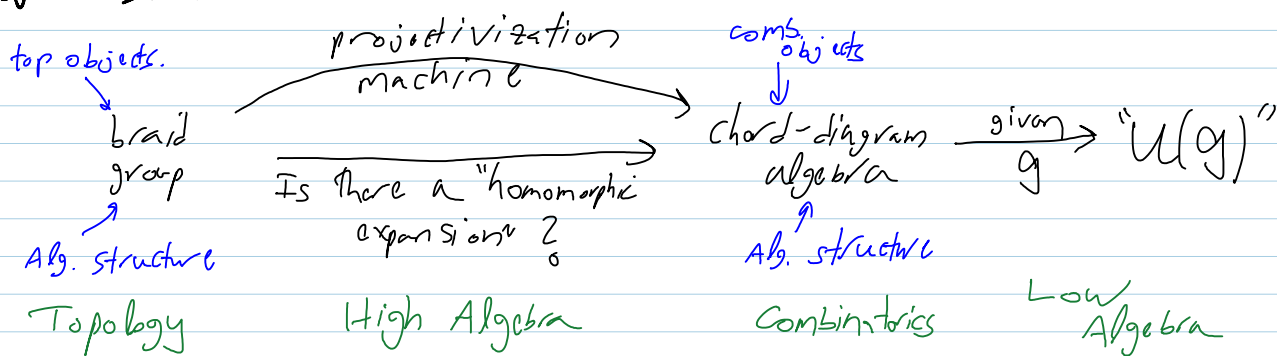


Subject Introduction.



	u-Knots	v-Knots	w-Knots
Topology	Ordinary (usual) knotted objects in 3D — braids, knots, links, tangles, knotted graphs, etc.	Virtual knotted objects — "algebraic" knotted objects, or "not specifically embedded" knotted objects; knots drawn on a surface, modulo stabilization.	Ribbon knotted objects in 4D; "flying rings". Like v, but also with "overcrossings commute".
Combinatorics	Chord diagrams and Jacobi diagrams, modulo $4T$, STU , IHX , etc.	Arrow diagrams and v-Jacobi diagrams, modulo $6T$ and various "directed" $STUs$ and $IHXs$, etc.	Like v, but also with "tails commute". Only "two in one out" internal vertices.
Low Algebra	Finite dimensional metrized Lie algebras, representations, and associated spaces.	Finite dimensional Lie bi-algebras, representations, and associated spaces.	Finite dimensional co-commutative Lie bi-algebras (i.e., $\mathfrak{g} \times \mathfrak{g}^*$), representations, and associated spaces.
High Algebra	The Drinfel'd theory of associators.	Likely, quantum groups and the Etingof-Kazhdan theory of quantization of Lie bi-algebras.	The Kashiwara-Vergne-Alekseev-Torossian theory of convolutions on Lie groups and Lie algebras.

- Why bother? 1. Knot theory is an excuse.
 2. Better understanding of the algebra.
 3. "Algebraic knot theory".

Course Introduction. A class, a seminar, an experiment.

- * Not a standard UoFT class: * No grades/credits
- * Our own time frame.

I need your help!

Dissonances.

1. Private / scientific record.

2. Should be complete / Motivation to complete

(this also has a technical side: how do I refer to numbered items?)

3. Needs time & love / high season administratively.

Location. Today only: exile next time: BA 4010
Eventually: My office I hope for lunches!

Section 2.1 - v-braids.

2.1.1 The "planar" way.

$$vB_n = \left\langle \begin{array}{l} \sigma_i = \begin{array}{c} \diagup \diagdown \\ \diagdown \diagup \end{array} \Big| \begin{array}{l} s_i^2 = 1, s_i s_{i+1} s_i = s_{i+1} s_i s_i, |i-j| > 1 \Rightarrow s_i s_j = s_j s_i \\ \sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1}, |i-j| > 1 \Rightarrow \sigma_i \sigma_j = \sigma_j \sigma_i \\ s_i \sigma_{i+1}^{\pm 1} s_i = s_{i+1} \sigma_i^{\pm 1} s_{i+1}, |i-j| > 1 \Rightarrow \sigma_i s_j = s_j \sigma_i \end{array} \end{array} \right\} \begin{array}{l} \text{"symmetric group"} \\ \text{"braid part"} \\ \text{"mixed relations."} \end{array}$$

There is an obvious "skeleton map":

$$\sigma: vB_n \rightarrow S_n$$

Def $PvB_n := \ker(\sigma)$

Claim we have a split sequence

$$1 \rightarrow PvB_n \rightarrow vB_n \xrightarrow{\sigma} S_n \rightarrow 0$$

& hence $vB_n = PvB_n \rtimes S_n$

So studying vB_n is +/- the same as studying PvB_n .

2.1.2 The "abstract" way.

2.1.2. The "Abstract" Way. The relations (2) and (6) that govern the behaviour of virtual crossings precisely say that virtual crossings really are "virtual" — if a piece of strand is routed within a braid so that there are only virtual crossings around it, it can be rerouted in any other "virtual only" way, provided the ends remain fixed (this is Kauffman's "detour move" [Ka2, KL]). Since a v-braid B is independent of the routing of virtual pieces of strand, we may as well never supply this routing information.

Thus for example, a perfectly fair verbal description of the (pure!) v-braid on the right is "strand 1 goes over strand 3 by a positive crossing then likewise positively over strand 2 then negatively over 3 then 2 goes positively over 1". We don't need to specify how strand 1 got to be near strand 3 so it can go over it — it got there by means of virtual crossings, and it doesn't matter how. Hence we arrive at the following "abstract" presentation of PvB_n and vB_n :



done
link

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Proposition 2.3. (E.g. [Ba])

- (1) The group PvB_n of pure v -braids is isomorphic to the group generated by symbols σ_{ij} for $1 \leq i \neq j \leq n$ (meaning “strand i crosses over strand j at a positive crossing”⁹), subject to the third Reidemeister move and to locality in space (compare with (3) and (4)):

$$\begin{aligned} \sigma_{ij}\sigma_{ik}\sigma_{jk} &= \sigma_{jk}\sigma_{ik}\sigma_{ij} && \text{whenever } |\{i, j, k\}| = 3, \\ \sigma_{ij}\sigma_{kl} &= \sigma_{kl}\sigma_{ij} && \text{whenever } |\{i, j, k, l\}| = 4. \end{aligned}$$

⁹The inverse, σ_{ij}^{-1} , is “strand i crosses over strand j at a negative crossing”