

Meta-Groups, Meta-Bicrossed Products and the Alexander Polynomial

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August 29, 2012

Abstract

Later

These are lecture notes for talks given by the first author, written and completed by the second. The talks, with handouts and videos, are available at [video]. See also further comments at [video].

1 Warm-up: the baby invariant, Z^G

Let T be an oriented tangle diagram. Let G be a group, and suppose we are given two pairs $R^\pm = (g_o^\pm, g_u^\pm)$ of elements of G . At each positive (resp. negative)¹ crossing of T , assign g_o^+ (resp. g_o^-) to the upper strand and g_u^+ (resp. g_u^-) to the lower strand, as in Figure 1. Then, for every strand, multiply all elements assigned to it in the order that they appear and store the end result. If T has n strands, we get a collection of n elements of G . Call this collection $Z^G(T)$.

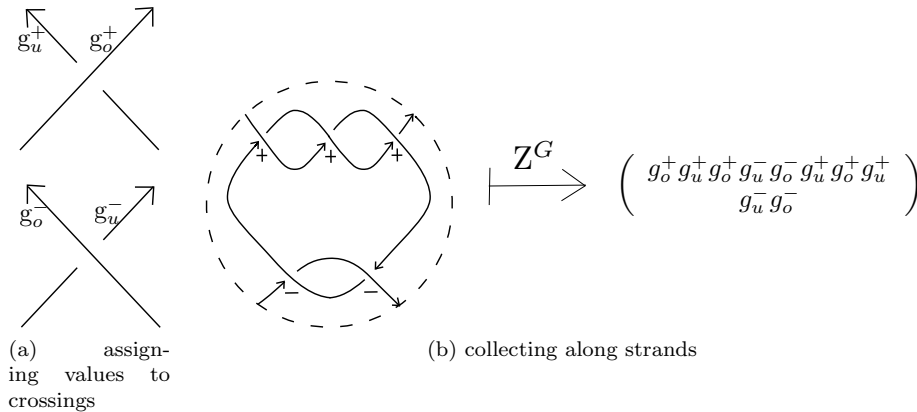


Figure 1: Computing Z^G of a tangle

Unfortunately, the gods are not so kind and Z^G is not worth much more than the effort that went in it. Indeed, invariance under the Reidemeister *II* move (see Figure 2) demands $g_o^- = (g_o^+)^{-1}$ and $g_u^- = (g_u^+)^{-1}$, while Reidemeister *III* adds that g_o^+ and g_u^+ , as well as g_o^- and g_u^- , commute. As a result, every component of $Z^G(T)$ collapses to the form $g_o^a g_u^b$ for some integers a and b , so all the information to bring home is the

¹Signs are determined by the “right-hand rule”: If the right-hand thumb points along the direction of the upper strand of a positive crossing, then the fingers curl in the direction of the lower strand.

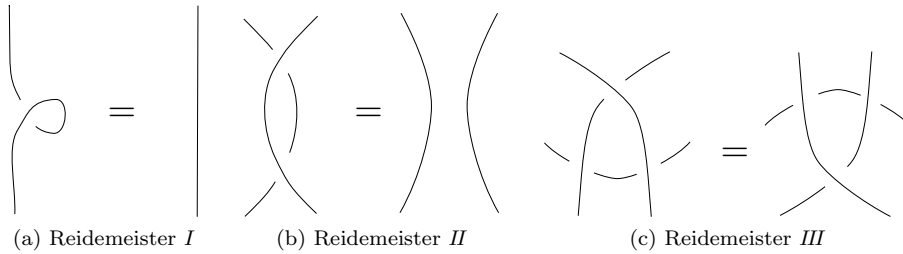


Figure 2: The three Reidemeister moves

→ signed number of times a given strand crosses over or under ~~any~~ other strand. It will turn out, nevertheless, that a similar procedure yields an amply non-trivial invariant with novel properties.
a generalised version of this

2 A better invariant: Z^β

The invariant that we wish to introduce can be thought of as taking values in a meta-group. This is a generalization of what we call a “group computer”:

2.1 Preliminary: A Group Computer

If X is a finite set and G is a group we let G^X denote the set of all possible assignments of elements of G to the set X ; these are “ G -valued datasets, with registers labelled by the elements of X ”.

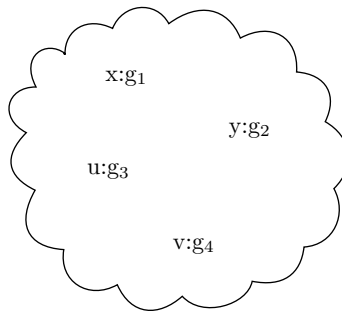


Figure 3: A typical element of $G^{\{x,y,u,v\}}$

if X does not contain the labels x, y, and z,

A group computer can manipulate registers in some prescribed ways. For example, define $m_{xy}^z : G^{X \cup \{x,y\}} \rightarrow G^{X \cup \{z\}}$ using the group multiplication, $\{x : g_1, y : g_2\} \mapsto \{z : g_1 g_2\}$. There are obvious ~~unary~~ operations for inverting or cloning an element, renaming or deleting a register, and inserting the identity in a new register, respectively denoted S^x , Δ_{yz}^x , ρ_x^y , d_x and e^y , and respectively implemented on $G^{X \cup \{x\}}$ by fixing the content of X and mapping $\{x : g\}$ to $\{x : g^{-1}\}$, $\{y : g, z : g\}$, $\{y : g\}$, $\{\}$ and $\{x : g, y : e\}$. In addition there is a binary operation for merging data sets, $\cup : G^X \times G^Y \rightarrow G^{X \cup Y}$, which takes two data sets P and Q and ~~makes~~ their disjoint union $P \cup Q$.

forms

2.2 Meta-Groups

The operations on a group computer obey a certain set of basic set-theoretic axioms as well as axioms inherited from the group G . A meta-group is an abstract computer that satisfies some but not all of those axioms. We postpone the precise definition to Section 3; it is best to begin with a prototypical example, as follows. Let $G_X := M_{X \times X}(\mathbf{Z})$ denote (not in reference to any group G) the set of $|X| \times |X|$ matrices of integers with rows and columns labelled by X . The operation of “multiplication”, on say, 3×3 matrices, $m_z^{xy} : G_{\{x,y,w\}} \rightarrow G_{\{z,w\}}$, is defined by simultaneously adding rows and columns labelled by x and y :

$$\begin{array}{c} x \quad y \quad w \\ x \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \mapsto \begin{array}{c} z \quad w \\ z \begin{pmatrix} a+b+d+e & c+f \\ g+h & i \end{pmatrix} \end{array} \end{array}$$

use and explain the // notation

While still satisfying the associativity condition $m_u^{xy} m_w^{uv} = m_u^{yv} m_w^{xu}$, this example differs from a group computer by the failure of a critical axiom: if $P \in G_{\{x,y\}}$,

$$d_y P \cup d_x P \neq P$$

Indeed, if $P \in G_{\{x,y\}}$ is the matrix $\begin{array}{c} x \quad y \\ x \begin{pmatrix} a & b \\ c & d \end{pmatrix} \end{array}$, then

$$d_y P \cup d_x P = \begin{array}{c} x \quad y \\ x \begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix} \end{array} \neq P$$

There should be an informal definition of a meta-group here: $\{G_X\}$, $m_{xy}^z : G_{\{x,y,w\}} \rightarrow \dots$, satisfying associativity $m_u^{xy} m_w^{yz} = \dots$, and other axioms to be specified later.

2.3 Meta-Bicrossed Products

Suppose a group G is given as the product $G = TH$ of two of its subgroups, where $T \cap H = \{e\}$. Then also $G = HT$ ² and every element of G has unique³ representations of the form th and $h't'$ where $h, h' \in H$ and $t, t' \in T$. Accordingly there is a “swap” map $sw : T \times H \rightarrow H \times T$, $(t, h) \mapsto (h', t')$ such that if $g = th$ then $g = h't'$ also. The swap map satisfies some relations; in group-computer language, the important ones are as in Figure 4⁴. Conversely, provided that the swap map satisfies relations 4a and 4b, the data (H, T, sw) determines a group G , with product given by $\{(h_1, t_1), (h_2, t_2)\} \mapsto (h_1 h_2, t_1 t_2)$ where $sw(t_1, h_2) = (h_2', t_1')$. G is called the bicrossed product of H and T , which we will denote $(H \times T)_{sw}$. In a semidirect product, one of H or T is normal (say T) and the swap map is $sw : (t, h) \mapsto (h, h^{-1}th)$.

²Indeed, if $g^{-1} = th$, then $g = h^{-1}t^{-1}$, so $g^{-1} \in TH$ implies $g \in HT$, and as $TH = G$, also $HT = G$.

³Separation of variables: suppose $g = h_1 t_1 = h_2 t_2$. Then we have $h_2^{-1} h_1 = t_2 t_1^{-1}$, which implies that $h_1 = h_2$ and $t_1 = t_2$ since $h_2^{-1} h_1 \in H$, $t_2 t_1^{-1} \in T$, and $H \cap T = \{e\}$.

⁴ $X // A // B$ is composition made unambiguous: first apply A to X , then apply B .

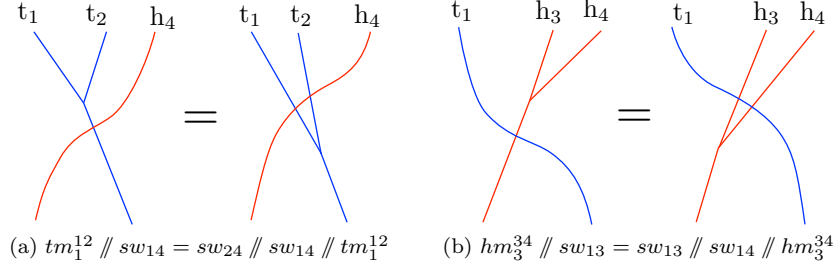
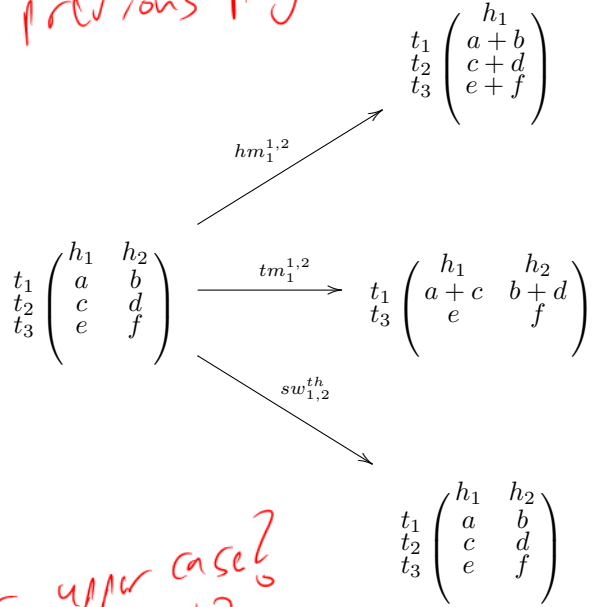


Figure 4: swap operation axioms. tm and hm stand for multiplication in T and H respectively.

M, T so as not to confuse with the groups from the previous page.

The corresponding notion of a meta-bicrossed product is a collection of sets $\beta(H, T)$ indexed by all pairs of finite sets H and T (H for “heads”, T for “tails”), and equipped with multiplication maps tm_z^{xy} (x, y and z tail labels), hm_z^{xy} (x, y and z head labels), and a swap map sw_{xy}^{th} (where t and h indicate that x is a tail label and y is a head label — note that sw_{yx}^{ht} is in general a different map) satisfying (a) and (b).

Given the above we can make a “group multiplication” map out of the head and tail multiplication maps via $gm_z^{xy} := sw_{xy}^{th} \parallel tm_z^{xy} \parallel hm_z^{xy}$. Thus a meta-bicrossed product defines a meta-group with $\Gamma_X = \beta(X, X)$. A prototypical example is again given by (now rectangular) matrices, $\mu(H, T) := M_{T \times H}(\mathbf{Z})$, with tm_z^{xy} and hm_z^{xy} corresponding to adding two rows and adding two columns, and swap being the trivial operation.



lower case or upper case? And where is it?

2.4 β Calculus

The β calculus has an arcane origin (VIDEO)⁵ which is not appropriate to mention here. We expect that it can be presented in a much simpler and fitting context than that in which it was discovered. Accordingly we will simply pull it out of a hat. Let $\beta(H, T)$ be (again, in reference to sets H and T) the collection of arrays with rows labeled by $t_i \in T$ and columns labeled by $h_j \in H$, along with a distinguished element ω . Such arrays are conveniently presented in the following format:

ω	h_1	h_2	\dots
t_1	α_{11}	α_{12}	\cdot
t_2	α_{21}	α_{22}	\cdot
\vdots	\cdot	\cdot	\cdot

The α_{ij} and ω are rational functions of variables T_i , which are in bijection with the row labels t_i .

⁵in which, among other things, the “heads and tails” vocabulary is motivated.

$\beta(H, T)$ is equipped with a peculiar set of operations. Despite being repulsive at sight, they are completely elementary. They are defined as follows:

$$tm_z^{xy} : \begin{array}{c|c} \omega & \dots \\ \hline t_x & \alpha \\ t_y & \beta \\ \vdots & \gamma \end{array} \mapsto \begin{array}{c|c} \omega & \dots \\ \hline t_z & \alpha + \beta \\ \vdots & \gamma \end{array}$$

Here α and β are rows and γ is a matrix. The sum $\alpha + \beta$ is accompanied by the necessary change of variables $T_x, T_y \mapsto T_z$.

$$hm_z^{xy} : \begin{array}{c|ccc} \omega & h_x & h_y & \dots \\ \hline \vdots & \alpha & \beta & \gamma \end{array} \mapsto \begin{array}{c|cc} \omega & h_z & \dots \\ \hline \vdots & \alpha + \beta + \langle \alpha \rangle \beta & \gamma \end{array}$$

Here α and β are columns, γ is a matrix, and $\langle \alpha \rangle = \sum_i \alpha_i$.

$$sw_{xy}^{th} : \begin{array}{c|cc} \omega & h_y & \dots \\ \hline t_x & \alpha & \beta \\ \vdots & \gamma & \delta \end{array} \mapsto \begin{array}{c|cc} \omega \epsilon & h_y & \dots \\ \hline t_x & \alpha(1 + \langle \gamma \rangle / \epsilon) & \beta(1 + \langle \gamma \rangle / \epsilon) \\ \vdots & \gamma / \epsilon & \delta - \gamma \beta / \epsilon \end{array}$$

Here α is a single entry, β is a row, γ is a column, and δ is a matrix comprised of the rest. $\epsilon = 1 + \alpha$. Note also that $\gamma \beta$ is the matrix product of the column γ with the row β and hence has the same dimensions as the matrix δ .

We also need the disjoint union, defined by

$$\frac{\omega_1}{T_1} \Big| \begin{array}{c} H_1 \\ \alpha_1 \end{array} \cup \frac{\omega_2}{T_2} \Big| \begin{array}{c} H_2 \\ \alpha_2 \end{array} = \frac{\omega_1 \omega_2}{T_1 T_2} \Big| \begin{array}{cc} H_1 & H_2 \\ \alpha_1 & 0 \\ 0 & \alpha_2 \end{array}$$

Finally there are two elements which will serve as a pair of ‘‘R-matrices’’, analogous to the pair of pairs (g_σ^\pm, g_u^\pm) of Z^G :

$$R_{xy}^+ = \begin{array}{c|cc} 1 & h_x & h_y \\ \hline t_x & 0 & T_x - 1 \\ t_y & 0 & 0 \end{array} \quad R_{xy}^- = \begin{array}{c|cc} 1 & h_x & h_y \\ \hline t_x & 0 & T_x^{-1} - 1 \\ t_y & 0 & 0 \end{array}$$



We make β into a meta-group via the ‘‘group-multiplication’’ map $gm_z^{xy} := sw_{xy} \parallel tm_z^{xy} \parallel hm_z^{xy}$. We will later set out to make proper definitions, write down the remaining operations, and establish the following

Theorem 1. β is a meta-bicrossed product.

2.5 Z^β

Let T be again an oriented tangle diagram. At each crossing, assign a number to the upper strand and to the lower strand. Form the disjoint union $\bigcup_{\{i,j\}} R_{ij}^\pm$ where $\{i, j\}$ runs over all pairs assigned to crossings, with i labelling the upper strand and j labelling the lower strand, and where \pm is determined by the sign of the given crossing. Now for each strand multiply all the labels in the order in which they appear. That is, if the first label on the strand is k , apply gm_k^{kl} where l runs over all labels subsequently encountered on the strand (in order). If T has n strands, the result is an $n \times n$ array with corner element. Call this array $Z^\beta(T)$.

As an example, for the knot 8_{17} [ROLFSEN] illustrated in Figure 5a, make the disjoint union⁶

$$R_{12,1}^- R_{2,7}^- R_{8,3}^- R_{4,11}^- R_{16,5}^+ R_{6,13}^+ R_{14,3}^+ R_{10,15}^+,$$

which is given by the following array:

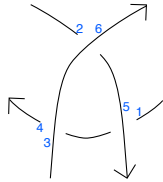
1	h_1	h_3	h_5	h_7	h_9	h_{11}	h_{13}	h_{15}
t_2	0	0	0	$T_2^{-1} - 1$	0	0	0	0
t_4	0	0	0	0	0	$T_4^{-1} - 1$	0	0
t_6	0	0	0	0	0	0	$T_6 - 1$	0
t_8	0	$T_8^{-1} - 1$	0	0	0	0	0	0
t_{10}	0	0	0	0	0	0	0	$T_{10} - 1$
t_{12}	$T_{12}^{-1} - 1$	0	0	0	0	0	0	0
t_{14}	0	0	0	0	$T_{14} - 1$	0	0	0
t_{16}	0	0	$T_{16} - 1$	0	0	0	0	0

Then apply the multiplications gm_1^{1k} , with k running from 1 to 16, to get the following 1×1 array with corner element:

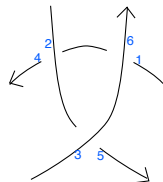
$$\frac{-T_1^{-3} + 4T_1^{-2} - 8T_1^{-1} + 11 - 8T_1 + 4T_1^2 - T_1^3}{t_1} \Big| \begin{array}{l} h_1 \\ 0 \end{array}$$

Theorem 2. (1) Z^β is an invariant of oriented tangle diagrams. (2) Restricted to braids, it is equivalent to the Burau representation. (3) Restricted to knots, the corner element is the Alexander polynomial.

Proof. (1) Trivial. We do the computation for the Reidemeister III move to illustrate. The disjoint unions for each side of the equality are given by:



$$R_{1,5}^- R_{6,2}^- R_{3,4}^+ = \begin{array}{c|ccc} 1 & h_1 & h_2 & h_4 \\ \hline t_3 & 0 & 0 & T_3 - 1 \\ t_5 & T_5^{-1} - 1 & 0 & 0 \\ t_6 & 0 & T_6^{-1} - 1 & 0 \end{array}$$



$$R_{6,1}^+ R_{2,4}^- R_{3,5}^- = \begin{array}{c|ccc} 1 & h_1 & h_4 & h_5 \\ \hline t_3 & 0 & T_2^{-1} - 1 & 0 \\ t_5 & 0 & 0 & T_3^{-1} - 1 \\ t_6 & T_6 - 1 & 0 & 0 \end{array}$$

Then one checks that indeed

$$R_{1,5}^- R_{6,2}^- R_{3,4}^+ \parallel gm_1^{1,4} \parallel gm_2^{2,5} \parallel gm_3^{3,6} = R_{6,1}^+ R_{2,4}^- R_{3,5}^- \parallel gm_1^{1,4} \parallel gm_2^{2,5} \parallel gm_3^{3,6} = \begin{array}{c|cc} 1 & h_1 & h_2 \\ \hline t_1 & T_2^{-1} - 1 & 0 \\ t_2 & T_2^{-1}(T_3 - 1) & T_3^{-1} - 1 \end{array}$$

(2) (SKETCH) The key is to show that a single crossing gets mapped to (essentially) its Burau representation via Z^β and that concatenating braids (essentially) corresponds to matrix multiplication of the “matrix part” of Z^β .

⁶From now on we omit the \cup in disjoint unions: $\beta_1 \beta_2 := \beta_1 \cup \beta_2$. We also suppress rows/columns of zeros.

(3) (WISHFUL) Note first that a priori Z^β does not make sense on round knots, as one would have to multiply all the labels together (including the last remaining one with itself). It turns out however that round knots are equivalent to long knots, so one can simply pick an arbitrary⁷ point to cut the knot open and compute Z^β without ambiguity. However to prove the assertion, given a knot K , turn it first into a braid b_K via Alexander's theorem. Compute $Z^\beta(b_K)$ to obtain the Burau representation, as in (2). Then multiply all the strands together except the last one; this operation is equivalent to taking the determinant of an $(n - 1) \times (n - 1)$ minor. \square

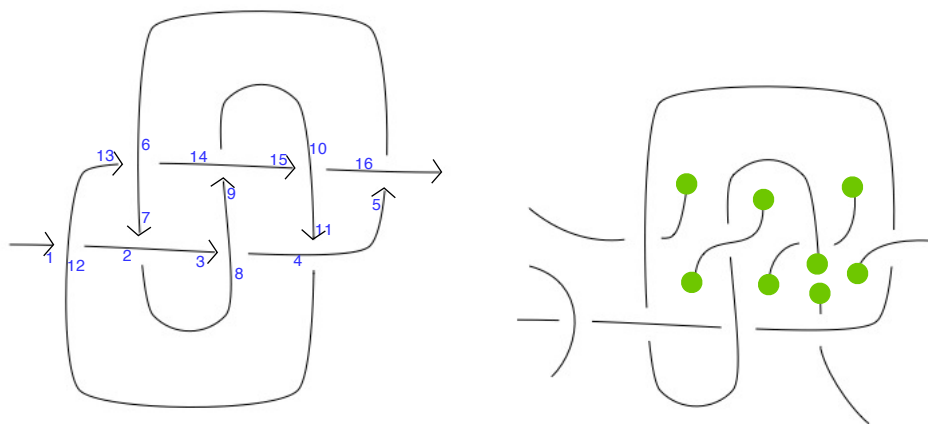
1. too much missing
2. I'd much prefer to avoid braids.

One philosophically appealing major property of Z^β is that the operations used to compute it have a literal interpretation of gluing crossings together. In particular, at every stage of the computation we get an invariant of the tangle⁸ made of all the crossings but only those for which the corresponding gm was carried out have been glued. Additionally, unlike other existing extensions of the Alexander polynomial to tangles, Z^β takes values in spaces of polynomial size, at every step of the calculation.

3 More on meta-groups

3.1 The meta-group of coloured v-tangles

When one tries to follow the interpretation of the computation of Z^β as progressively attaching crossings together to form a tangle, one will in general encounter a step where the tangle becomes non-planar (a strand will have to go through another in an “artificial” crossing to reach the boundary disk). See Figure 5b. Such tangles are called virtual or v-tangles and constitute a rich subject of study on their own [REF]. For us it will suffice to give them a name.



(a) 817 with crossings labelled

(b) 817 after attaching crossings 1 through 10. The arcs with green dots can not make it out to the boundary disk.

Figure 5: The knot 817

Armed with this new word in our vocabulary we can now define what seems to be the “most natural” meta-group: the meta-group of oriented coloured v-tangles. Let Γ_X be the set of v-tangles with strands labelled by X . There is a natural definition for all the meta-group operations. m_z^{xy} ⁹ concatenates strand x with

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⁸the careful reader may wish to peek ahead at Section 3.1 for a better grasp of this statement.

strand y and labels the resulting strand z (note that we *need* virtual tangles for this to be well-defined), S^x reverses the orientation of strand x , e^x creates an isolated strand with label x , d^x deletes strand x , and Δ_{yz}^x is the cabling operation with input strand x and output strands y and z . EXPAND

also note that Δ_{yz}^x is not "commutative", and make sense only for framed tangles.

3.2 Definitions

We now proceed to laying down the details of the definitions of meta-groups and meta-bicrossed products. A more elegant approach is possible and partially realized in the next section.

A meta-group is a collection of sets Γ indexed by all finite sets, equipped with operations $m_z^{xy} : \Gamma_{\{x,y\} \cup X} \rightarrow \Gamma_{\{z\} \cup X}$, $S_x : \Gamma_X \rightarrow \Gamma_X$, $e_x : \Gamma_X \rightarrow \Gamma_{\{x\} \cup X}$, $d_x : \Gamma_{\{x\} \cup X} \rightarrow \Gamma_X$, $\Delta_{yz}^x : \Gamma_{\{x\} \cup X} \rightarrow \Gamma_{\{x,y\} \cup X}$, and $\cup : \Gamma_X \times \Gamma_Y \rightarrow \Gamma_{X \cup Y}$ satisfying the following:

- "Group theory axioms"

- $e_x \parallel m_z^{xy} = \rho_z^y$ (left identity)
- $m_u^{xy} \parallel m_v^{uz} = m_u^{yz} \parallel m_v^{xu}$ (associativity)
- $\Delta_{y,z}^x \parallel S_y \parallel m_x^{yz} = d_x \parallel e_x$ (left inverse)

- "Set manipulation axioms"

- $\rho_x^y \parallel \rho_y^x = id$
- $\rho_y^x \parallel \rho_z^y = \rho_z^x$
- $\Delta_{yz}^x \parallel d_y = \rho_z^x$
- $\Delta_{yz}^x \parallel d_x = \rho_y^x$
- $\rho_x^y \parallel d_y = d_x$
- $m_z^{xy} \parallel d_z = d_x \parallel d_y$
- $e_x \parallel d_x = id$
- $S_x \parallel d_x = id$
- $\Delta_{yz}^x = \Delta_{zy}^x$
- $\Delta_{yz}^x \parallel \rho_u^z = \Delta_{yuz}^x$
- $\rho_u^x \parallel \Delta_{yz}^u = \Delta_{yuz}^x$
- $m_z^{xy} \parallel \rho_u^z = m_u^{xy}$
- $\rho_u^x \parallel m_z^{uy} = m_z^{xy}$
- $e_x \parallel \rho_y^x = e_y$
- $S_x \parallel \rho_y^x = \rho_y^x \parallel S_y$
- {operations involving disjoint sets of labels commute (e.g. $e_x \parallel e_y = e_y \parallel e_x$)}

two columns

A meta-bicrossed product is a collection of sets Γ indexed by all pairs of finite sets, equipped with maps hm , tm , and sw , such that:

- $hm_{h_z}^{h_x h_y} : \Gamma(H \cup \{h_x, h_y\}, T) \rightarrow \Gamma(H \cup \{h_z\}, T)$ and $tm_{t_z}^{t_x t_y} : \Gamma(H, T \cup \{t_x, t_y\}) \rightarrow \Gamma(H, T \cup \{t_z\})$ define meta-groups η and τ for each particular particular $t \in T$ and $h \in H$ respectively.

⁹Remark: this is *not* a meta-generalization of the group structure on braids.

- $m_z^{xy} = sw_{xy} \parallel hm_{h_z}^{h_x h_y} \parallel tm_{t_z}^{t_x t_y}$ defines a meta-group with $\Gamma_X = \Gamma(X, X)$
- sw_{xy} satisfies the following relations
 - $tm_x^{xy} \parallel sw_{xz} = sw_{xz} \parallel sw_{yz} \parallel tm_x^{xy}$
 - $hm_y^{yz} \parallel sw_{xy} = sw_{xy} \parallel sw_{xz} \parallel hm_y^{yz}$
 - $sw_{xy} \parallel t\rho_u^x = t\rho_u^x \parallel sw_{uy}$
 - $sw_{xy} \parallel h\rho_u^y = h\rho_u^y \parallel sw_{xu}$
 - $te_x \parallel sw_{xy} = te_x$
 - $he_y \parallel sw_{xy} = he_y$

If in addition all head operations commute with all tail operations, we call Γ a Hopf meta-bicrossed product (Hopf, because in the β calculus it is the doubling map that gives trouble, see Section 4.1).

3.3 An alternative approach

There is a curious way to package the definition of a meta-group in a much tidier fashion using categorical language, as follows. Let Op and $mset$ be the multicategories whose objects are finite sets and such that

$$Hom_{Op}(X^1, \dots, X^n, Y) = Hom_{Group}(FY \rightarrow F(X^1 \cup \dots \cup X^n))$$

$$Hom_{mset}(\Xi^1, \dots, \Xi^n \rightarrow \Theta) = Hom_{set}(\prod_{i=1}^n \Xi^i \rightarrow \Theta)$$

Here FX denotes the free group on the alphabet X . We can now give a very simple definition: a meta-group is a functor $\Gamma : Op \rightarrow mset$. The operations of Section 2 then correspond via Γ to free group homomorphisms given as follows:

$$m_z^{xy} : F(\{z\} \cup X) \rightarrow F(\{x, y\} \cup X), m_z^{xy}(a) = \begin{cases} xy & a = z \\ a & a \neq z \end{cases}$$

$$S^x : F(\{x\} \cup X) \rightarrow F(\{x\} \cup X), S^x(a) = \begin{cases} a^{-1} & a = x \\ a & a \neq x \end{cases}$$

$$e_x : F(\{x\} \cup X) \rightarrow FX, e_x(a) = \begin{cases} e & a = x \\ a & a \neq x \end{cases}$$

$$\rho_y^x : F(\{y\} \cup X) \rightarrow F(\{x\} \cup X), \rho_y^x(a) = \begin{cases} x & a = y \\ a & a \neq y \end{cases}$$

$$d_x : FX \rightarrow F(\{x\} \cup X), d_x(a) = a$$

$$\Delta_{yz}^x : F(\{y, z\} \cup X) \rightarrow F(\{x\} \cup X), \Delta_{yz}^x(a) = \begin{cases} x & a = y, a = z \\ a & \text{otherwise} \end{cases}$$

$$\cup_{X, Y} : F(X \cup Y) \rightarrow FX \times FY$$

The axioms listed in the previous section then follow from identities satisfied by the above homomorphisms. For example, the axiom for the identity element insertion, $e_x \parallel m_z^{xy} = \rho_z^y$ (the statement $eg = g$ for groups) follows from the calculation $e_x(m_z^{xy}(z)) = e_x(xy) = e_x(x)e_x(y) = ey = y = \rho_z^y(z)$.

It is slightly more challenging to find a “universal” model for meta-bicrossed products. One can ask whether there is a systematic way to turn any algebraic structure into a meta-algebraic structure. We will leave these matters open.

4 Some verifications: computer program

As mentioned and made explicit above, the operations of the β calculus are ugly. However, it can be implemented in a computer program in a very short paragraph, and the program handles the proofs of Theorems 1 and 2 very well. The following *Mathematica* code produces a ready-to-use program with neatly formatted output:

Initialization

```
 $\beta$ Simp = Factor; SetAttributes[ $\beta$ Collect, Listable];
 $\beta$ Collect[B[ $\omega$ _,  $\Lambda$ _]] := B[ $\beta$ Simp[ $\omega$ ],
  Collect[ $\Lambda$ , h_, Collect[#_, t_,  $\beta$ Simp] &]];
 $\beta$ Form[B[ $\omega$ _,  $\Lambda$ _]] := Module[{ts, hs, M},
  ts = Union[Cases[B[ $\omega$ ,  $\Lambda$ ], (t | T)_s  $\mapsto$  s, Infinity]];
  hs = Union[Cases[B[ $\omega$ ,  $\Lambda$ ], h_s  $\mapsto$  s, Infinity]];
  M = Outer[ $\beta$ Simp[Coefficient[ $\Lambda$ , h_{#1} t_{#2}]] &, hs, ts];
  PrependTo[M, t_ & /@ ts];
  M = Prepend[Transpose[M], Prepend[h_ & /@ hs,  $\omega$ ]];
  MatrixForm[M];
 $\beta$ Form[else_] := else /.  $\beta$ _B  $\mapsto$   $\beta$ Form[ $\beta$ ];
Format[ $\beta$ _B, StandardForm] :=  $\beta$ Form[ $\beta$ ];
B /: B[ $\omega$ 1_,  $\beta$ 1_] == B[ $\omega$ 2_,  $\beta$ 2_] := ( $\omega$ 1 ==  $\omega$ 2) && ( $\beta$ 1 ==  $\beta$ 2);
```

Program

```
<math>\mu</math>_ :=  $\mu$  /. t_  $\rightarrow$  1;
tm_{x,y $\rightarrow$ z}_[ $\beta$ _] :=  $\beta$  /. {t_x|y  $\rightarrow$  t_x, T_x|y  $\rightarrow$  T_x};
hm_{x,y $\rightarrow$ z}_[B[ $\omega$ _,  $\Lambda$ _]] := Module[
  { $\alpha$  = D[ $\Lambda$ , h_x],  $\beta$  = D[ $\Lambda$ , h_y],  $\gamma$  =  $\Lambda$  /. h_x|y  $\rightarrow$  0},
  B[ $\omega$ , ( $\alpha$  + (1 +  $\langle\alpha\rangle$ )  $\beta$ ) h_x +  $\gamma$ ] //  $\beta$ Collect];
sw_{x,y}_[B[ $\omega$ _,  $\Lambda$ _]] := Module[{ $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta$ ,  $\epsilon$ },
   $\alpha$  = Coefficient[ $\Lambda$ , h_y t_x];  $\beta$  = D[ $\Lambda$ , t_x] /. h_y  $\rightarrow$  0;
   $\gamma$  = D[ $\Lambda$ , h_y] /. t_x  $\rightarrow$  0;  $\delta$  =  $\Lambda$  /. h_y | t_x  $\rightarrow$  0;
   $\epsilon$  = 1 +  $\alpha$ ;
  B[ $\omega$ * $\epsilon$ ,  $\alpha$  (1 +  $\langle\gamma\rangle$ ) /  $\epsilon$ ] h_y t_x +  $\beta$  (1 +  $\langle\gamma\rangle$ ) /  $\epsilon$  t_x
    +  $\gamma$  /  $\epsilon$  h_y +  $\delta$  -  $\gamma$ * $\beta$  /  $\epsilon$ 
] //  $\beta$ Collect];
gm_{x,y $\rightarrow$ z}_[ $\beta$ _] :=  $\beta$  // sw_{x,y} // hm_{x,y $\rightarrow$ z} // tm_{x,y $\rightarrow$ z};
t $\Delta$ _{x $\rightarrow$ y,z}_[ $\beta$ _] :=  $\beta$  /. {t_x  $\rightarrow$  t_y + t_x, T_x  $\rightarrow$  T_y T_x};
h $\Delta$ _{x $\rightarrow$ y,z}_[ $\beta$ _] :=  $\beta$  /. {h_x  $\rightarrow$  h_y + h_x};
B /: B[ $\omega$ 1_,  $\Lambda$ 1_] B[ $\omega$ 2_,  $\Lambda$ 2_] := B[ $\omega$ 1* $\omega$ 2,  $\Lambda$ 1 +  $\Lambda$ 2];
Rp_{x,y}_ := B[1, (T_x - 1) t_x h_y];
Rm_{x,y}_ := B[1, (T_x^{-1} - 1) t_x h_y];
```

In the above, a β matrix is represented as a polynomial in two variables $\mu = \sum \alpha_{ij} t_i h_j$. This makes some calculations very simple! Selecting the content of column i is achieved by taking a derivative with respect to h_i ; setting all the t 's equal to 1 computes its column sum. The disjoint union of two matrices is simply the sum of their polynomials.

4.1 Theorem 1

To establish Theorem 1 we just need to check that the operations of β calculus satisfy the axioms of a meta-bicrossed product listed in Section 3.2. Let us illustrate the method with the important swap map axiom $tm_1^{12} \parallel sw_{14} = sw_{14} \parallel sw_{24} \parallel tm_1^{12}$. We can use the computer program to check it on an arbitrary 3×2 array (i.e. an array with one more than the number of “participating” indices of each type):

$$\left\{ \beta = \mathbf{B}[\omega, \text{Sum}[\alpha_{10 \ i+j} \ t_i \ h_j, \{i, \{1, 2, 3\}\}, \{j, \{4, 5\}\}]], \right. \\
\left. \begin{aligned} \beta 1 &= \beta \ // \ \mathbf{tm}_{1,2 \rightarrow 1} \ // \ \mathbf{sw}_{1,4}; \\ \beta 2 &= \beta \ // \ \mathbf{sw}_{2,4} \ // \ \mathbf{sw}_{1,4} \ // \ \mathbf{tm}_{1,2 \rightarrow 1}, \\ \mathbf{FullSimplify}[\beta 1] &= \mathbf{FullSimplify}[\beta 2] \end{aligned} \right\} \\
\left\{ \begin{pmatrix} \omega & h_4 & h_5 \\ t_1 & \alpha_{14} & \alpha_{15} \\ t_2 & \alpha_{24} & \alpha_{25} \\ t_3 & \alpha_{34} & \alpha_{35} \end{pmatrix}, \begin{pmatrix} \omega (1 + \alpha_{14} + \alpha_{24}) & h_4 & h_5 \\ t_1 & \frac{(\alpha_{14} + \alpha_{24}) (1 + \alpha_{14} + \alpha_{24} + \alpha_{34})}{1 + \alpha_{14} + \alpha_{24}} & \frac{(\alpha_{15} + \alpha_{25}) (1 + \alpha_{14} + \alpha_{24} + \alpha_{34})}{1 + \alpha_{14} + \alpha_{24}} \\ t_3 & \frac{\alpha_{34}}{1 + \alpha_{14} + \alpha_{24}} & \frac{-\alpha_{15} \alpha_{34} - \alpha_{25} \alpha_{34} + \alpha_{35} + \alpha_{14} \alpha_{35} + \alpha_{24} \alpha_{35}}{1 + \alpha_{14} + \alpha_{24}} \end{pmatrix}, \text{True} \right\}$$

We claim that this constitutes a proof that the identity holds on arrays of arbitrary dimension. The key lies in the fact that the operations are linear in the “non-participating” indices. It is very clear then, from the 2-variable polynomial point of view, that the result still holds if one replaces a non-participating entry by an arbitrary sum. The argument applies to the other axioms as well and the reader is welcome to verify them.

As it stands, the β calculus is not a Hopf meta-bicrossed product. It is readily seen that doubling tails does not commute with multiplying heads:

$$\left\{ \beta = \mathbf{B}[\omega, \mathbf{a} \ t_1 \ h_1 + \mathbf{b} \ t_1 \ h_2], \right. \\
\left. \begin{aligned} \beta &\ // \ \mathbf{hm}_{1,2 \rightarrow 1} \ // \ \mathbf{t}\Delta_{1 \rightarrow 1, 2}, \\ \beta &\ // \ \mathbf{t}\Delta_{1 \rightarrow 1, 2} \ // \ \mathbf{hm}_{1,2 \rightarrow 1} \end{aligned} \right\} \\
\left\{ \left(\begin{pmatrix} \omega & h_1 & h_2 \\ t_1 & \mathbf{a} & \mathbf{b} \end{pmatrix}, \begin{pmatrix} \omega & h_1 \\ t_1 & \mathbf{a} + \mathbf{b} + \mathbf{a} \mathbf{b} \\ t_2 & \mathbf{a} + \mathbf{b} + \mathbf{a} \mathbf{b} \end{pmatrix}, \begin{pmatrix} \omega & h_1 \\ t_1 & \mathbf{a} + \mathbf{b} + 2 \ \mathbf{a} \ \mathbf{b} \\ t_2 & \mathbf{a} + \mathbf{b} + 2 \ \mathbf{a} \ \mathbf{b} \end{pmatrix} \right) \right\}$$

It is possible, nevertheless, to slightly complicate the β calculus to make the above identity hold (in fact, this amounts to “simplifying it less” from its origin in [REF]):

In this alternate scheme, we use variables c_x instead of their exponentials T_x . We have different “R-matrices” given by:

$$R_{xy}^+ = \begin{array}{c|cc} 1 & h_x & h_y \\ t_x & 0 & c_x^{-1}(e^{c_x} - 1) \\ t_y & 0 & 0 \end{array} \qquad R_{xy}^- = \begin{array}{c|cc} 1 & h_x & h_y \\ t_x & 0 & c_x^{-1}(e^{-c_x} - 1) \\ t_y & 0 & 0 \end{array}$$

The operations are the same as before except that the “column norm” is now $\langle \mu \rangle = \sum_i c_i \alpha_i$. This fixes the “bug” above and makes all the axioms of a Hopf meta-bicrossed product hold. The verifications are left to the reader.

4.2 Theorem 2