

Cheat Sheet J

<http://drorbn.net/AcademicPensieve/2013-04/>
 initiated 18/3/13; continues 2013-03; modified 12/4/13, 4:04pm

With alphabet T and with $u, v, w \in T$, $\alpha, \beta, \gamma \in FL(T)$, $D \in \text{tder}(T)$, $g, h \in \exp(\text{tder}(T)) = \text{TAut}(T)$.
 Checkmarks (\checkmark) as in CheatSheetJ-Verification.nb.

1. The definition of J :

$$J_u(\gamma) := \int_0^1 ds \operatorname{div}_u(\gamma // RC_u^{s\gamma}) // C_u^{-s\gamma}$$

2. \checkmark The t equation (desired; obvious splitting seems to fail):

$$J_w(\gamma // tm_w^{uv}) // RC_w^{\gamma // tm_w^{uv}} = J_u(\gamma) // tm_w^{uv} // RC_u^{\gamma // tm_w^{uv}} + J_v(\gamma // RC_u^\gamma) // RC_v^{\gamma // RC_u^\gamma} // tm_w^{uv}$$

A \checkmark

3. \checkmark The h equation (desired):

$$J_u(bch(\alpha, \beta)) = J_u(\alpha) + J_u(\beta // RC_u^\alpha) // C_u^{-\alpha}$$

4. \checkmark The meaning(s) of RC :

$$C_u^\gamma // RC_u^{-\gamma} = Id, \quad C_u^{\gamma // RC_u^\gamma} = RC_u^\gamma$$

5. RC equation t :

$$tm_w^{uv} // RC_w^{\gamma // tm_w^{uv}} = RC_u^\gamma // RC_v^{\gamma // RC_u^\gamma} // tm_w^{uv}$$

$$RC_u^{bch(\alpha, \beta)} = RC_u^\alpha // RC_u^{\beta // RC_u^\alpha}$$

6. RC equation h :

$$\operatorname{div}_u(\alpha // RC_u^\gamma) // C_u^\gamma = ?$$

7. RCC equation div :

$$\operatorname{div}_u(\alpha // C_u^\gamma) // RC_u^\gamma = ?$$

8. CRC equation div :

9. div property t : ~~X~~ \checkmark

$$\operatorname{div}_w(\gamma // tm_w^{uv}) = (\operatorname{div}_u(\gamma) + \operatorname{div}_v(\gamma)) // tm_w^{uv}$$

10. \checkmark div property h — the “cocycle condition”: with $\operatorname{ad}_u\{\gamma\} := \operatorname{der}(u \rightarrow [\gamma, u])$,

$$(\operatorname{div}_u \alpha) // \operatorname{ad}_u \{\beta\} - (\operatorname{div}_u \beta) // \operatorname{ad}_u \{\alpha\} = \operatorname{div}_u([\alpha, \beta] + \alpha // \operatorname{ad}_u \{\beta\} - \beta // \operatorname{ad}_u \{\alpha\})$$

11. ~~div of bch:~~

$$\operatorname{div}_u(bch(\alpha, \beta)) = ?$$

remove \checkmark

12. The definition of JA :

$$JA_u(\gamma) := J_u(\gamma) // RC_u^\gamma$$

13. The ODE for JA : with $\gamma_s = \gamma // RC_u^{s\gamma}$,

$$JA(0) = 0, \quad \frac{dJA(s)}{ds} = JA(s) // \operatorname{ad}_u\{\gamma_s\} + \operatorname{div}_u \gamma_s, \quad JA(1) = JA_u(\gamma)$$

14. The relation with tder :

$$e^{\operatorname{ad}_u\{\gamma\}} = C_u^\gamma \text{ and } C_u^\gamma = e^{\operatorname{ad}_u\{\gamma\}}$$

15. The definition of j (following A-T):

$$j(e^D) = \int_0^1 ds e^{sD} (\operatorname{div} D) = \frac{e^D - 1}{D} (\operatorname{div} D)$$

16. j 's cocycle property:

$$j(gh) = j(g) + g \cdot j(h)$$

17. The differential of \exp :

$$\delta e^\gamma = e^\gamma \cdot \left(\delta \gamma // \frac{1 - e^{-\operatorname{ad} \gamma}}{\operatorname{ad} \gamma} \right) = \left(\delta \gamma // \frac{e^{\operatorname{ad} \gamma} - 1}{\operatorname{ad} \gamma} \right) \cdot e^\gamma$$

18. \checkmark The differential of $\gamma = bch(\alpha, \beta)$:

$$\delta \gamma // \frac{1 - e^{-\operatorname{ad} \gamma}}{\operatorname{ad} \gamma} = \left(\delta \alpha // \frac{1 - e^{-\operatorname{ad} \alpha}}{\operatorname{ad} \alpha} // e^{-\operatorname{ad} \beta} \right) + \left(\delta \beta // \frac{1 - e^{-\operatorname{ad} \beta}}{\operatorname{ad} \beta} \right)$$

19. \checkmark The differential of C :

$$\delta C_u^\gamma = \operatorname{ad}_u \left\{ \delta \gamma // \frac{e^{\operatorname{ad} \gamma} - 1}{\operatorname{ad} \gamma} // RC_u^{-\gamma} \right\} // C_u^\gamma$$

20. \checkmark The differential of RC :

$$\delta RC_u^\gamma = RC_u^\gamma // \operatorname{ad}_u \left\{ \delta \gamma // \frac{1 - e^{-\operatorname{ad} \gamma}}{\operatorname{ad} \gamma} // RC_u^\gamma \right\}$$

21. \checkmark The differential of J :

$$\delta J_u(\gamma) = \delta \gamma // \frac{1 - e^{-\operatorname{ad} \gamma}}{\operatorname{ad} \gamma} // RC_u^\gamma // \operatorname{div}_u // C_u^{-\gamma}$$

A: $J_w(\gamma_w) = J_u(\gamma) // t_w^{uv} + J_v(\gamma // RC_u^\gamma) // C_u^{-\gamma} // t_w^{uv}$ \checkmark

$$\text{B: } \alpha // \text{div}_u // \text{ad}_v^\beta - \beta // \text{div}_v // \text{ad}_u^\alpha = \checkmark$$

$$\alpha // \text{ad}_v^\beta // \text{div}_u - \beta // \text{ad}_u^\alpha // \text{div}_v$$

$C_u C_v$:

$$C_u^{\gamma // RC_v^{-\delta}} // C_v^\gamma = C_v^{\gamma // RC_u^{-\delta}} // C_u^\gamma \quad \left. \begin{array}{l} \text{confirm} \\ \times \end{array} \right\}$$

$RC_u RC_v$:

$$RC_u^\gamma // RC_v^{\gamma // RC_u^{-\delta}} = RC_v^\gamma // RC_u^{\gamma // RC_v^{-\delta}} \quad \left. \begin{array}{l} \text{add.} \\ \checkmark \end{array} \right\}$$