

Let M be a manifold and let A be a finite set.

Definition 1. The open configuration space of A in M is $C_A^o(M) := \{\text{injections } p: A \rightarrow M\}$.

Definition 2. The compactified configuration space of A in M is

$$C_A(M) := \coprod_{\substack{\{A_1, \dots, A_k\}, \\ A = \cup A_\alpha, A_\alpha \neq \emptyset}} \left\{ (p_\alpha \in M, c_\alpha \in \tilde{C}_{A_\alpha}(T_{p_\alpha} M))_{\alpha=1}^k : p_\alpha \neq p_\beta \text{ for } \alpha \neq \beta \right\}$$

where if V is a vector space and A is a singleton, $\tilde{C}_A(V) := \{\text{a point}\}$ and if $|A| \geq 2$,

$$\tilde{C}_A(V) := \coprod_{\substack{\{A_1, \dots, A_k\} \\ A = \cup A_\alpha; k \geq 2, A_\alpha \neq \emptyset}} \left\{ (v_\alpha \in V, c_\alpha \in \tilde{C}_{A_\alpha}(T_{v_\alpha} V))_{\alpha=1}^k : v_\alpha \neq v_\beta \text{ for } \alpha \neq \beta \right\} \Big/ \begin{array}{l} \text{translations and} \\ \text{dilations.} \end{array}$$

Definition 3. A “ d -manifold with corners” is defined in the same way as a manifold, except coordinate patches look like neighborhoods of 0 in $\mathbb{R}_{+k}^d := \{x \in \mathbb{R}^d : x^i \geq 0 \text{ for } i \leq k\}$ instead of merely like neighborhoods of 0 in \mathbb{R}^d or in $\mathbb{R}_+^d := \{x \in \mathbb{R}^d : x^1 \geq 0\}$.

Theorem 4. $C_A(M)$ is a manifold with corners, and $\partial C_A(M) = \coprod_{A' \subset A, |A'| \geq 2} \{(p, c) : p \in C_{A/A'}^o(M), c \in \tilde{C}_{A'}(T_{p_{A'}} M)\}$.

Theorem 5. (1) If M is compact, so is $C_A(M)$.

(2) If A is a singleton, $C_A(M) = M$. If A is a doubleton, then $C_A(M)$ is isomorphic to $M \times M$ minus a tubular neighborhood of the diagonal $\Delta \subset M \times M$. That is, $C_A(M) = M \times M - V(\Delta)$.

(3) If $B \subset A$ then there is a natural map $p_B: C_A(M) \rightarrow C_B(M)$. In particular, for every $i, j \in A$ there is a “direction map” $\phi_{ij}: C_A(\mathbb{R}^n) \rightarrow C_{\{i,j\}}(\mathbb{R}^n) \sim S^{n-1}$.

(4) If $f: M \rightarrow N$ is a smooth embedding, then there’s a natural $f_\star: C_A(M) \rightarrow C_A(N)$.

Now let D be a graph whose set of vertices is A . If two different vertices $a_{0,1} \in A$ are connected by an edge in D , we write $a_0 \xrightarrow{D} a_1$. Likewise, if $A_{0,1} \subset A$ are disjoint subsets, we write $A_0 \xrightarrow{D} A_1$ if $a_0 \xrightarrow{D} a_1$ for some $a_0 \in A_0$ and $a_1 \in A_1$. For any subset A_0 of A we let $D(A_0)$ be the restriction of D to A_0 .

Definition 6. The open configuration space of D in M is $C_D^o(M) := \{p: A \rightarrow M : p(a_0) \neq p(a_1) \text{ whenever } a_0 \xrightarrow{D} a_1\}$.

Definition 7. The compactified configuration space of D in M is

$$C_D(M) := \coprod_{\substack{\{A_1, \dots, A_k\} \\ A = \cup A_\alpha, A_\alpha \neq \emptyset \\ \forall \alpha D(A_\alpha) \text{ connected}}} \left\{ (p_\alpha \in M, c_\alpha \in \tilde{C}_{D(A_\alpha)}(T_{p_\alpha} M))_{\alpha=1}^k : p_\alpha \neq p_\beta \text{ whenever } A_\alpha \xrightarrow{D} A_\beta \right\}$$

where if V is a vector space and A is a singleton, $\tilde{C}_D(V) := \{\text{a point}\}$, and if $|A| \geq 2$,

$$\tilde{C}_D(V) := \coprod_{\substack{\{A_1, \dots, A_k\} \\ A = \cup A_\alpha; k \geq 2, A_\alpha \neq \emptyset \\ \forall \alpha D(A_\alpha) \text{ connected}}} \left\{ (v_\alpha \in V, c_\alpha \in \tilde{C}_{D(A_\alpha)}(T_{v_\alpha} V))_{\alpha=1}^k : v_\alpha \neq v_\beta \text{ whenever } A_\alpha \xrightarrow{D} A_\beta \right\} \Big/ \begin{array}{l} \text{translations} \\ \text{and} \\ \text{dilations.} \end{array}$$

Theorem 8. The obvious parallel of the previous theorems holds.

Definition 9. Write $S^n = \mathbb{R}^n \cup \{\infty\}$ and set $\bar{C}_A(\mathbb{R}^n) := \{c \in C_{A \cup \{\infty\}}(S^n) : p_\infty(c) = \infty\}$.

Theorem 10. $\bar{C}_A(\mathbb{R}^n)$ is a compact manifold with corners and the direction maps $\phi_{ij}: \bar{C}_A(\mathbb{R}^n) \rightarrow S^{n-1}$ remain well-defined.

Finally, given $\gamma: S^1 \rightarrow \mathbb{R}^3$ and disjoint finite sets A and B , we set

$$C_{A,B}^\gamma := \{(c', c) : c' \in C_A(S^1), c \in \bar{C}_{A \cup B}(\mathbb{R}^3), \gamma_*(c') = p_A(c)\}$$

(and similarly C_D^γ for appropriate graphs D). The obvious variants of the theorems remain valid.