

From the AT paper.

In order to discuss the groups KV_n and $\widehat{\text{KV}}_2$ we introduce a Lie group 1-cocycle $j : \text{TAut}_n \rightarrow \mathfrak{tr}_n$ which integrates the Lie algebra 1-cocycle $\text{div} : \mathfrak{tder}_n \rightarrow \mathfrak{tr}_n$.

Proposition 5.1. *There is a unique map $j : \text{TAut}_n \rightarrow \mathfrak{tr}_n$ which satisfies the group cocycle condition*

$$(18) \quad j(gh) = j(g) + g \cdot j(h),$$

and has the property

$$(19) \quad \underset{\downarrow}{\text{nice language}} \quad \frac{d}{ds} j(\exp(su))|_{s=0} = \text{div}(u).$$

That's also what I want for λ -calculus.

Proof. Let \mathfrak{g} be a semi-direct sum of \mathfrak{tder}_n and \mathfrak{tr}_n . The cocycle property of the divergence implies that the map $\mathfrak{tder}_n \rightarrow \mathfrak{g}$ defined by formula $u \mapsto u + \text{div}(u)$ is a Lie algebra homomorphism. Define $j(\exp(u))$ by formula $\exp(u + \text{div}(u)) = \exp(j(\exp(u))) \exp(u)$. For $g = \exp(u)$ and $h = \exp(v)$ we have

$$\exp(j(gh))gh = (\exp(j(g))g)(\exp(j(h))h) = \exp(j(g) + g \cdot j(h))gh$$

which implies (18).

Equations (18) and (19) imply the following differential equation for j :

$$\frac{d}{ds} j(\exp(su)) = \text{div}(u) + u \cdot j(\exp(su)).$$

Given the initial condition $j(e) = 0$, this equation admits a unique solution,

$$j(\exp(u)) = \frac{e^u - 1}{u} \cdot \text{div}(u)$$

which proves uniqueness of the cocycle j .

There ought to be a direct proof that the j given by this formula satisfies (18).

In λ calculus: (approximate)

$$\left. \frac{d}{ds} j(su) \right|_{s=0} = \text{div}_y u$$

$$j((s_1 + s_2)u) = (s_1 u)j(s_2 u) + j(s_1 u)$$

so

$$\frac{d}{ds} j(su) = u j(su) + \text{div}_y u$$

Aside: solve $\dot{f} = u f + a$

$$\text{Sol'n: } f = \frac{e^{tu} - 1}{u} a$$



$$\vec{f} = \ell^{tu} a$$

u v

✓

I must have a better description of stability?!

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There may not
be one.