

Pensieve header: The $\frac{g}{1}$ Invariant.

The g_1 Invariant

Reminder

Make sure that you have Mathematica and that you play with these programs!

The main g_k lemma

In $g^\epsilon = \langle h, e, l, f \rangle / ([e, l] = -e, [f, l] = f, [e, f] = h - 2\epsilon l, [h, *] = 0)$ and at $\epsilon^{k+1} = 0$, we have

1. $\mathcal{O}(e^{Yl+\beta e} \mid l e) = \mathcal{O}(e^{Yl+e^Y \beta e} \mid e l)$,
2. $\mathcal{O}(e^{Yl+\beta f} \mid f l) = \mathcal{O}(e^{Yl+e^Y \beta f} \mid l f)$,
3. $\mathcal{O}(e^{\beta e+\alpha f+\delta e f} \mid f e) = \mathcal{O}(v e^{v(-\alpha \beta h+\beta e+\alpha f+\delta e f)} \Lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta) \mid e f)$, with $v = (1 + h \delta)^{-1}$ and where for any fixed k , $\Lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta)$ is a fixed polynomial of degree at most $4k$ in $e, \sqrt{l}, f, \alpha, \beta$, with scalar coefficients.

Comment. Even better, $\log(\Lambda_k)$ is of degree at most $2k + 2$ in said variables.

The Main g_k Theorem

Raw Version. The g_k invariant of any S-component tangle T can be written in the form $Z(T) = \mathcal{O}(\omega e^{L+Q+P} \mid \prod_{i \in S} e_i l_i f_i)$, where ω is a scalar (meaning, a rational function in the variables h_i and their exponentials $t_i = e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients a_{ij} , where $Q = \sum b_{ij} e_i f_j$ is a balanced quadratic in the variables e_i and f_j with scalar coefficients b_{ij} , and where P is a polynomial in $\{\epsilon, e_i, l_i, f_i\}$ (with scalar coefficients) whose ϵ^d -term is of degree at most $2d + 2$ in $\{e_i, \sqrt{l_i}, f_i\}$. Furthermore, after setting $h_i = h$ and $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

Partial Proof. Indeed,

0. $R^\pm = ?$, $n^\pm = ?$.
1. $\mathcal{O}(\mathcal{P}(l, e) e^{Yl+\beta e} \mid l e) = \mathcal{O}(\mathcal{P}(\partial_Y, \partial_\beta) e^{Yl+e^Y \beta e} \mid e l)$,
2. $\mathcal{O}(\mathcal{P}(l, f) e^{Yl+\beta f} \mid f l) = \mathcal{O}(\mathcal{P}(\partial_Y, \partial_\beta) e^{Yl+e^Y \beta f} \mid l f)$,
3. $\mathcal{O}(\mathcal{P}(e, f) e^{\beta e+\alpha f+\delta e f} \mid f e) = \mathcal{O}(v \mathcal{P}(\partial_\beta, \partial_\alpha) e^{v(-\alpha \beta h+\beta e+\alpha f+\delta e f)} \Lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta) \mid e f)$, with $v = (1 + h \delta)^{-1}$, and $\Lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta)$ as above.

Implementation at $k = 1$

$E1n[\omega, L, Q, P]$ stands for $\omega e^{L+Q}(1+\epsilon P)$.

```
DPx→Dα, y→Dβ[P-][f-] := Total[CoefficientRules[P, {x, y}] /. ({m-, n-} → c-) ⇒ c D[f, {α, m}, {β, n}]]
```

```
Λk[h-, e-, l-, f-, α-, β-, δ-] := Λk[h, e, l, f, α, β, δ] = Module[{λ},
  λ = Normal@Series[e $\frac{f+\alpha\beta}{1-\alpha\beta e}$  (1 - α β ε)-2L +  $\frac{h}{\epsilon}$ , {ε, 0, k}] /. e → 1;
  Collect[DPα→Df, β→De[λ][e $(f+\alpha\beta e f \delta) / (1+h\delta)$ ] /. e → 1, ε, Simplify]];
```

```
ε /: εp /; p > 1 := 0;
```

```

CF[E1n[ω_, L_, Q_, P_]] := E1n[Together[ω], Together[L], Together[Q], Together[P]];
E1n /: E1n[ω1_, L1_, Q1_, P1_] E1n[ω2_, L2_, Q2_, P2_] := CF@E1n[ω1 ω2, L1 + L2, Q1 + Q2, P1 + P2];
E1n[ω1_, L1_, Q1_, P1_] ≡ E1n[ω2_, L2_, Q2_, P2_] := Simplify[ω1 == ω2 ∧ L1 == L2 ∧ Q1 == Q2 ∧ P1 == P2];

```

$$0. R = \mathcal{O}\left(\exp\left(hl + \frac{e^h - 1}{h} ef + P\right) \mid e \otimes f\right):$$

```

E1n[X_{i,j}^+] := E1n[1, h_i l_j, h_i^{-1} (e^{h_i} - 1) e_i f_j, P^+];
E1n[X_{i,j}^-] := E1n[1, -h_i l_j, h_i^{-1} (e^{-h_i} - 1) e_i f_j, P^-];
E1n[p_Times] := E1n /@ p;

```

$E1n[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+]$

$$E1n\left[1, h_4 l_1 + h_6 l_3 + h_2 l_5, \frac{1}{h_2 h_4 h_6} \left(-e_6 f_3 h_2 h_4 + e^{h_6} e_6 f_3 h_2 h_4 - e_4 f_1 h_2 h_6 + e^{h_4} e_4 f_1 h_2 h_6 - e_2 f_5 h_4 h_6 + e^{h_2} e_2 f_5 h_4 h_6\right), 3 P^+\right]$$

$$1. \mathcal{O}(\mathcal{P}(l, e) e^{Vl+\beta e} \mid l e) = \mathcal{O}(\mathcal{P}(\partial_V, \partial_\beta) e^{Vl+e^V \beta e} \mid e l),$$

$$2. \mathcal{O}(\mathcal{P}(l, f) e^{Vl+\beta f} \mid f l) = \mathcal{O}(\mathcal{P}(\partial_V, \partial_\beta) e^{Vl+e^V \beta f} \mid l f).$$

```

NO_{(x:f|e)_i l_j} [E1n[ω_, L_, Q_, P_]] := With[{q = e^γ β x_i + γ l_j},
CF[E1n[ω, L,
e^γ β x_i + (Q /. x_i → 0),
e^{-q} DP_{l_j → D_γ, x_i → D_β} [P] [e^q]
] /. {γ → ∂_{l_j} L, β → ∂_{x_i} Q}]];

```

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta ef} \mid fe) = \mathcal{O}(v e^{v(-\alpha \beta h_r + \beta e_k + \alpha f_k + \delta e_k f_k)} \mid ef), \text{ with } v = (1 + h\delta)^{-1}:$$

```

NO_{f_i e_j → k} [E1n[ω_, L_, Q_, P_]] := With[{q = v (-α β h_r + β e_k + α f_k + δ e_k f_k)},
CF[E1n[v ω, L,
q + (Q /. f_i | e_j → 0),
e^{-q} DP_{f_i → D_α, e_j → D_β} [P] [e^q] + (Λ_1[h_r, e_k, l_k, f_k, α, β, δ] - 1 /. e → 1)
] /. v → (1 + h_r δ)^{-1} /. {α → ∂_{f_i} Q /. e_j → 0, β → ∂_{e_j} Q /. f_i → 0, δ → ∂_{f_i, e_j} Q}]];

```

```

m_{i,j → k} [Z_] := Module[{x, z}, CF[(Z // NO_{f_i e_j → x} // NO_{l_i e_x} // NO_{f_x l_j}) /. z_{-i|j|x} → z_k]];

```

Meta-associativity

$$\zeta = E1n\left[\omega, \sum_{i=1}^4 \sum_{j=1}^4 a_{i,j} h_i l_j, \sum_{i=1}^4 \sum_{j=1}^4 b_{i,j} e_i f_j, \theta\right]$$

$$E1n[\omega, h_1 l_1 a_{1,1} + h_1 l_2 a_{1,2} + h_1 l_3 a_{1,3} + h_1 l_4 a_{1,4} + h_2 l_1 a_{2,1} + h_2 l_2 a_{2,2} + h_2 l_3 a_{2,3} + h_2 l_4 a_{2,4} + h_3 l_1 a_{3,1} + h_3 l_2 a_{3,2} + h_3 l_3 a_{3,3} + h_3 l_4 a_{3,4} + h_4 l_1 a_{4,1} + h_4 l_2 a_{4,2} + h_4 l_3 a_{4,3} + h_4 l_4 a_{4,4}, e_1 f_1 b_{1,1} + e_1 f_2 b_{1,2} + e_1 f_3 b_{1,3} + e_1 f_4 b_{1,4} + e_2 f_1 b_{2,1} + e_2 f_2 b_{2,2} + e_2 f_3 b_{2,3} + e_2 f_4 b_{2,4} + e_3 f_1 b_{3,1} + e_3 f_2 b_{3,2} + e_3 f_3 b_{3,3} + e_3 f_4 b_{3,4} + e_4 f_1 b_{4,1} + e_4 f_2 b_{4,2} + e_4 f_3 b_{4,3} + e_4 f_4 b_{4,4}, \theta]$$

Short[$\xi // m_{1,2 \rightarrow 1}, 5 // \text{Timing}$

$$\left\{ 1.09375, \right. \\ \left. \text{E1n} \left[\frac{\omega}{1 + h_1 b_{2,1}}, h_1 l_1 a_{1,1} + h_1 l_1 a_{1,2} + h_1 l_3 a_{1,3} + h_1 l_4 a_{1,4} + h_1 l_1 a_{2,1} + h_1 l_1 a_{2,2} + h_1 l_3 a_{2,3} + h_1 l_4 a_{2,4} + h_3 l_1 a_{3,1} + \right. \right. \\ \left. \left. h_3 l_1 a_{3,2} + h_3 l_3 a_{3,3} + h_3 l_4 a_{3,4} + h_4 l_1 a_{4,1} + h_4 l_1 a_{4,2} + h_4 l_3 a_{4,3} + h_4 l_4 a_{4,4}, \frac{e^{\ll 1 \gg} e_1 f_1 b_{1,1} + \ll 41 \gg + \ll 1 \gg}{1 + h_1 b_{2,1}}, \right. \right. \\ \left. \left. (4 l_1 b_{2,1} + 4 e^{h_1 a_{1,2} + h_1 a_{2,2} + h_3 a_{3,2} + h_4 a_{4,2}} e_1 f_1 b_{1,1} b_{2,1} + 4 e^{h_1 a_{\ll 1 \gg} + \ll 2 \gg + h_4 \ll 1 \gg} e_1 f_1 l_1 b_{1,1} b_{2,1} + \ll 270 \gg) \right/ \right. \\ \left. \left. (2 (1 + h_1 b_{2,1})^4) \right] \right\}$$

Short[lhs = $\xi // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}, 5 // \text{Timing}$

$$\left\{ 136.859, \text{E1n} \left[\omega / (1 + h_1 b_{2,1} + e^{h_1 a_{1,2} + h_1 a_{2,2} + h_1 a_{3,2} + h_4 a_{4,2}} h_1 b_{3,1} - h_1^2 b_{2,2} b_{3,1} + h_1 b_{3,2} + h_1^2 b_{2,1} b_{3,2}), \right. \right. \\ \left. \left. h_1 l_1 a_{1,1} + h_1 l_1 a_{1,2} + h_1 l_1 a_{1,3} + \ll 10 \gg + h_4 l_1 a_{4,2} + h_4 l_1 a_{4,3} + h_4 l_4 a_{4,4}, \frac{\ll 1 \gg}{\ll 1 \gg}, \right. \right. \\ \left. \left. (4 l_1 b_{2,1} + 4 e^{h_1 a_{1,2} + \ll 6 \gg + h_4 a_{4,3}} e_1 f_1 b_{1,1} b_{2,1} + 4 e^{\ll 1 \gg} e_1 f_1 l_1 b_{1,1} b_{2,1} + \ll 11299 \gg + \ll 1 \gg + 2 \ll 7 \gg b_{4,2}^2 - \right. \right. \\ \left. \left. e_4^2 f_4^2 h_1^5 b_{2,2}^2 b_{3,1}^2 b_{3,4}^2 b_{4,2}^2) \right/ (2 (1 + h_1 b_{2,1} + e^{\ll 1 \gg} h_1 b_{3,1} - h_1^2 \ll 1 \gg b_{\ll 1 \gg} + h_1 b_{3,2} + h_1^2 b_{2,1} b_{3,2})^4) \right] \right\}$$

Short[rhs = $\xi // m_{2,3 \rightarrow 2} // m_{1,2 \rightarrow 1}, 5 // \text{Timing}$

$$\left\{ 112.891, \text{E1n} \left[\omega / (1 + h_1 b_{2,1} + e^{h_1 a_{1,2} + h_1 a_{2,2} + h_1 a_{3,2} + h_4 a_{4,2}} h_1 b_{3,1} - h_1^2 b_{2,2} b_{3,1} + h_1 b_{3,2} + h_1^2 b_{2,1} b_{3,2}), \right. \right. \\ \left. \left. h_1 l_1 a_{1,1} + h_1 l_1 a_{1,2} + h_1 l_1 a_{1,3} + \ll 10 \gg + h_4 l_1 a_{4,2} + h_4 l_1 a_{4,3} + h_4 l_4 a_{4,4}, \frac{\ll 1 \gg}{\ll 1 \gg}, \right. \right. \\ \left. \left. (4 l_1 b_{2,1} + 4 e^{h_1 a_{1,2} + \ll 6 \gg + h_4 a_{4,3}} e_1 f_1 b_{1,1} b_{2,1} + 4 e^{\ll 1 \gg} e_1 f_1 l_1 b_{1,1} b_{2,1} + \ll 11299 \gg + \ll 1 \gg + 2 \ll 7 \gg b_{4,2}^2 - \right. \right. \\ \left. \left. e_4^2 f_4^2 h_1^5 b_{2,2}^2 b_{3,1}^2 b_{3,4}^2 b_{4,2}^2) \right/ (2 (1 + h_1 b_{2,1} + e^{\ll 1 \gg} h_1 b_{3,1} - h_1^2 \ll 1 \gg b_{\ll 1 \gg} + h_1 b_{3,2} + h_1^2 b_{2,1} b_{3,2})^4) \right] \right\}$$

lhs == rhs

True

Profiling

<< "C:\drorbn\AcademicPensieve\Projects\Profile\Profile.m"

This is Profile.m of <http://drorbn.net/AcademicPensieve/Projects/Profile/>.

This version: March 2017. Original version: July 1994.

CF[E1n[ω, L, Q, P]] := PP_{CF}@E1n[Together[ω], Together[L], Together[Q], Together[P]];

NO_(x:f|e)_i_j[E1n[ω, L, Q, P]] := PP_{NOx1}@With[{q = $e^{\gamma} \beta x_i + \gamma l_j$ },

CF[E1n[$\omega, L,$
 $e^{\gamma} \beta x_i + (Q /. x_i \rightarrow \theta),$
 $e^{-q} \text{DP}_{1_j \rightarrow D_{\gamma}, x_i \rightarrow D_{\beta}} [P] [e^q]$
 $] /. \{\gamma \rightarrow \partial_{1_j} L, \beta \rightarrow \partial_{x_i} Q\}];$

NO_{f_i}_{e_j}_k[E1n[ω, L, Q, P]] := PP_{NOfe}@With[{q = $v (-\alpha \beta h_k + \beta e_k + \alpha f_k + \delta e_k f_k)$ },

CF[E1n[$v \omega, L,$
 $q + (Q /. f_i | e_j \rightarrow \theta),$
 $e^{-q} \text{DP}_{f_i \rightarrow D_{\alpha}, e_j \rightarrow D_{\beta}} [P] [e^q] + (\Lambda_1 [h_k, e_k, l_k, f_k, \alpha, \beta, \delta] - 1 /. \epsilon \rightarrow 1)$
 $] /. v \rightarrow (1 + h_k \delta)^{-1} /. \{\alpha \rightarrow \partial_{f_i} Q /. e_j \rightarrow \theta, \beta \rightarrow \partial_{e_j} Q /. f_i \rightarrow \theta, \delta \rightarrow \partial_{f_i, e_j} Q\}];$

```
BeginProfile[];
Short[ξ // m1,2→1 // m1,3→1]
EndProfile[];
PrintProfile[]
```

$$\mathbb{E}1n\left[\frac{\omega}{1 + h_1 b_{2,1} + \langle\langle 1 \rangle\rangle - \langle\langle 1 \rangle\rangle + h_1 b_{\langle\langle 1 \rangle\rangle} + h_1^2 b_{2,1} b_{3,2}}, h_1 l_1 a_{1,1} + \langle\langle 14 \rangle\rangle + h_4 l_4 a_{4,4}, \frac{\langle\langle 1 \rangle\rangle}{\langle\langle 1 \rangle\rangle}, \frac{\langle\langle 1 \rangle\rangle}{2 (\langle\langle 1 \rangle\rangle)^4}\right]$$

CF: called 8 times, time in 122.108/122.108

Parents:

- (2) 45.172/ 45.172 under NOfe
- (4) 69.874/ 69.874 under NOx1
- (2) 7.062/ 7.062 under ProfileRoot

NOx1: called 4 times, time in 9.001/78.875

Parents:

- (4) 9.001/ 78.875 under ProfileRoot

Children:

- (4) 69.874/ 69.874 above CF

NOfe: called 2 times, time in 0.173/45.345

Parents:

- (2) 0.173/ 45.345 under ProfileRoot

Children:

- (2) 45.172/ 45.172 above CF

ProfileRoot: called 0 times, time in 0./0.

Children:

- (2) 7.062/ 7.062 above CF
- (2) 0.173/ 45.345 above NOfe
- (4) 9.001/ 78.875 above NOx1

Logos Games

$\Lambda_1[h, e, l, f, \alpha, \beta, \delta]$

$$1 + \frac{1}{2(1+h\delta)^4} \left(4l(1+h\delta)^2((\alpha+e\delta)(\beta+f\delta) + \delta(1+h\delta)) + 2f(\alpha+e\delta)(1+h\delta)((\alpha+e\delta)(\beta+f\delta) + 2\delta(1+h\delta)) + 2e(\beta+f\delta)(1+h\delta)((\alpha+e\delta)(\beta+f\delta) + 2\delta(1+h\delta)) - h((\alpha+e\delta)^2(\beta+f\delta)^2 + 4\delta(\alpha+e\delta)(\beta+f\delta)(1+h\delta) + 2\delta^2(1+h\delta)^2) \right) \in$$

With $\left\{ \xi = \frac{h}{t-1} \right\}$,

$\Lambda_1[h, e, l, f, \alpha, \beta, \delta] /. \text{Thread}[\{h, e, l, f, \alpha, \beta, \delta\} \rightarrow \{h, \xi e, l, f, \alpha, \xi^{-1} \beta, \xi^{-1} \delta\}] // \text{Simplify}$

$$1 + \frac{1}{2h(1+(-1+t)\delta)^4} \left((-1+t) \left(-(-1+t)(\alpha+e\delta)^2(\beta+f\delta)^2 - 4(-1+t)\delta(\alpha+e\delta)(\beta+f\delta)(1+(-1+t)\delta) - 2(-1+t)\delta^2(1+(-1+t)\delta)^2 + 4l(1+(-1+t)\delta)^2(\alpha(\beta+f\delta) + \delta(1+(-1+t)\delta) + e(\beta+f\delta)) \right) + 2f(\alpha+e\delta)(1+(-1+t)\delta)(\alpha(\beta+f\delta) + \delta(2+2(-1+t)\delta) + e(\beta+f\delta)) + 2e(\beta+f\delta)(1+(-1+t)\delta)(\alpha(\beta+f\delta) + \delta(2+2(-1+t)\delta) + e(\beta+f\delta)) \right) \in$$

Pragmatic Simplifications

$\mathbb{E}1n[\omega, L, Q, P]$ stands for $\omega e^{L+Q}(1 + \epsilon P)$; $\mathbb{E}1p[\omega, L, Q, P]$ stands for $\omega^{-1} e^{L+\omega^{-1}Q}(1 + \epsilon \omega^{-4} P)$ /. $e_i \rightarrow \frac{t_i-1}{h_i} e_i$, all written in $t_i = e^{h_i}$.

$\mathbb{E}1n[\mathbb{E}1p[\omega_, L_, Q_, P_]] := CF[\text{PowerExpand} / @ CF[\mathbb{E}1n[\omega^{-1}, L, \omega^{-1} Q, \omega^{-4} P] /. e_{i_} \mapsto \frac{t_i - 1}{h_i} e_i /. t_{i_} \mapsto e^{h_i}]]];$

$CF[\mathbb{E}1p[\omega_, L_, Q_, P_]] := \mathbb{E}1p[\text{Together}[\omega], \text{Together}[L], \text{Together}[Q], \text{Together}[P]]];$

$\mathbb{E}1p[\mathbb{E}1n[\omega_, L_, Q_, P_]] := CF[\mathbb{E}1p[\omega^{-1}, L, \omega^{-1} Q, \omega^{-4} P] /. e_{i_} \mapsto \frac{h_i}{t_i - 1} e_i /. h_{i_} \mapsto \text{Log}[t_i]]];$

$\mathbb{E}1p[\omega 1_, L 1_, Q 1_, P 1_]\equiv \mathbb{E}1p[\omega 2_, L 2_, Q 2_, P 2_]:= \text{Simplify}[\omega 1 == \omega 2 \wedge L 1 == L 2 \wedge Q 1 == Q 2 \wedge P 1 == P 2];$

$X_{1,2}^+ // \mathbb{E}1n$

$\mathbb{E}1n[1, h_1 l_2, \frac{(-1 + e^{h_1}) e_1 f_2}{h_1}, P^+]$

$X_{1,2}^+ // \mathbb{E}1n // \mathbb{E}1p$

$\mathbb{E}1p[1, \text{Log}[t_1] l_2, e_1 f_2, P^+]$

$\zeta = \text{ReplacePart}[\zeta, 4 \rightarrow P]$

ζ

$\text{Simplify} / @ \mathbb{E}1p[\zeta]$

$\mathbb{E}1p[\zeta]$

$\zeta \equiv (\mathbb{E}1p[\zeta] // \mathbb{E}1n)$

$\zeta \equiv \mathbb{E}1n[\mathbb{E}1p[\zeta]]$

$\text{Simplify} / @ \mathbb{E}1n[\mathbb{E}1p @ \zeta]$

$\mathbb{E}1n[\zeta]$

$(\mathbb{E}1p @ \zeta /. h_{i_} \mapsto \text{Log}[t_i]) \equiv (\mathbb{E}1n[\mathbb{E}1p @ \zeta] // \mathbb{E}1p)$

$\zeta \equiv \mathbb{E}1p[\mathbb{E}1n[\zeta]]$

$\mathbb{E}1p[\omega, L, e_1 f_2 + f_1 e_2 + \delta e_1 f_1, \theta] // \mathbb{E}1n$

$\mathbb{E}1n\left[\frac{1}{\omega}, L, \frac{1}{\omega h_1 h_2} (-e_2 f_1 h_1 + e^{h_2} e_2 f_1 h_1 - \delta e_1 f_1 h_2 + e^{h_1} \delta e_1 f_1 h_2 - e_1 f_2 h_2 + e^{h_1} e_1 f_2 h_2), \theta\right]$

$\text{Simplify} / @$

$(\mathbb{E}1p[\omega, L, e_1 f_2 + f_1 e_2 + \delta e_1 f_1, \theta] // \mathbb{E}1n // \text{NO}_{f_1, e_1 \rightarrow \theta} // \mathbb{E}1p) /. \{t_\theta \rightarrow t_1, h_\theta \rightarrow h_1, l_\theta \rightarrow l_1\} /. \{e_2 \rightarrow \alpha, f_2 \rightarrow \beta\}$

$\mathbb{E}1p\left[-\delta + \omega + \delta t_1, L, e_\theta (\beta + \delta f_\theta) + \frac{\alpha (\beta + \omega f_\theta - \beta t_1)}{\omega}, \frac{1}{2 \text{Log}[t_1]}\right]$

$(-1 + t_1) \left(\alpha^2 \beta^2 - 4 \alpha \beta \delta^2 + 2 \delta^4 + 4 \alpha \beta \delta \omega - 4 \delta^3 \omega + 2 \delta^2 \omega^2 + 4 \alpha \beta \delta^2 l_1 - 4 \delta^4 l_1 - 8 \alpha \beta \delta \omega l_1 + 12 \delta^3 \omega l_1 + 4 \alpha \beta \omega^2 l_1 - 12 \delta^2 \omega^2 l_1 + 4 \delta \omega^3 l_1 - \alpha^2 \beta^2 t_1 + 8 \alpha \beta \delta^2 t_1 - 6 \delta^4 t_1 - 4 \alpha \beta \delta \omega t_1 + 8 \delta^3 \omega t_1 - 2 \delta^2 \omega^2 t_1 - 8 \alpha \beta \delta^2 l_1 t_1 + 12 \delta^4 l_1 t_1 + 8 \alpha \beta \delta \omega l_1 t_1 - 24 \delta^3 \omega l_1 t_1 + 12 \delta^2 \omega^2 l_1 t_1 - 4 \alpha \beta \delta^2 t_1^2 + 6 \delta^4 t_1^2 - 4 \delta^3 \omega t_1^2 + 4 \alpha \beta \delta^2 l_1 t_1^2 - 12 \delta^4 l_1 t_1^2 + 12 \delta^3 \omega l_1 t_1^2 - 2 \delta^4 t_1^3 + 4 \delta^4 l_1 t_1^3 + \alpha^2 \delta f_\theta^2 (-\delta + 2 \omega + \delta t_1) + \delta e_\theta^2 (\beta + \delta f_\theta) (\beta (-\delta + 2 \omega + \delta t_1) + \delta f_\theta (-3 \delta + 4 \omega + 3 \delta t_1)) + 2 \alpha f_\theta (2 \delta l_1 (-\delta + \omega + \delta t_1)^2 + \omega (\alpha \beta + 2 \delta (-\delta + \omega) + 2 \delta^2 t_1)) + 2 e_\theta (\alpha \delta^2 f_\theta^2 (-2 \delta + 3 \omega + 2 \delta t_1) + 2 \delta f_\theta (\delta l_1 (-\delta + \omega + \delta t_1)^2 + (-\delta + 2 \omega + \delta t_1) (\alpha \beta + \delta (-\delta + \omega) + \delta^2 t_1)) + \beta (2 \delta l_1 (-\delta + \omega + \delta t_1)^2 + \omega (\alpha \beta + 2 \delta (-\delta + \omega) + 2 \delta^2 t_1)) \right)$

Simplify /@ ($\{\mathbf{E1p}[\omega, L, \omega \mathbf{e}_1 \beta + \omega \mathbf{f}_1 \alpha + \omega \delta \mathbf{e}_1 \mathbf{f}_1, \mathbf{0}] // \mathbf{E1n} // \mathbf{NO}_{\mathbf{f}_1 \mathbf{e}_1 \rightarrow \mathbf{0}} // \mathbf{E1p}\} /. \{\mathbf{t}_0 \rightarrow \mathbf{t}_1, \mathbf{h}_0 \rightarrow \mathbf{h}_1, \mathbf{l}_0 \rightarrow \mathbf{l}_1\}$)

$\mathbf{E1p}[\omega (1 - \delta + \delta \mathbf{t}_1), L, \omega (\mathbf{e}_0 (\beta + \delta \mathbf{f}_0) + \alpha (\beta + \mathbf{f}_0 - \beta \mathbf{t}_1))]$,

$$\frac{1}{2 \text{Log}[\mathbf{t}_1]} \omega^4 (-1 + \mathbf{t}_1) \left(\alpha^2 \beta^2 + 4 \alpha \beta \delta + 2 \delta^2 - 4 \alpha \beta \delta^2 - 4 \delta^3 + 2 \delta^4 + 4 \alpha \beta \mathbf{l}_1 + 4 \delta \mathbf{l}_1 - \right. \\ \left. 8 \alpha \beta \delta \mathbf{l}_1 - 12 \delta^2 \mathbf{l}_1 + 4 \alpha \beta \delta^2 \mathbf{l}_1 + 12 \delta^3 \mathbf{l}_1 - 4 \delta^4 \mathbf{l}_1 - \alpha^2 \beta^2 \mathbf{t}_1 - 4 \alpha \beta \delta \mathbf{t}_1 - 2 \delta^2 \mathbf{t}_1 + 8 \alpha \beta \delta^2 \mathbf{t}_1 + \right. \\ \left. 8 \delta^3 \mathbf{t}_1 - 6 \delta^4 \mathbf{t}_1 + 8 \alpha \beta \delta \mathbf{l}_1 \mathbf{t}_1 + 12 \delta^2 \mathbf{l}_1 \mathbf{t}_1 - 8 \alpha \beta \delta^2 \mathbf{l}_1 \mathbf{t}_1 - 24 \delta^3 \mathbf{l}_1 \mathbf{t}_1 + 12 \delta^4 \mathbf{l}_1 \mathbf{t}_1 - 4 \alpha \beta \delta^2 \mathbf{t}_1^2 - \right. \\ \left. 4 \delta^3 \mathbf{t}_1^2 + 6 \delta^4 \mathbf{t}_1^2 + 4 \alpha \beta \delta^2 \mathbf{l}_1 \mathbf{t}_1^2 + 12 \delta^3 \mathbf{l}_1 \mathbf{t}_1^2 - 12 \delta^4 \mathbf{l}_1 \mathbf{t}_1^2 - 2 \delta^4 \mathbf{t}_1^3 + 4 \delta^4 \mathbf{l}_1 \mathbf{t}_1^3 + \alpha^2 \delta \mathbf{f}_0^2 (2 - \delta + \delta \mathbf{t}_1) + \right. \\ \left. 2 \alpha \mathbf{f}_0 (\alpha \beta + 2 \delta - 2 \delta^2 + 2 \delta^2 \mathbf{t}_1 + 2 \delta \mathbf{l}_1 (1 - \delta + \delta \mathbf{t}_1)^2) + \delta \mathbf{e}_0^2 (\beta + \delta \mathbf{f}_0) (\beta (2 - \delta + \delta \mathbf{t}_1) + \delta \mathbf{f}_0 (4 - 3 \delta + 3 \delta \mathbf{t}_1)) + \right. \\ \left. 2 \mathbf{e}_0 (\alpha \delta^2 \mathbf{f}_0^2 (3 - 2 \delta + 2 \delta \mathbf{t}_1) + \beta (\alpha \beta + 2 \delta - 2 \delta^2 + 2 \delta^2 \mathbf{t}_1 + 2 \delta \mathbf{l}_1 (1 - \delta + \delta \mathbf{t}_1)^2) + \right. \\ \left. 2 \delta \mathbf{f}_0 (\delta \mathbf{l}_1 (1 - \delta + \delta \mathbf{t}_1)^2 + (2 - \delta + \delta \mathbf{t}_1) (\alpha \beta + \delta - \delta^2 + \delta^2 \mathbf{t}_1)) \right) \Big]]$$

Simplify /@

$\left(\left(\mathbf{E1p}[\omega, L, \mathbf{e}_1 \beta + \mathbf{f}_1 \alpha + \delta \mathbf{e}_1 \mathbf{f}_1 * \left(\frac{\mathbf{t}_1 - 1}{\text{Log}[\mathbf{t}_1]} \right), \mathbf{0}] // \mathbf{E1n} // \mathbf{NO}_{\mathbf{f}_1 \mathbf{e}_1 \rightarrow \mathbf{0}} // \mathbf{E1p} \right) /. \{\mathbf{t}_0 \rightarrow \mathbf{t}_1, \mathbf{h}_0 \rightarrow \mathbf{h}_1, \mathbf{l}_0 \rightarrow \mathbf{l}_1\} \right)$

$\mathbf{E1p}\left[\frac{\delta + \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2}{\text{Log}[\mathbf{t}_1]}, L, \mathbf{e}_0 \left(\beta + \frac{\delta \mathbf{f}_0 (-1 + \mathbf{t}_1)}{\text{Log}[\mathbf{t}_1]} \right) + \frac{\alpha (\beta + \omega \mathbf{f}_0 - \beta \mathbf{t}_1)}{\omega} \right]$,

$$\frac{1}{2 \text{Log}[\mathbf{t}_1]^5} (-1 + \mathbf{t}_1) \left(2 \delta^4 + 4 \delta^3 \omega \text{Log}[\mathbf{t}_1] - 4 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 + 2 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 - 4 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 + \alpha^2 \beta^2 \text{Log}[\mathbf{t}_1]^4 - \right. \\ \left. 4 \delta^4 \mathbf{l}_1 - 12 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 + 4 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 - 12 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 + 8 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 \mathbf{l}_1 - 4 \delta \omega^3 \text{Log}[\mathbf{t}_1]^3 \mathbf{l}_1 + \right. \\ \left. 4 \alpha \beta \omega^2 \text{Log}[\mathbf{t}_1]^4 \mathbf{l}_1 - 14 \delta^4 \mathbf{t}_1 - 20 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{t}_1 + 16 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1 - 6 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1 + \right. \\ \left. 8 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 \mathbf{t}_1 - \alpha^2 \beta^2 \text{Log}[\mathbf{t}_1]^4 \mathbf{t}_1 + 28 \delta^4 \mathbf{l}_1 \mathbf{t}_1 + 60 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 \mathbf{t}_1 - 16 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1 + \right. \\ \left. 36 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1 - 16 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 \mathbf{l}_1 \mathbf{t}_1 + 4 \delta \omega^3 \text{Log}[\mathbf{t}_1]^3 \mathbf{l}_1 \mathbf{t}_1 + 42 \delta^4 \mathbf{t}_1^2 + 40 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{t}_1^2 - \right. \\ \left. 24 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1^2 + 6 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1^2 - 4 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 \mathbf{t}_1^2 - 84 \delta^4 \mathbf{l}_1 \mathbf{t}_1^2 - 120 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 \mathbf{t}_1^2 + \right. \\ \left. 24 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1^2 - 36 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1^2 + 8 \alpha \beta \delta \omega \text{Log}[\mathbf{t}_1]^3 \mathbf{l}_1 \mathbf{t}_1^2 - 70 \delta^4 \mathbf{t}_1^3 - 40 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{t}_1^3 + \right. \\ \left. 16 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1^3 - 2 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1^3 + 140 \delta^4 \mathbf{l}_1 \mathbf{t}_1^3 + 120 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 \mathbf{t}_1^3 - 16 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1^3 + \right. \\ \left. 12 \delta^2 \omega^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1^3 + 70 \delta^4 \mathbf{t}_1^4 + 20 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{t}_1^4 - 4 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{t}_1^4 - 140 \delta^4 \mathbf{l}_1 \mathbf{t}_1^4 - 60 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 \mathbf{t}_1^4 + \right. \\ \left. 4 \alpha \beta \delta^2 \text{Log}[\mathbf{t}_1]^2 \mathbf{l}_1 \mathbf{t}_1^4 - 42 \delta^4 \mathbf{t}_1^5 - 4 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{t}_1^5 + 84 \delta^4 \mathbf{l}_1 \mathbf{t}_1^5 + 12 \delta^3 \omega \text{Log}[\mathbf{t}_1] \mathbf{l}_1 \mathbf{t}_1^5 + 14 \delta^4 \mathbf{t}_1^6 - 28 \delta^4 \mathbf{l}_1 \mathbf{t}_1^6 - \right. \\ \left. 2 \delta^4 \mathbf{t}_1^7 + 4 \delta^4 \mathbf{l}_1 \mathbf{t}_1^7 + \alpha^2 \delta \text{Log}[\mathbf{t}_1]^2 \mathbf{f}_0^2 (-1 + \mathbf{t}_1) (\delta + 2 \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2) + \delta \mathbf{e}_0^2 (\beta \text{Log}[\mathbf{t}_1] + \delta \mathbf{f}_0 (-1 + \mathbf{t}_1)) \right. \\ \left. (-1 + \mathbf{t}_1) (\beta \text{Log}[\mathbf{t}_1] (\delta + 2 \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2) + \delta \mathbf{f}_0 (-1 + \mathbf{t}_1) (3 \delta + 4 \omega \text{Log}[\mathbf{t}_1] - 6 \delta \mathbf{t}_1 + 3 \delta \mathbf{t}_1^2)) + \right. \\ \left. 2 \alpha \text{Log}[\mathbf{t}_1] \mathbf{f}_0 (2 \delta \mathbf{l}_1 (-1 + \mathbf{t}_1) (\delta + \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2)^2 + \right. \\ \left. \omega \text{Log}[\mathbf{t}_1] (-2 \delta^2 - 2 \delta \omega \text{Log}[\mathbf{t}_1] + \alpha \beta \text{Log}[\mathbf{t}_1]^2 + 2 \delta (3 \delta + \omega \text{Log}[\mathbf{t}_1]) \mathbf{t}_1 - 6 \delta^2 \mathbf{t}_1^2 + 2 \delta^2 \mathbf{t}_1^3) \right) + \right. \\ \left. 2 \mathbf{e}_0 (\alpha \delta^2 \text{Log}[\mathbf{t}_1] \mathbf{f}_0^2 (-1 + \mathbf{t}_1)^2 (2 \delta + 3 \omega \text{Log}[\mathbf{t}_1] - 4 \delta \mathbf{t}_1 + 2 \delta \mathbf{t}_1^2) + \right. \\ \left. 2 \delta \mathbf{f}_0 (-1 + \mathbf{t}_1) (\delta \mathbf{l}_1 (-1 + \mathbf{t}_1) (\delta + \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2)^2 + \right. \\ \left. (\delta + 2 \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2) (-\delta^2 - \delta \omega \text{Log}[\mathbf{t}_1] + \alpha \beta \text{Log}[\mathbf{t}_1]^2 + \delta (3 \delta + \omega \text{Log}[\mathbf{t}_1]) \mathbf{t}_1 - 3 \delta^2 \mathbf{t}_1^2 + \delta^2 \mathbf{t}_1^3) \right) + \right. \\ \left. \beta \text{Log}[\mathbf{t}_1] (2 \delta \mathbf{l}_1 (-1 + \mathbf{t}_1) (\delta + \omega \text{Log}[\mathbf{t}_1] - 2 \delta \mathbf{t}_1 + \delta \mathbf{t}_1^2)^2 + \omega \text{Log}[\mathbf{t}_1] \right. \\ \left. (-2 \delta^2 - 2 \delta \omega \text{Log}[\mathbf{t}_1] + \alpha \beta \text{Log}[\mathbf{t}_1]^2 + 2 \delta (3 \delta + \omega \text{Log}[\mathbf{t}_1]) \mathbf{t}_1 - 6 \delta^2 \mathbf{t}_1^2 + 2 \delta^2 \mathbf{t}_1^3) \right) \Big]]$$