

$$\underline{f \circ T_\theta = f}$$

$$f(T_\theta(\alpha)) = f(\alpha) \Rightarrow$$

$$\underline{f(e^{i\theta}\alpha) = f(\alpha)} \quad \forall \theta \in [0, 2\pi]. \quad \text{constant!}$$



$$D(f \circ T_\theta)(\alpha) = Df(T_\theta(\alpha)) \circ \underline{DT_\theta(\alpha)} = Df(\alpha)$$

differential of
a linear transform.
equals the transform
itself!

$$D(f \circ T_\theta)(\alpha) \begin{pmatrix} y \\ x \end{pmatrix} = \dots$$

$$f(x, y) = |xy|$$

If $x_0 \neq 0$
 $y_0 \neq 0 \Rightarrow f$ is differentiable at $(x_0, y_0) =$

$$\frac{\partial f}{\partial x} = \pm |y_0|, \quad \frac{\partial f}{\partial y} = \pm |x_0|$$

$$\frac{\partial f}{\partial x}(x_0, y_0) = \text{sgn}(x_0)|y_0| = \lim_{h \rightarrow 0} \frac{(x_0+h)|y_0| - x_0|y_0|}{h}$$

$$\frac{\partial f}{\partial y}(x_0, y_0) = \text{sgn}(y_0)|x_0|$$

($y_0 \neq 0$)

$$f = |xy|$$

$$\frac{\partial f}{\partial x}(x_0, y_0) = \lim_{h \rightarrow 0} \frac{|x_0+h||y_0| - |x_0||y_0|}{h} = |y_0| \cdot \lim_{h \rightarrow 0} \frac{|x_0+h| - |x_0|}{h} = \text{sgn}(x_0) |y_0|$$

$$\begin{matrix} 1 & \text{if } x_0 > 0 \\ -1 & \text{if } x_0 < 0. \end{matrix}$$

$$\xrightarrow{-1} \bullet \left(\frac{1}{0, 1} \right)$$

a discontinuity!

Let us try doing the same for $x_0 = 0$.

$$\lim_{h \rightarrow 0} \frac{|h||y_0| - |0||y_0|}{h} = \lim_{h \rightarrow 0} \frac{|h||y_0|}{h} = \lim_{h \rightarrow 0} \text{sgn}(h) \cdot |y_0|$$

this limit does not make sense for $x_0 = 0$
 $y_0 \neq 0$.

However, we claim that

$$\lim_{(x,y) \rightarrow 0} \frac{|xy|}{\sqrt{x^2+y^2}} = 0$$

$$\frac{|xy| = o(\sqrt{x^2+y^2})}{\sqrt{x^2+y^2}} \quad (\text{we guess that } Df(0) = 0)$$

$$\Leftrightarrow \lim_{(x,y) \rightarrow 0} \frac{x^2 y^2}{x^2 + y^2} = 0 = \lim_{(x,y) \rightarrow 0} |xy| \cdot \frac{|xy|}{x^2 + y^2}$$

$$|xy| \leq x^2 + y^2$$

bounded times $\searrow 0 = \searrow 0$

TT1R5:

$$f = o(h)$$



$$\underline{f(0) = 0.}$$



$$f(h) - \underbrace{f(0)}_0 = \underbrace{Df(0)}_0(h) + o(h)$$

$$\lim_{h \rightarrow 0} \frac{f(h)}{h} = 0$$

TT1R6:

$$(x, y) \mapsto \begin{pmatrix} e^x + e^y \\ e^x + e^{-y} \end{pmatrix}$$

$$\det \begin{pmatrix} \underline{e^{x_0}} & e^{y_0} \\ e^{x_0} & \underline{-e^{-y_0}} \end{pmatrix} = \underbrace{-e^{x_0 - y_0}}_0 \underbrace{-e^{x_0 + y_0}}_0$$

$$(e^{-x})' = -e^{-x}$$

$$\Downarrow: \begin{matrix} x_1 \rightsquigarrow \lambda x_1 \\ x_2 \rightsquigarrow \lambda x_2 \end{matrix}$$

\rightsquigarrow WLOG $A = Id. \dots$

Consider $\theta = \pi$.

$$f(T_\pi(x)) = f(-x)$$

$$Df(-x) = -Df(x)$$

$$f(x) = f(-x)$$

$$Df_x = -Df_{-x}$$

$$Df_{T_\theta a} \circ T_\theta = Df_a$$

$$\left(\frac{\partial f}{\partial x} \Big|_{T_\theta a}, \frac{\partial f}{\partial y} \Big|_{T_\theta a} \right) \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \left(\frac{\partial f}{\partial x} \Big|_a, \frac{\partial f}{\partial y} \Big|_a \right)$$

Argue in terms of directional derivatives!

Consider

$$g: \mathbb{R} \rightarrow \mathbb{R}^2, g(t) = f(T_\theta(t))$$

On the one hand, $g'_a(0) = 0 \quad \forall \theta \in \mathbb{R}$.

chain rule

$$\mathbb{R} \xrightarrow{T_\theta} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}$$

$$\left(\frac{\partial f}{\partial x} \Big|_{T_\theta a}, \frac{\partial f}{\partial y} \Big|_{T_\theta a} \right) \cdot$$

$$Df|_a = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = 0.$$

g_a is a constant f-n $\varphi: \mathbb{R} \rightarrow \mathbb{R}^2$

← apply the chain rule to this

$$\begin{pmatrix} -\sin \theta & -\cos \theta \\ \cos \theta & -\sin \theta \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Recall:

or homogeneous fn-n : $f(\lambda x) = \lambda^n f(x)$

$$\frac{d}{dx} f(\lambda x)$$

$$\underbrace{x \rightsquigarrow x^3}_{(x^3)' = 3x^2} \text{ is } 1-1 \text{ (for } x=0 \text{)}$$

If you have a fn-n $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ =>

$$Df = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

iff Df is well-def.

↑

Jacobian

↑
Jacobian matrix

arctan(x)



$$f: \mathbb{R}^n \rightarrow \mathbb{R}^p$$

$p \leq n$

$$f(a) = 0$$

$$\left(\begin{array}{ccc} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_p}{\partial x_1} & \dots & \frac{\partial f_p}{\partial x_n} \end{array} \right) \Bigg\}^p$$

n

r_k is full \Rightarrow
 $\Rightarrow p$ lin. indep. columns \Rightarrow
 det of the minor is non-zero \Rightarrow
 \Rightarrow IFT.

11: try z is a function of x, y

$$x \mapsto \begin{pmatrix} \cos x \\ \sin x \end{pmatrix}$$

$x, x + 2\pi$

$$1 + \frac{\partial z}{\partial x} = \cos(xy z) \cdot \frac{\partial}{\partial x} (xy z) =$$

$$= \cos(xy z) \left(yz + xy \frac{\partial z}{\partial x} \right)$$

express

$\exists y(x, y):$

$$x + y + y(x, y) = \sin(x, y(x, y))$$

$\frac{\partial}{\partial x}:$

$$1 + \frac{\partial y}{\partial x} = \cos$$

$\frac{\partial z}{\partial x}$ in terms of x, y, z and then plug in $x=y=z=0$