]];
HL[tab7Z[[2]] == tab7Z1[[2]]]
Out[=]= True

In[=]:= Timing[tab10Z = Table[K \[Rule] LogCF@Z[K], {K, AllKnots[{3, 10}]}];]
Out[=]= {7519.83, Null}

In[=]:= Timing[tab10Z1 = Table[K \[Rule] LogCF@Z1[K], {K, AllKnots[{3, 10}]}];
HL[tab10Z[[2]] == tab10Z1[[2]]]
Out[=]= {6947.72, Null}

Out[=]= True
```