

$\text{In}[1]:= \{\eta, \xi, y, x\}^*$

$\text{Out}[1]= \{y, x, \eta, \xi\}$

$\text{In}[2]:= \mathbf{m}_{i,j \rightarrow k}$

$\mathbf{lhs} = \mathbf{m}_{1,2 \rightarrow 1} // \mathbf{m}_{1,3 \rightarrow 1}$

$\mathbf{rhs} = \mathbf{m}_{2,3 \rightarrow 2} // \mathbf{m}_{1,2 \rightarrow 1}$

$\mathbf{lhs} \equiv \mathbf{rhs}$

$\text{Out}[2]= \mathbb{E}_{\{i,j\} \rightarrow \{k\}} [1, y_k (\eta_i + \eta_j) - \eta_j \xi_i + x_k (\xi_i + \xi_j), \in \text{Series}[0, 0]]$

$\text{Out}[3]= \mathbb{E}_{\{1,2,3\} \rightarrow \{1\}} [1, y_1 \eta_1 + y_1 \eta_2 + y_1 \eta_3 + x_1 \xi_1 - \eta_2 \xi_1 - \eta_3 \xi_1 + x_1 \xi_2 - \eta_3 \xi_2 + x_1 \xi_3, \in \text{Series}[0, 0]]$

$\text{Out}[4]= \mathbb{E}_{\{1,2,3\} \rightarrow \{1\}} [1, y_1 \eta_1 + y_1 \eta_2 + y_1 \eta_3 + x_1 \xi_1 - \eta_2 \xi_1 - \eta_3 \xi_1 + x_1 \xi_2 - \eta_3 \xi_2 + x_1 \xi_3, \in \text{Series}[0, 0]]$

$\text{Out}[5]= \text{True}$

$\text{In}[6]:= \mathbf{R}_{1,2} \bar{\mathbf{R}}_{3,4}$

$\text{Out}[6]= \mathbb{E}_{\{\} \rightarrow \{1,2,3,4\}} [1, (-1 + T) x_2 (y_1 - y_2) + \left(-1 + \frac{1}{T}\right) x_4 (y_3 - y_4), \in \text{Series}[0, -\frac{1}{2} (1 - T) x_2^2 y_1^2 + x_1 x_2 y_1 y_2 + \frac{1}{2} (1 - 3 T) x_2^2 y_1 y_2 - \frac{(-1 + T) x_3 x_4 y_3^2}{T^2} - \frac{(1 - T) x_4^2 y_3^2}{2 T^3} - \frac{x_3 x_4 y_3 y_4}{T^2} - \frac{(-1 - T) x_4^2 y_3 y_4}{2 T^3}]]$

$\text{In}[7]:= (\mathbf{R}_{1,2} \bar{\mathbf{R}}_{3,4}) // \mathbf{m}_{1,3 \rightarrow 1}$

$\text{Out}[7]= \mathbb{E}_{\{\} \rightarrow \{1,2,4\}} [1, (-1 + T) x_2 y_1 + \frac{(1 - T) x_4 y_1}{T} + (1 - T) x_2 y_2 + \frac{(-1 + T) x_4 y_4}{T}, \in \text{Series}[0, \frac{1}{2} (-1 + T) x_2^2 y_1^2 + \frac{(1 - T) x_1 x_4 y_1^2}{T^2} + \frac{(-1 + T) x_4^2 y_1^2}{2 T^3} + x_1 x_2 y_1 y_2 + \frac{1}{2} (1 - 3 T) x_2^2 y_1 y_2 + \frac{(-1 + T) x_2 x_4 y_1 y_2}{T} - \frac{x_1 x_4 y_1 y_4}{T^2} + \frac{(1 + T) x_4^2 y_1 y_4}{2 T^3}]]$

$\text{In}[8]:= \{Z[0], Z[1], Z[2]\} // \text{Column}$

$\in \text{Series}[0,$

$\frac{1}{2} (1 - 3 T) x_2^2 y_2 (y_1 + y_{\$[1]}) + x_2 \left(x_1 - \frac{(1 - T) x_4}{T} + x_{\$[1]}\right) y_2 (y_1 + y_{\$[1]}) - \frac{1}{2} (1 - T) x_2^2 (y_1 + y_{\$[1]})^2 -$

$\text{Out}[8]= \frac{(-1 - T) x_2^2 y_4 (y_1 + y_{\$[3]})}{2 T^3} - \frac{x_4 (x_1 + x_{\$[3]}) y_4 (y_1 + y_{\$[3]})}{T^2} - \frac{(1 - T) x_2^2 (y_1 + y_{\$[3]})^2}{2 T^3} - \frac{(-1 + T) x_4 (x_1 + x_{\$[3]}) (y_1 + y_{\$[3]})^2}{T^2}]$

$\in \text{Series}[0, 0]$

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$\text{In}[9]:= \mathbf{m}_{2,4 \rightarrow 2}$

$\text{Out}[9]= \mathbb{E}_{\{2,4\} \rightarrow \{2\}} [1, y_2 (\eta_2 + \eta_4) - \eta_4 \xi_2 + x_2 (\xi_2 + \xi_4), \in \text{Series}[0, 0]]$

$\text{In}[10]:= \mathbf{R}_{1,2} \bar{\mathbf{R}}_{3,4} // \mathbf{m}_{1,3 \rightarrow 1} // \mathbf{m}_{2,4 \rightarrow 2} // \text{CF}$

$\text{Out}[10]= \mathbb{E}_{\{\} \rightarrow \{1,2\}} [1, 0, \in \text{Series}[0, 0]]$

In[1]:= ? Z

Symbol

Global`Z

Definitions

$$Z[0] = \text{eSeries}\left[0, -\frac{1}{2} (1-T) \left(x_2 + \frac{(1-T)x_2}{T} + x_{2(2)}\right)^2 y_1^2 - \frac{(-1+T)x_1(x_2+x_{4(4)})y_1^2}{T^2} - \frac{(1-T)(x_2+x_{4(4)})^2 y_1^2}{2T^3} + \frac{1}{2} (1-3T)$$

$$Z[1] = \text{eSeries}[0, 0]$$

Out[1]=

$$Z[2] = \text{eSeries}[0, 0]$$

$$Z[\text{rvk_RVK}] := \text{Module}\left[\{\text{todo}, n, \text{rots}, \zeta, \text{done}, \text{st}, \text{cx}, \zeta 1, i, j, k, k1, k2, k3\}, \{\text{todo}, \text{rots}\} = L\right]$$

$$Z[K_] := Z[\text{RVK}[K]]$$

Full Name Global`Z

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In[2]:= CF@Z[Knot[3, 1]]

$$\text{Out[2]}= \mathbb{E}_{\{\}} \rightarrow \{\theta\} \left[\frac{T}{1-T+T^2}, 0, \text{eSeries}\left[0, \frac{-2+3T-2T^2+T^3}{T-2T^2+3T^3-2T^4+T^5}\right] \right]$$

$$\text{In[3]}= \text{Factor}\left[\frac{-2+3T-2T^2+T^3}{T-2T^2+3T^3-2T^4+T^5} \right]$$

$$\text{Out[3]}= \frac{(-1+T)(2-T+T^2)}{T(1-T+T^2)^2}$$

$$\text{In[4]}= \frac{T-2T^2+2T^3}{\sqrt{(1-3T+5T^2-4T^3+2T^4)^2}} // \text{PowerExpand}$$

$$\text{In[5]}= \frac{T-2T^2+2T^3}{1-3T+5T^2-4T^3+2T^4} // \text{Factor}$$

$$\text{Out[5]}= \frac{T}{1-T+T^2}$$