

Pensieve header: The main \mathfrak{g}_0 theorem.

Reminders

1. Fill out "Graduate Course Participation Form" (see <http://drorbn.net/AcademicPensieve/Classes/17-1350-AKT/GCP.jpg>, in time).
2. Make sure that you have Mathematica and that you play with these programs!
3. Change meeting time?

$R = \sum a_i \otimes b_j \in A \otimes A = U(\mathfrak{g}) \otimes U(\mathfrak{g})$
 s.t. $R^{12} R^{13} R^{23} = R^{23} R^{13} R^{12}$

$\sum_{i,j,k} b_j a_i b_k a_i b_j a_k \in U(\mathfrak{g})$

Today: $\mathfrak{g}_0 = \langle h, e, f \rangle / [e, h] = -e \quad [f, h] = f \quad [e, f] = h$
 $r = h \otimes 1 + e \otimes f \quad R = \exp(r)$

Note $U(\mathfrak{g}_0)^{\otimes S} = U(\bigoplus_S \mathfrak{g}_0) = U(\langle h_i, e_i, f_i \rangle / [e_i, h_j] = \delta_{ij} e_i \text{ etc.})$ h_i central

Theorem. $R = e^{h \otimes 1 + e \otimes f} = \mathcal{O}(\exp(h1 + \frac{e^h - 1}{h} ef \mid e \otimes f)$.

Representing \mathfrak{g}_0

Date: Sun, 23 May 1999 17:24:53 +0200 (MET DST)
 From: Dylan Thurston <Dylan.Thurston@math.unige.ch>
 To: Dror Bar-Natan <drorbn@math.huji.ac.il>
 Subject: Oh, yeah...

Duflo had another possibly useful comment: he said that there is a simpler (non-trivial) algebra than \mathfrak{sl}_2 , given by the relations (more or less)

$$\begin{aligned}
 [x, y] &= z \\
 [x, t] &= x \\
 [y, t] &= -y \\
 [t, z] &= [x, z] = [y, z] = 0
 \end{aligned}$$

I hope I got that right; it should be the Lie algebra of matrices

$$\begin{pmatrix}
 0 & x & z \\
 0 & t & y \\
 0 & 0 & 0
 \end{pmatrix}$$

He says that one can write down the exponential explicitly, that commutators very quickly go to zero, etc. Apparently it plays the same role for reducible lie algebras that \mathfrak{sl}_2 plays for semi-simple ones. It's worth thinking about.

Best,
 Dylan

$$\rho_h = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \rho_e = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}; \rho_l = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \rho_f = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix};$$

$B[x_?MatrixQ, y_?MatrixQ] := x.y - y.x;$

MatrixForm /@ {B[ρe, ρl], B[ρf, ρl], B[ρe, ρf], B[ρh, ρe], B[ρh, ρl], B[ρh, ρf]}

$$\left\{ \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right\}$$

Implementing g_0

```
PBWRule = {e → 1, l → 2, f → 3};
B[U@e, U@l] = -U@e;
B[U@f, U@l] = U@f;
B[U@e, U@f] = h U[];
```

```
$TD = 3; h /: h^d. /; d > $TD := 0;
```

```
x_ ≤ y_ := OrderedQ[{x, y} /. PBWRule]; x_ < y_ := !OrderedQ[{y, x} /. PBWRule];
Simp[ε_] := Collect[ε, _U, Expand];
```

```
U_i[ε_] := ε /. {h → h_i, t → t_i, u_U ⇒ Replace[u, x_ ⇒ x_i, 1]};
B[U[(x_)_i], U[(y_)_i]] := B[U[x_i], U[y_i]] = U_i[B[U@x, U@y]];
B[U[(x_)_i], U[(y_)_j]] /; i != j := 0;
B[x_, x_] = 0;
B[U[y_], U[x_]] := B[U[y], U[x]] = Simp[-B[U[x], U[y]]];
B[x_, y_] := x**y - y**x;
```

```
Unprotect[NonCommutativeMultiply];
NonCommutativeMultiply[x_] := x;
0**_ = _**0 = 0;
x_**U[] := x; U[]**x_ := x;
(a_**x_U)**(b_**y_U) := If[ab === 0, 0, Simp[ab(x**y)]];
(a_**x_U)**y_ := Simp[a(x**y)]; x_**(a_**y_U) := Simp[a(x**y)];
(x_Plus)**y_ := (#**y) & /@ x; x_**(y_Plus) := (x**#) & /@ y;
```

```
U[xx___, x_] ** U[y_, yy___] := If[x ≤ y, U[xx, x, y, yy], U@xx ** (U@y ** U@x + B[U@x, U@y]) ** U@yy];
```

```
UU[L___, x^n_, r___] := UU[L, Sequence@@Table[x, {n}], r];
UU[L___, 1, r___] := UU[L, r];
UU[] = U[];
UU[L_, r___] := U[L] ** UU[r];
```

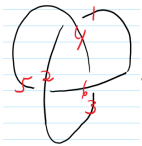
```
UProducts[{}, 0] = {UU[]};
UProducts[{}, n_Integer] /; n > 0 = {};
UProducts[{x_, xs___}, n_Integer] :=
  Sort@Flatten@Table[UU[x^k] ** u, {k, 0, n}, {u, Uroducts[{xs}, n - k]};
UProducts[xs_List, k_Integer, n_Integer] := Uroducts[Flatten@Table[x_j, {x, xs}, {j, k}], n];
UProducts[any___, {n_}] := Flatten@Table[Uroducts[any, k], {k, 0, n}];
```

```
r_{i,j}_ := Simp[ħ (h_i UU[l_j] + UU[e_i, f_j])]
```

```
UExp[u_] := Module[{s, t, k},
  s = t = U[]; k = 0;
  While[k < 20 & 0 != (t = t ** u), s += t / (++k)];
  Simp[s];
  R_{i,j}_ := UExp[r_{i,j}_];
```

```
m[i_, j_, k_][ε_] := Simp[ε /. {
  u_U := UU@@Join[DeleteCases[u, x_{i|j}], U@@Cases[u, x_{-i} := x_k], U@@Cases[u, x_{-j} := x_k]],
  h_{i|j} → h_k}]
```

The Invariant of the Trefoil



; \$TD = 2; R_{4,1} ** R_{2,5} ** R_{6,3}

$$\begin{aligned}
 & U[] + \hbar h_4 U[l_1] + \hbar h_6 U[l_3] + \hbar h_2 U[l_5] + \left(\hbar + \frac{\hbar^2 h_2}{2}\right) U[e_2, f_5] + \left(\hbar + \frac{\hbar^2 h_4}{2}\right) U[e_4, f_1] + \left(\hbar + \frac{\hbar^2 h_6}{2}\right) U[e_6, f_3] + \\
 & \frac{1}{2} \hbar^2 h_4^2 U[l_1, l_1] + \hbar^2 h_4 h_6 U[l_1, l_3] + \hbar^2 h_2 h_4 U[l_1, l_5] + \frac{1}{2} \hbar^2 h_6^2 U[l_3, l_3] + \hbar^2 h_2 h_6 U[l_3, l_5] + \frac{1}{2} \hbar^2 h_2^2 U[l_5, l_5] + \\
 & \hbar^2 h_4 U[e_2, l_1, f_5] + \hbar^2 h_6 U[e_2, l_3, f_5] + \hbar^2 h_2 U[e_2, l_5, f_5] + \hbar^2 h_4 U[e_4, l_1, f_1] + \hbar^2 h_6 U[e_4, l_3, f_1] + \\
 & \hbar^2 h_2 U[e_4, l_5, f_1] + \hbar^2 h_4 U[e_6, l_1, f_3] + \hbar^2 h_6 U[e_6, l_3, f_3] + \hbar^2 h_2 U[e_6, l_5, f_3] + \frac{1}{2} \hbar^2 U[e_2, e_2, f_5, f_5] + \\
 & \hbar^2 U[e_2, e_4, f_1, f_5] + \hbar^2 U[e_2, e_6, f_3, f_5] + \frac{1}{2} \hbar^2 U[e_4, e_4, f_1, f_1] + \hbar^2 U[e_4, e_6, f_1, f_3] + \frac{1}{2} \hbar^2 U[e_6, e_6, f_3, f_3]
 \end{aligned}$$

Timing[\$TD = 3; R_{4,1} ** R_{2,5} ** R_{6,3} // m[1, 2, 1] // m[1, 3, 1] // m[1, 4, 1] // m[1, 5, 1] // m[1, 6, 1]]

$$\begin{aligned}
 & \{0.625, \left(1 - 2 \hbar h_1 + \hbar^2 h_1^2 + \frac{2}{3} \hbar^3 h_1^3\right) U[] + \left(3 \hbar h_1 - 6 \hbar^2 h_1^2 + 3 \hbar^3 h_1^3\right) U[l_1] + \\
 & \left(3 \hbar - \frac{3 \hbar^2 h_1}{2} - \frac{3}{2} \hbar^3 h_1^2\right) U[e_1, f_1] + \left(\frac{9}{2} \hbar^2 h_1^2 - 9 \hbar^3 h_1^3\right) U[l_1, l_1] + \\
 & \left(9 \hbar^2 h_1 - \frac{9}{2} \hbar^3 h_1^2\right) U[e_1, l_1, f_1] + \frac{9}{2} \hbar^3 h_1^3 U[l_1, l_1, l_1] + \left(\frac{9 \hbar^2}{2} + \frac{9 \hbar^3 h_1}{2}\right) U[e_1, e_1, f_1, f_1] + \\
 & \frac{27}{2} \hbar^3 h_1^2 U[e_1, l_1, l_1, f_1] + \frac{27}{2} \hbar^3 h_1 U[e_1, e_1, l_1, f_1, f_1] + \frac{9}{2} \hbar^3 U[e_1, e_1, e_1, f_1, f_1, f_1]\}
 \end{aligned}$$

Ordering Symbols

```
0[poly_, specs___] := Module[{vs, us, z},
  vs = Join@@(First /@ {specs});
  us = Join@@({specs} /. (L_ -> s_) := (L /. x_{-i} := x_s));
  Simp@Total[CoefficientRules[Normal@Series[poly, {ħ, 0, $TD}], vs] /. (p_ -> c_) := c UU@@(us^p)]
]
```

Theorem. $R = e^{\hbar \otimes + e \otimes f} = \mathcal{O}(\exp(\hbar l + \frac{e^{\hbar-1}}{\hbar} e f \mid e \otimes l f))$.

Brute Proof.

$$\$TD = 6; 0[\text{Exp}[\hbar h_1 l_2 + \frac{e^{\hbar h_1} - 1}{h_1} e_1 f_2], \{e_1\} \rightarrow 1, \{l_2, f_2\} \rightarrow 2] == R_{1,2}$$

True

Debts.

1. How does the \mathcal{O} program work?

2. Why is the above theorem true?
3. What do you do with it?

old above / new below

Theorem. $R = e^{h\otimes l + e\otimes f} = \mathcal{O}(\exp(hl + \frac{e^h - 1}{h} ef \mid e\otimes lf).$

Gentler Proof, Presented Brutely.

MatrixForm /@ {**MatrixExp**[**h** **ρ** **l** + **e** **ρ** **f**], **MatrixExp**[**h** **ρ** **l**].**MatrixExp**[$\frac{e^h - 1}{h}$ **e** **ρ** **f**] }

$$\left\{ \begin{pmatrix} 1 & \frac{e(-1+e^h)}{h} & 0 \\ 0 & e^h & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & \frac{e(-1+e^h)}{h} & 0 \\ 0 & e^h & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

The Invariant of the Trefoil, Again

Timing[\$TD = 3;

$$\begin{aligned} & \mathcal{O} \left[\text{Exp} \left[\hbar h l_1 + \frac{e^{\hbar h} - 1}{h} e_4 f_1 + \hbar h l_5 + \frac{e^{\hbar h} - 1}{h} e_2 f_5 + \hbar h l_3 + \frac{e^{\hbar h} - 1}{h} e_6 f_3 \right], \right. \\ & \quad \left. \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1 \right] /. h_1 \rightarrow h \\ & \{0.0625, \left(1 - 2 h \hbar + h^2 \hbar^2 + \frac{2 h^3 \hbar^3}{3} \right) U[] + \\ & \quad (3 h \hbar - 6 h^2 \hbar^2 + 3 h^3 \hbar^3) U[l_1] + \left(3 \hbar - \frac{3 h \hbar^2}{2} - \frac{3 h^2 \hbar^3}{2} \right) U[e_1, f_1] + \left(\frac{9 h^2 \hbar^2}{2} - 9 h^3 \hbar^3 \right) U[l_1, l_1] + \\ & \quad \left(9 h \hbar^2 - \frac{9 h^2 \hbar^3}{2} \right) U[e_1, l_1, f_1] + \frac{9}{2} h^3 \hbar^3 U[l_1, l_1, l_1] + \left(\frac{9 \hbar^2}{2} + \frac{9 h \hbar^3}{2} \right) U[e_1, e_1, f_1, f_1] + \\ & \quad \left. \frac{27}{2} h^2 \hbar^3 U[e_1, l_1, l_1, f_1] + \frac{27}{2} h \hbar^3 U[e_1, e_1, l_1, f_1, f_1] + \frac{9}{2} \hbar^3 U[e_1, e_1, e_1, f_1, f_1, f_1] \right\} \end{aligned}$$

Timing[\$TD = 5;

$$\begin{aligned} & \mathcal{O} \left[\text{Exp} \left[\hbar h l_1 + \frac{e^{\hbar h} - 1}{h} e_4 f_1 + \hbar h l_5 + \frac{e^{\hbar h} - 1}{h} e_2 f_5 + \hbar h l_3 + \frac{e^{\hbar h} - 1}{h} e_6 f_3 \right], \right. \\ & \quad \left. \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1 \right] /. h_1 \rightarrow h \\ & \{1.09375, \left(1 - 2 h \hbar + h^2 \hbar^2 + \frac{2 h^3 \hbar^3}{3} - \frac{5 h^4 \hbar^4}{12} - \frac{23 h^5 \hbar^5}{30} \right) U[] + \\ & \quad \left(3 h \hbar - 6 h^2 \hbar^2 + 3 h^3 \hbar^3 + 2 h^4 \hbar^4 - \frac{5 h^5 \hbar^5}{4} \right) U[l_1] + \left(3 \hbar - \frac{3 h \hbar^2}{2} - \frac{3 h^2 \hbar^3}{2} + \frac{7 h^3 \hbar^4}{8} + \frac{61 h^4 \hbar^5}{40} \right) U[e_1, f_1] + \\ & \quad \left(\frac{9 h^2 \hbar^2}{2} - 9 h^3 \hbar^3 + \frac{9 h^4 \hbar^4}{2} + 3 h^5 \hbar^5 \right) U[l_1, l_1] + \left(9 h \hbar^2 - \frac{9 h^2 \hbar^3}{2} - \frac{9 h^3 \hbar^4}{2} + \frac{21 h^4 \hbar^5}{8} \right) U[e_1, l_1, f_1] + \\ & \quad \left(\frac{9 h^3 \hbar^3}{2} - 9 h^4 \hbar^4 + \frac{9 h^5 \hbar^5}{2} \right) U[l_1, l_1, l_1] + \left(\frac{9 \hbar^2}{2} + \frac{9 h \hbar^3}{2} + \frac{9 h^2 \hbar^4}{8} - \frac{3 h^3 \hbar^5}{8} \right) U[e_1, e_1, f_1, f_1] + \\ & \quad \left(\frac{27 h^2 \hbar^3}{2} - \frac{27 h^3 \hbar^4}{4} - \frac{27 h^4 \hbar^5}{4} \right) U[e_1, l_1, l_1, f_1] + \left(\frac{27 h^4 \hbar^4}{8} - \frac{27 h^5 \hbar^5}{4} \right) U[l_1, l_1, l_1, l_1] + \\ & \quad \left(\frac{27 h \hbar^3}{2} + \frac{27 h^2 \hbar^4}{2} + \frac{27 h^3 \hbar^5}{8} \right) U[e_1, e_1, l_1, f_1, f_1] + \left(\frac{27 h^3 \hbar^4}{2} - \frac{27 h^4 \hbar^5}{4} \right) U[e_1, l_1, l_1, l_1, f_1] + \\ & \quad \frac{81}{40} h^5 \hbar^5 U[l_1, l_1, l_1, l_1, l_1] + \left(\frac{9 \hbar^3}{2} + \frac{45 h \hbar^4}{4} + \frac{117 h^2 \hbar^5}{8} \right) U[e_1, e_1, e_1, f_1, f_1, f_1] + \\ & \quad \left(\frac{81 h^2 \hbar^4}{4} + \frac{81 h^3 \hbar^5}{4} \right) U[e_1, e_1, l_1, l_1, f_1, f_1] + \frac{81}{8} h^4 \hbar^5 U[e_1, l_1, l_1, l_1, l_1, f_1] + \\ & \quad \left(\frac{27 h \hbar^4}{2} + \frac{135 h^2 \hbar^5}{4} \right) U[e_1, e_1, e_1, l_1, f_1, f_1, f_1] + \frac{81}{4} h^3 \hbar^5 U[e_1, e_1, l_1, l_1, l_1, f_1, f_1] + \\ & \quad \left(\frac{27 \hbar^4}{8} + \frac{27 h \hbar^5}{2} \right) U[e_1, e_1, e_1, e_1, f_1, f_1, f_1, f_1] + \frac{81}{4} h^2 \hbar^5 U[e_1, e_1, e_1, l_1, l_1, f_1, f_1, f_1] + \\ & \quad \left. \frac{81}{8} h \hbar^5 U[e_1, e_1, e_1, e_1, l_1, f_1, f_1, f_1, f_1] + \frac{81}{40} \hbar^5 U[e_1, e_1, e_1, e_1, e_1, f_1, f_1, f_1, f_1] \right\} \end{aligned}$$

The Big 90 Lemma.

1. $\mathcal{O}(e^{Vl+\beta e} \mid |e) = \mathcal{O}(e^{Vl+e^V \beta e} \mid |e).$
2. $\mathcal{O}(e^{Vl+\beta f} \mid |f) = \mathcal{O}(e^{Vl+e^V \beta f} \mid |f)$ <http://drorbn.net/AcademicPensieve/Classes/17-1350-AKT/#MathematicaNotebooks>

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta e f} \mid fe) = \mathcal{O}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} \mid ef), \text{ with } v = (1 + h\delta)^{-1}.$$

Brute Proof.

$$\text{\$TD} = 3; \mathcal{O}[e^{\hbar \gamma l_1 + \beta \hbar e_1}, \{l_1, e_1\} \rightarrow 1]$$

$$U[] + (\beta \hbar + \beta \gamma \hbar^2 + \frac{1}{2} \beta \gamma^2 \hbar^3) U[e_1] + \gamma \hbar U[l_1] + \left(\frac{\beta^2 \hbar^2}{2} + \beta^2 \gamma \hbar^3\right) U[e_1, e_1] + (\beta \gamma \hbar^2 + \beta \gamma^2 \hbar^3) U[e_1, l_1] + \frac{1}{2} \gamma^2 \hbar^2 U[l_1, l_1] + \frac{1}{6} \beta^3 \hbar^3 U[e_1, e_1, e_1] + \frac{1}{2} \beta^2 \gamma \hbar^3 U[e_1, e_1, l_1] + \frac{1}{2} \beta \gamma^2 \hbar^3 U[e_1, l_1, l_1] + \frac{1}{6} \gamma^3 \hbar^3 U[l_1, l_1, l_1]$$

$$\text{\$TD} = 3; \mathcal{O}[e^{\hbar \gamma l_1 + e^{\hbar \gamma} \beta \hbar e_1}, \{e_1, l_1\} \rightarrow 1]$$

$$U[] + (\beta \hbar + \beta \gamma \hbar^2 + \frac{1}{2} \beta \gamma^2 \hbar^3) U[e_1] + \gamma \hbar U[l_1] + \left(\frac{\beta^2 \hbar^2}{2} + \beta^2 \gamma \hbar^3\right) U[e_1, e_1] + (\beta \gamma \hbar^2 + \beta \gamma^2 \hbar^3) U[e_1, l_1] + \frac{1}{2} \gamma^2 \hbar^2 U[l_1, l_1] + \frac{1}{6} \beta^3 \hbar^3 U[e_1, e_1, e_1] + \frac{1}{2} \beta^2 \gamma \hbar^3 U[e_1, e_1, l_1] + \frac{1}{2} \beta \gamma^2 \hbar^3 U[e_1, l_1, l_1] + \frac{1}{6} \gamma^3 \hbar^3 U[l_1, l_1, l_1]$$

$$\text{\$TD} = 6; \mathcal{O}[e^{\hbar \gamma l_1 + \beta \hbar e_1}, \{l_1, e_1\} \rightarrow 1] == \mathcal{O}[e^{\hbar \gamma l_1 + e^{\hbar \gamma} \beta \hbar e_1}, \{e_1, l_1\} \rightarrow 1]$$

True

$$\text{\$TD} = 6; \mathcal{O}[e^{\hbar \gamma l_1 + \beta \hbar f_1}, \{f_1, l_1\} \rightarrow 1] == \mathcal{O}[e^{\hbar \gamma l_1 + e^{\hbar \gamma} \beta \hbar f_1}, \{l_1, f_1\} \rightarrow 1]$$

True

$$\text{\$TD} = 3; \mathcal{O}[e^{\hbar (\beta e_1 + \alpha f_1 + \delta e_1 f_1)}, \{f_1, e_1\} \rightarrow 1]$$

$$\begin{aligned} & (1 - \delta \hbar h_1 - \alpha \beta \hbar^2 h_1 + \delta^2 \hbar^2 h_1^2 + 2 \alpha \beta \delta \hbar^3 h_1^2 - \delta^3 \hbar^3 h_1^3) U[] + (\beta \hbar - 2 \beta \delta \hbar^2 h_1 - \alpha \beta^2 \hbar^3 h_1 + 3 \beta \delta^2 \hbar^3 h_1^2) U[e_1] + \\ & (\alpha \hbar - 2 \alpha \delta \hbar^2 h_1 - \alpha^2 \beta \hbar^3 h_1 + 3 \alpha \delta^2 \hbar^3 h_1^2) U[f_1] + \left(\frac{\beta^2 \hbar^2}{2} - \frac{3}{2} \beta^2 \delta \hbar^3 h_1\right) U[e_1, e_1] + \\ & (\delta \hbar + \alpha \beta \hbar^2 - 2 \delta^2 \hbar^2 h_1 - 4 \alpha \beta \delta \hbar^3 h_1 + 3 \delta^3 \hbar^3 h_1^2) U[e_1, f_1] + \left(\frac{\alpha^2 \hbar^2}{2} - \frac{3}{2} \alpha^2 \delta \hbar^3 h_1\right) U[f_1, f_1] + \frac{1}{6} \beta^3 \hbar^3 U[e_1, e_1, e_1] + \\ & \left(\beta \delta \hbar^2 + \frac{1}{2} \alpha \beta^2 \hbar^3 - 3 \beta \delta^2 \hbar^3 h_1\right) U[e_1, e_1, f_1] + \left(\alpha \delta \hbar^2 + \frac{1}{2} \alpha^2 \beta \hbar^3 - 3 \alpha \delta^2 \hbar^3 h_1\right) U[e_1, f_1, f_1] + \frac{1}{6} \alpha^3 \hbar^3 U[f_1, f_1, f_1] + \\ & \frac{1}{2} \beta^2 \delta \hbar^3 U[e_1, e_1, e_1, f_1] + \left(\frac{\delta^2 \hbar^2}{2} + \alpha \beta \delta \hbar^3 - \frac{3}{2} \delta^3 \hbar^3 h_1\right) U[e_1, e_1, f_1, f_1] + \frac{1}{2} \alpha^2 \delta \hbar^3 U[e_1, f_1, f_1, f_1] + \\ & \frac{1}{2} \beta \delta^2 \hbar^3 U[e_1, e_1, e_1, f_1, f_1] + \frac{1}{2} \alpha \delta^2 \hbar^3 U[e_1, e_1, f_1, f_1, f_1] + \frac{1}{6} \delta^3 \hbar^3 U[e_1, e_1, e_1, f_1, f_1, f_1] \end{aligned}$$

$$\text{\$TD} = 6; \text{With}[\{v = (1 + \hbar h \delta)^{-1}\},$$

$$\mathcal{O}[e^{\hbar (\beta e_1 + \alpha f_1 + \delta e_1 f_1)}, \{f_1, e_1\} \rightarrow 1] == \mathcal{O}[v e^{\hbar v (-\hbar h \alpha \beta + \beta e_1 + \alpha f_1 + \delta e_1 f_1)}, \{e_1, f_1\} \rightarrow 1] \quad /. \quad h_1 \rightarrow h$$

True

The Big g_0 Lemma. (again)

$$1. \mathcal{O}(e^{v l + \beta e} \mid le) = \mathcal{O}(e^{v l + e^v \beta e} \mid el).$$

$$2. \mathcal{O}(e^{v l + \beta f} \mid fl) = \mathcal{O}(e^{v l + e^v \beta f} \mid lf).$$

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta e f} \mid fe) = \mathcal{O}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} \mid ef), \text{ with } v = (1 + h\delta)^{-1}.$$

Gentler Proofs of 1 & 2 and of 3 at $\delta=0$.

$$\text{MatrixForm} \text{ /@ } \{\text{MatrixExp}[\gamma \rho l].\text{MatrixExp}[\beta \rho e], \text{MatrixExp}[e^\gamma \beta \rho e].\text{MatrixExp}[\gamma \rho l]\}$$

$$\left\{ \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^\gamma & e^\gamma \beta \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^\gamma & e^\gamma \beta \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

$$\text{MatrixForm} \text{ /@ } \{\text{MatrixExp}[\beta \rho f].\text{MatrixExp}[\gamma \rho l], \text{MatrixExp}[\gamma \rho l].\text{MatrixExp}[e^\gamma \beta \rho f]\}$$

$$\left\{ \begin{pmatrix} 1 & e^\gamma \beta & 0 \\ 0 & e^\gamma & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & e^\gamma \beta & 0 \\ 0 & e^\gamma & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

MatrixForm /@ {**MatrixExp**[$\alpha \rho f$].**MatrixExp**[$\beta \rho e$], **MatrixExp**[$-\alpha \beta \rho h$].**MatrixExp**[$\beta \rho e$].**MatrixExp**[$\alpha \rho f$]} }

$$\left\{ \begin{pmatrix} 1 & \alpha & \alpha \beta \\ 0 & 1 & \beta \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & \alpha & \alpha \beta \\ 0 & 1 & \beta \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

The Main g_0 Theorem.

Raw Version. The g_0 invariant of any S-component tangle T can be written in the form $Z(T) = \mathcal{O}(\omega e^{L+Q} \mid \prod_{i \in S} e_i l_i f_i)$, where ω is a scalar (meaning, a rational function in the variables h_i and their exponentials $t_i = e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients a_{ij} and where $Q = \sum b_{ij} e_i f_j$ is a balanced quadratic in the variables e_i and f_j with scalar coefficients b_{ij} . Furthermore, after setting $h_i = h$ and $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

Proof. Indeed,

$$0. R = e^{h \otimes l + e \otimes f} = \mathcal{O}(\exp(hl + \frac{e^h - 1}{h} ef \mid e \otimes l f),$$

$$1. \mathcal{O}(e^{\gamma l + \beta e} \mid l e) = \mathcal{O}(e^{\gamma l + e^\gamma \beta e} \mid e l),$$

$$2. \mathcal{O}(e^{\gamma l + \beta f} \mid f l) = \mathcal{O}(e^{\gamma l + e^\gamma \beta f} \mid l f),$$

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta e f} \mid f e) = \mathcal{O}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} \mid e f), \text{ with } v = (1 + h\delta)^{-1},$$

and the rest is straight-forward.

Polished Version. With $\bar{e} = \frac{(e^h - 1)}{h} e$, the g_0 invariant of any S-component tangle T can be written in the form

$Z(T) = \mathcal{O}(\omega^{-1} e^{-L + \omega^{-1} Q} \mid \prod_{i \in S} \bar{e}_i l_i f_i)$, where ω is a scalar (meaning, a **polynomial** in the variables $t_i = e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients a_{ij} and where $Q = \sum b_{ij} \bar{e}_i f_j$ is a balanced quadratic in the variables \bar{e}_i and f_j with scalar coefficients b_{ij} . Furthermore, after setting $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

Debts.

1. Implement (and verify!).
2. Really prove part 3 of the big g_0 -lemma.