

Pensieve header: The Alexander polynomial using bridges, tunnels, and Alexander numbering.

```
In[=]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\2023-12"];
Once[
  << KnotTheory`;
  << "../Talks/Oaxaca-2210/Rot.m"
]

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.
Read more at http://katlas.org/wiki/KnotTheory.

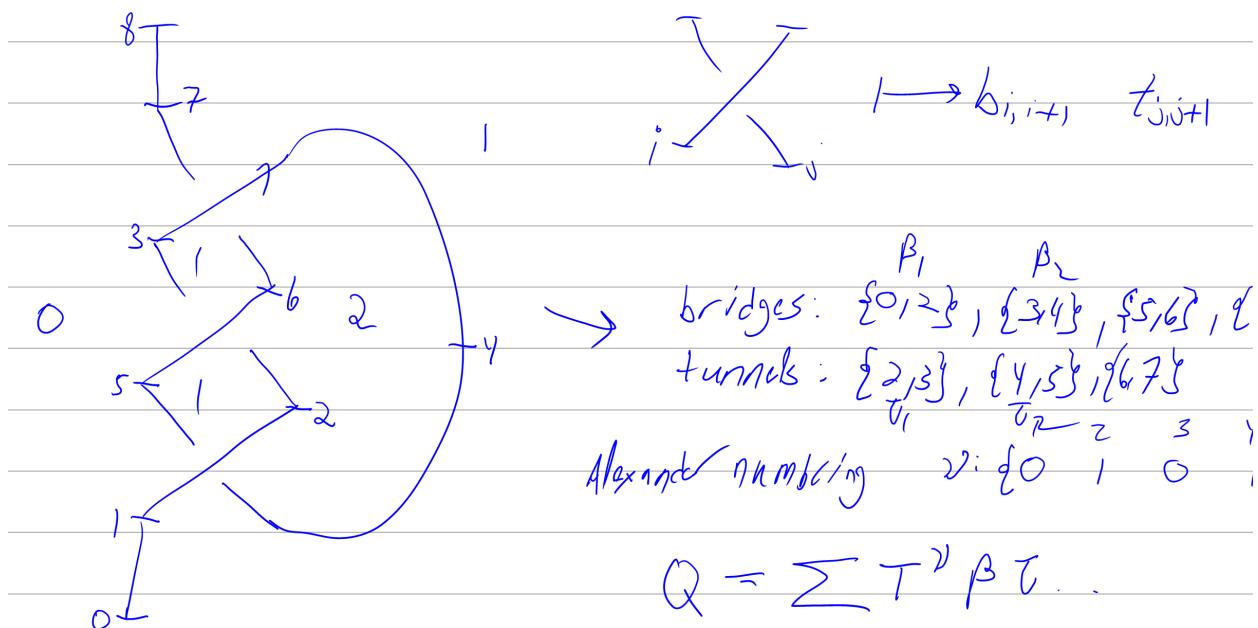
Loading Rot.m from http://drorbn.net/la22/ap to compute rotation numbers.

In[=]:= K1 = EPD[X1,2];
K3 = EPD[X1,4, X5,2, X3,6];
K8 = Knot[8, 17];
K10 = Knot[10, 165];
{Cs, ϕ} = Rot[K = K10] /. {s_, i_, j_} :> {s, j, i}
n = Length[Cs]

Out[=]=
{{{-1, 1, 6}, {-1, 7, 18}, {1, 3, 8}, {1, 17, 2},
  {1, 5, 14}, {1, 9, 16}, {1, 15, 10}, {1, 11, 4}, {1, 20, 13}, {1, 12, 19}},
 {0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, -1, 1, -1, 0, 0, 0}}
```

Out[=]=

10



```
In[=]:= bridges = tunnels = {};
bn = tn = 0; (* completed features *)
cfb = False; (* current feature is bridge *);
cfs = 0; (* current feature start *)
v = {lv = 0};
φ = {};
Q = 0;
For[k = 1, k ≤ 2 n, ++k,
  Cs /. {
    {s_, k, j_} :> (
      AppendTo[φ, bn + 1];
      If[! cfb, AppendTo[tunnels, {cfs, k}]; ++tn;
       cfb = True;
       cfs = k; Q += T^lv (T - 1) βbn+1 τtn];
      AppendTo[v, lv += s];
    ),
    {s_, i_, k} :> (
      AppendTo[φ, tn + 1];
      If[cfb, AppendTo[bridges, {cfs, k}]; ++bn;
       cfb = False;
       cfs = k; Q += T^lv (1 - T) βbn τtn+1];
      AppendTo[v, lv -= s];
    )
  };
  Cs /. {
    {s_, k, j_} /; k > j :> (Q += T^(k-j) (T - 1) (T^s - 1) βφ[[k]] τφ[[j]]),
     {s_, i_, k} /; k > i :> (Q += T^(i-k) (T - 1) (T^s - 1) βφ[[i]] τφ[[k]])
  }
];
{v, bridges, tunnels, φ, Q} // Column

Out[=]=
{0, -1, -2, -1, -2, -1, 0, -1, -2, -1, -2, -1, 0, -1, -2, -1, -2, -1, 0, -1, 0}
{{1, 2}, {3, 4}, {5, 6}, {7, 8}, {9, 10}, {11, 13}, {15, 16}, {17, 18}}
{{0, 1}, {2, 3}, {4, 5}, {6, 7}, {8, 9}, {10, 11}, {13, 15}, {16, 17}, {18, 20}}
{1, 2, 2, 3, 3, 4, 4, 5, 5, 6, 6, 6, 7, 7, 8, 8, 9, 9, 9}
(-1 + T) β1 τ1 +  $\frac{(1-T)\beta_1\tau_2}{T}$  +  $\frac{(-1+T)\beta_2\tau_2}{T^2}$  +  $\frac{(-1+T)^2\beta_3\tau_2}{T^2}$  +  $\frac{(1-T)\beta_2\tau_3}{T}$  +  $\frac{(-1+T)\beta_3\tau_3}{T^2}$  +  $\frac{(-1+T)^2\beta_6\tau_3}{T^2}$  +
 $(-1 + \frac{1}{T}) (-1 + T) \beta_1 \tau_4 + \frac{(1-T)\beta_3\tau_4}{T}$  +  $(-1 + T) \beta_4 \tau_4 + \frac{(-1+T)^2\beta_2\tau_5}{T^2}$  +  $\frac{(1-T)\beta_4\tau_5}{T}$  +  $\frac{(-1+T)\beta_5\tau_5}{T^2}$  +
 $\frac{(1-T)\beta_5\tau_6}{T}$  +  $\frac{(-1+T)\beta_6\tau_6}{T^2}$  +  $\frac{(-1+T)^2\beta_7\tau_6}{T^2}$  +  $\frac{(-1+T)^2\beta_3\tau_7}{T^2}$  +  $(1 - T) \beta_6 \tau_7 + \frac{(-1+T)\beta_7\tau_7}{T^2}$  +  $\frac{(-1+T)^2\beta_9\tau_7}{T}$  +
 $\frac{(-1+T)^2\beta_5\tau_8}{T^2}$  +  $\frac{(1-T)\beta_7\tau_8}{T}$  +  $\frac{(-1+T)\beta_8\tau_8}{T^2}$  +  $(-1 + \frac{1}{T}) (-1 + T) \beta_4 \tau_9 + \frac{(-1+T)^2\beta_6\tau_9}{T}$  +  $\frac{(1-T)\beta_8\tau_9}{T}$  +  $\frac{(-1+T)\beta_9\tau_9}{T}$ 

In[=]:= {bn, tn}

Out[=]=
{8, 9}
```

In[=]:= **MatrixForm**[**mat** = **Factor**@**Table**[$\frac{\partial_{\beta_i, \tau_j} Q}{T - 1}$, {i, 1, bn + 1}, {j, 1, tn}]]

Out[=]//**MatrixForm**=

$$\begin{pmatrix} 1 & -\frac{1}{T} & 0 & -\frac{-1+T}{T} & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & \frac{-1+T}{T^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & 0 & \frac{-1+T}{T^2} & 0 & 0 \\ 0 & 0 & 0 & 1 & -\frac{1}{T} & 0 & 0 & 0 & -\frac{-1+T}{T} \\ 0 & 0 & 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & \frac{-1+T}{T^2} & 0 \\ 0 & 0 & \frac{-1+T}{T^2} & 0 & 0 & \frac{1}{T^2} & -1 & 0 & \frac{-1+T}{T} \\ 0 & 0 & 0 & 0 & 0 & \frac{-1+T}{T^2} & \frac{1}{T^2} & -\frac{1}{T} & 0 \\ 0 & \frac{-1+T}{T^2} & 0 & 0 & 0 & 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} \\ 0 & 0 & 0 & 0 & 0 & \frac{-1+T}{T} & 0 & 0 & \frac{1}{T} \end{pmatrix}$$

In[=]:= **Factor**[-**mat** 0^T /. T → T⁻¹] // **MatrixForm**

Out[=]//**MatrixForm**=

$$\begin{pmatrix} 1 & -\frac{1}{T} & 0 & -\frac{-1+T}{T} & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & \frac{-1+T}{T^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & 0 & \frac{-1+T}{T^2} & 0 & 0 \\ 0 & 0 & 0 & 1 & -\frac{1}{T} & 0 & 0 & 0 & -\frac{-1+T}{T} \\ 0 & 0 & 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} & 0 & \frac{-1+T}{T^2} & 0 \\ 0 & 0 & \frac{-1+T}{T^2} & 0 & 0 & \frac{1}{T^2} & -1 & 0 & \frac{-1+T}{T} \\ 0 & 0 & 0 & 0 & 0 & \frac{-1+T}{T^2} & \frac{1}{T^2} & -\frac{1}{T} & 0 \\ 0 & \frac{-1+T}{T^2} & 0 & 0 & 0 & 0 & 0 & \frac{1}{T^2} & -\frac{1}{T} \\ 0 & 0 & 0 & 0 & 0 & \frac{-1+T}{T} & 0 & 0 & \frac{1}{T} \end{pmatrix}$$

In[=]:= **Factor**[**mat** + (**mat** 0^T /. T → T⁻¹)]

Out[=]=

$$\{ \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \\ \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \\ \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0, 0, 0, 0, 0\} \}$$

In[=]:= **Det**[**mat**]

Out[=]=

$$\frac{-2 T^3 + 10 T^4 - 15 T^5 + 10 T^6 - 2 T^7}{T^{14}}$$

In[=]:= **Alexander**[K][T]

Out[=]=

$$-15 - \frac{2}{T^2} + \frac{10}{T} + 10 T - 2 T^2$$