

Pensieve Header: The β -calculus, continuing pensieve://Projects/w-Computations/, continued in pensieve://2012-02/ and pensieve://2012-03/.

β is to remind of “B picture”, though it is “wheeled”. Also, in faux German, β is β is SS, for “semi-symmetrized”.

Continues “Projects/w-Computations/Wheeled Semi-Symmetrized 2D Calculus.nb” and other notebooks referenced there.

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SetDirectory["C:\\drorbn\\AcademicPensieve\\2012-01"];
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Generalities

```
 $\beta$ Simplify = Factor;
ar[i_, j_] := t[i] h[j];
W /: W[a_] + W[b_] := W[ $\beta$ Simplify[a * b]];
W /: n_* W[a_] := W[ $\beta$ Simplify[a^n]];
SetAttributes[ $\beta$ Collect, Listable];
 $\beta$ Collect[ $\beta$ _] :=
  Collect[ $\beta$ , _h, Collect[#, _t,  $\beta$ Simplify] &] /. W[ws_]  $\rightarrow$  W[ $\beta$ Simplify[ws]];
(* "L" for "Labels" *)
hL[ $\beta$ _] := Union[Cases[ $\beta$ , h[s_]  $\rightarrow$  s, Infinity]];
tL[ $\beta$ _] := Union[Cases[ $\beta$ , (t | c)[s_]  $\rightarrow$  s, Infinity]];
dL[ $\beta$ _] := Union[hL[ $\beta$ ], tL[ $\beta$ ]];
SetAttributes[ $\beta$ Form, Listable];
 $\beta$ Form[ $\beta$ _] := Module[
  {tails, heads, mat},
  tails = tL[ $\beta$ ]; heads = hL[ $\beta$ ];
  mat = Outer[ $\beta$ Simplify[Coeficient[ $\beta$ , h[#1] t[#2]]] &, heads, tails];
  PrependTo[mat, t /@ tails];
  mat = Prepend[Transpose[mat], Prepend[h /@ heads,  $\beta$  /. (h[_] | t[_])  $\rightarrow$  0]];
  MatrixForm[mat]
];
 $\beta$ Equations[ $\beta$ 1_ ==  $\beta$ 2_] := Module[
  {tails, heads, l1, l2},
  tails = tL[{ $\beta$ 1,  $\beta$ 2}]; heads = hL[{ $\beta$ 1,  $\beta$ 2}];
  l1 = Flatten[Outer[ $\beta$ Simplify[Coeficient[ $\beta$ 1, h[#1] t[#2]]] &, heads, tails]];
  l2 = Flatten[Outer[ $\beta$ Simplify[Coeficient[ $\beta$ 2, h[#1] t[#2]]] &, heads, tails]];
  Append[
    MapThread[Equal, {l1, l2}],
    ( $\beta$ 1 ==  $\beta$ 2) /. (h[_] | t[_])  $\rightarrow$  0 /. W[w_]  $\rightarrow$  w
  ]
];
];
```

Wheel / DeWheel

```

DeWheel[ $\beta$ _] := Module[
  {heads,  $\xi$ s, nheads},
  heads = Union[Cases[ $\beta$ , h[s_]  $\rightarrow$  s, Infinity]];
   $\xi$ s = (D[ $\beta$ , h[#]] /. t[s_]  $\rightarrow$  c[s]) & /@ heads;
  nheads = MapThread[(h[#1] * Log[1 + #2] / #2) &, {heads,  $\xi$ s}];
   $\beta$ Collect[ $\beta$  /. Thread[(h /@ heads)  $\rightarrow$  nheads]]
];
Wheel[ $\alpha$ _] := Module[
  {heads,  $\eta$ s, nheads},
  heads = Union[Cases[ $\alpha$ , h[s_]  $\rightarrow$  s, Infinity]];
   $\eta$ s = (D[ $\alpha$ , h[#]] /. t[s_]  $\rightarrow$  c[s]) & /@ heads;
  nheads = MapThread[(h[#1] * (Exp[#2] - 1) / #2) &, {heads,  $\eta$ s}];
   $\beta$ Collect[ $\alpha$  /. Thread[(h /@ heads)  $\rightarrow$  nheads]]
];
ar[1, 2] // Wheel

$$\frac{(-1 + e^{c[1]}) h[2] t[1]}{c[1]}$$


$$\frac{(-1 + e^{c[1]}) h[2] t[1]}{c[1]} // DeWheel$$


$$\frac{h[2] \log[e^{c[1]}] t[1]}{c[1]}$$

(Sum[ $\alpha_{10} i_j ar[i, j]$ , {i, 2}, {j, 3}] // Wheel // DeWheel // FullSimplify) /.
Log[Exp[x_]]  $\rightarrow$  x //  $\beta$ Form

$$\begin{pmatrix} 0 & h[1] & h[2] & h[3] \\ t[1] & \alpha_{11} & \alpha_{12} & \alpha_{13} \\ t[2] & \alpha_{21} & \alpha_{22} & \alpha_{23} \end{pmatrix}$$

Sum[ $\alpha_{10} i_j ar[i, j]$ , {i, 2}, {j, 3}] // DeWheel // Wheel // FullSimplify //  $\beta$ Form

$$\begin{pmatrix} 0 & h[1] & h[2] & h[3] \\ t[1] & \alpha_{11} & \alpha_{12} & \alpha_{13} \\ t[2] & \alpha_{21} & \alpha_{22} & \alpha_{23} \end{pmatrix}$$


```

Tails Works

```

tm[x_, y_, z_][ $\beta$ _] :=  $\beta$ Collect[ $\beta$  /. {t[x] | t[y]  $\rightarrow$  t[z], c[x] | c[y]  $\rightarrow$  c[z]}];
t $\Delta$ [z_, x_, y_][ $\beta$ _] :=  $\beta$ Collect[ $\beta$  /. {t[z]  $\rightarrow$  t[x] + t[y], c[z]  $\rightarrow$  c[x] + c[y]}];
t $\eta$ [x_][ $\beta$ _] :=  $\beta$ Collect[( $\beta$  /. t[x]  $\rightarrow$  0) /. c[x]  $\rightarrow$  0];
t $s$ [x_][ $\beta$ _] :=  $\beta$ Collect[ $\beta$  /. {t[x]  $\rightarrow$  -t[x], c[x]  $\rightarrow$  -c[x]}];
tA[_][ $\beta$ _] :=  $\beta$ Collect[ $\beta$ ];
tP[rules___Rule][ $\beta$ _] :=  $\beta$ Collect[
   $\beta$  /. {t[x_]  $\rightarrow$  t[x /. {rules}], c[x_]  $\rightarrow$  c[x /. {rules}]}
];

```

Heads Works

```

hm[x_, y_, z_][β_] := Module[
{ξ, η},
ξ = D[β, h[x]];
η = D[β, h[y]];
βCollect[(β /. h[x | y] → 0) + ξ h[z] + (1 + ξ /. t[s_] → c[s]) η h[z]]
];
hΔ[z_, x_, y_][β_] := βCollect[β /. h[z] → h[x] + h[y]];
hη[x_][β_] := βCollect[β /. h[x] → 0];
hS[x_][β_] := Module[{γ},
γ = 1 + D[β, h[x]] /. t[s_] → c[s];
βCollect[β /. h[x] → -h[x] / γ]
];
hA[x_][β_] := hS[x][β];
hP[rules___Rule][β_] := βCollect[β /. h[x_] → h[x /. {rules}]];
hm[3, 4, 5][ar[1, 3] + ar[2, 4]]
h[5] (t[1] + (1 + c[1]) t[2])
hm[3, 4, 5][ar[1, 3] + ar[2, 4]] // βForm

$$\begin{pmatrix} 0 & h[5] \\ t[1] & 1 \\ t[2] & 1 + c[1] \end{pmatrix}$$

{β = ar[1, 3] + ar[2, 4],
β // hP[3 → 7, 4 → 2]
} // βForm

$$\left\{ \begin{pmatrix} 0 & h[3] & h[4] \\ t[1] & 1 & 0 \\ t[2] & 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & h[2] & h[7] \\ t[1] & 0 & 1 \\ t[2] & 1 & 0 \end{pmatrix} \right\}$$


```

■ Associativity of Heads Multiplication

```

β1 = α1 ar[1, 1] + α2 ar[2, 2] + α3 ar[3, 3]
α1 h[1] t[1] + α2 h[2] t[2] + α3 h[3] t[3]
{β1, β1 // hm[1, 2, 1]} // βForm

$$\left\{ \begin{pmatrix} 0 & h[1] & h[2] & h[3] \\ t[1] & α1 & 0 & 0 \\ t[2] & 0 & α2 & 0 \\ t[3] & 0 & 0 & α3 \end{pmatrix}, \begin{pmatrix} 0 & h[1] & h[3] \\ t[1] & α1 & 0 \\ t[2] & α2 (1 + α1 c[1]) & 0 \\ t[3] & 0 & α3 \end{pmatrix} \right\}$$

{t1 = β1 // hm[1, 2, 1] // hm[1, 3, 1], t2 = β1 // hm[2, 3, 2] // hm[1, 2, 1]} // βForm

$$\left\{ \begin{pmatrix} 0 & h[1] \\ t[1] & α1 \\ t[2] & α2 (1 + α1 c[1]) \\ t[3] & α3 (1 + α1 c[1]) (1 + α2 c[2]) \end{pmatrix}, \begin{pmatrix} 0 & h[1] \\ t[1] & α1 \\ t[2] & α2 (1 + α1 c[1]) \\ t[3] & α3 (1 + α1 c[1]) (1 + α2 c[2]) \end{pmatrix} \right\}$$

t1 == t2 // βSimplify
True

```

■ Compatibility of m and Δ

```
{
   $\beta_1 = \alpha_1 \text{ar}[1, 1] + \alpha_2 \text{ar}[2, 2],$ 
   $t_1 = \beta_1 // h\Delta[1, 1, 3] // h\Delta[2, 2, 4] // hm[1, 2, 1] // hm[3, 4, 2],$ 
   $t_2 = \beta_1 // hm[1, 2, 1] // h\Delta[1, 1, 2]$ 
} //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & 0 \\ t[2] & 0 & \alpha_2 \end{pmatrix}, \begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & \alpha_1 \\ t[2] & \alpha_2 (1 + \alpha_1 c[1]) & \alpha_2 (1 + \alpha_1 c[1]) \end{pmatrix}, \right.$ 
 $\left. \begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & \alpha_1 \\ t[2] & \alpha_2 (1 + \alpha_1 c[1]) & \alpha_2 (1 + \alpha_1 c[1]) \end{pmatrix} \right\}$ 

 $t_1 == t_2$ 

True
```

■ The Square of the Antipode

```
{
   $\beta_1 = \alpha \text{ar}[1, 1],$ 
   $\beta_1 // hs[1],$ 
   $\beta_1 // hs[1] // hs[1]$ 
} //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} 0 & h[1] \\ t[1] & \alpha \end{pmatrix}, \begin{pmatrix} 0 & h[1] \\ t[1] & -\frac{\alpha}{1+\alpha c[1]} \end{pmatrix}, \begin{pmatrix} 0 & h[1] \\ t[1] & \alpha \end{pmatrix} \right\}$ 
```

■ The Antipode is an Anti-Homomorphism

```
{
   $\beta_1 = \alpha_1 \text{ar}[1, 1] + \alpha_2 \text{ar}[2, 2],$ 
   $\beta_1 // hm[1, 2, 3],$ 
   $\beta_1 // hm[2, 1, 3],$ 
   $t_1 = \beta_1 // hm[1, 2, 3] // hs[3],$ 
   $t_2 = \beta_1 // hs[1] // hs[2] // hm[2, 1, 3]$ 
} //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & 0 \\ t[2] & 0 & \alpha_2 \end{pmatrix}, \begin{pmatrix} 0 & h[3] \\ t[1] & \alpha_1 \\ t[2] & \alpha_2 (1 + \alpha_1 c[1]) \end{pmatrix}, \begin{pmatrix} 0 & h[3] \\ t[1] & \alpha_1 (1 + \alpha_2 c[2]) \\ t[2] & \alpha_2 \end{pmatrix}, \right.$ 
 $\left. \begin{pmatrix} 0 & h[3] \\ t[1] & -\frac{\alpha_1}{(1+\alpha_1 c[1]) (1+\alpha_2 c[2])} \\ t[2] & -\frac{\alpha_2}{1+\alpha_2 c[2]} \end{pmatrix}, \begin{pmatrix} 0 & h[3] \\ t[1] & -\frac{\alpha_1}{(1+\alpha_1 c[1]) (1+\alpha_2 c[2])} \\ t[2] & -\frac{\alpha_2}{1+\alpha_2 c[2]} \end{pmatrix} \right\}$ 

 $t_1 == t_2 // \beta\text{Simplify}$ 

True
```

■ The Antipode “Inverse” Property

```
{
   $\alpha \text{ar}[1, 1] // h\Delta[1, 1, 2] // hs[2] // hm[1, 2, 1],$ 
   $\alpha \text{ar}[1, 1] // h\Delta[1, 1, 2] // hs[2] // hm[2, 1, 1]$ 
}

{0, 0}
```

■ The Antipode and de-wheeling

```
{
   $\beta_1 = W[1] + a \text{ar}[1, 1] + b \text{ar}[1, 2] + c \text{ar}[2, 1] + d \text{ar}[2, 2],$ 
   $\beta_1 // hs[1] // \text{DeWheel},$ 
   $\beta_1 // \text{DeWheel}$ 
} //  $\beta\text{Form}$ 


$$\left\{ \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & a & b \\ t[2] & c & d \end{pmatrix}, \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & \frac{a \text{Log}\left[1 - \frac{a c[1]}{1+a c[1]+c c[2]} - \frac{c c[2]}{1+a c[1]+c c[2]}\right]}{a c[1]+c c[2]} & \frac{b \text{Log}\left[1+b c[1]+d c[2]\right]}{b c[1]+d c[2]} \\ t[2] & \frac{c \text{Log}\left[1 - \frac{a c[1]}{1+a c[1]-c c[2]} - \frac{c c[2]}{1+a c[1]-c c[2]}\right]}{a c[1]+c c[2]} & \frac{d \text{Log}\left[1+b c[1]+d c[2]\right]}{b c[1]+d c[2]} \end{pmatrix}, \right.$$


$$\left. \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & \frac{a \text{Log}\left[1+a c[1]+c c[2]\right]}{a c[1]+c c[2]} & \frac{b \text{Log}\left[1+b c[1]+d c[2]\right]}{b c[1]+d c[2]} \\ t[2] & \frac{c \text{Log}\left[1+a c[1]+c c[2]\right]}{a c[1]+c c[2]} & \frac{d \text{Log}\left[1+b c[1]+d c[2]\right]}{b c[1]+d c[2]} \end{pmatrix} \right\}$$


$$\left(1 - \frac{a c[1]}{1+a c[1]+c c[2]} - \frac{c c[2]}{1+a c[1]+c c[2]}\right) (1+a c[1]+c c[2]) // \text{Simplify}$$

1
{
   $\beta_1 = W[1] + a \text{ar}[1, 1] + b \text{ar}[1, 2] + c \text{ar}[2, 1] + d \text{ar}[2, 2],$ 
   $\beta_1 // hs[1],$ 
   $((\beta_1 // \text{DeWheel}) /. h[1] \rightarrow -h[1]) // \text{Wheel} // \text{FullSimplify}$ 
} //  $\beta\text{Form}$ 


$$\left\{ \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & a & b \\ t[2] & c & d \end{pmatrix}, \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & -\frac{a}{1+a c[1]+c c[2]} & b \\ t[2] & -\frac{c}{1+a c[1]+c c[2]} & d \end{pmatrix}, \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & -\frac{a}{1+a c[1]+c c[2]} & b \\ t[2] & -\frac{c}{1+a c[1]+c c[2]} & d \end{pmatrix} \right\}$$

```

Factorization

```

hfac[z_, xtails_List → x_, y_] [β_] := Module[
  {ytails},
  ytails = Complement[
    Union[Cases[β, t[s_] ↦ s, Infinity]],
    xtails
  ];
  hfac[z, xtails → x, ytails → y] [β]
];
hfac[z_, x_, ytails_List → y_] [β_] := Module[
  {xtails},
  xtails = Complement[
    Union[Cases[β, t[s_] ↦ s, Infinity]],
    ytails
  ];
  hfac[z, xtails → x, ytails → y] [β]
];
hfac[z_, xtails_List → x_, ytails_List → y_] [β_] := Module[
  {ξ, ξ, η},
  ξ = D[β, h[z]];
  ξ = ξ /. ((t[#] → 0) & /@ ytails);
  η = ξ /. ((t[#] → 0) & /@ xtails);
  βCollect[β - h[z] ξ + h[x] ξ + h[y] η / (1 + ξ /. t[s_] → c[s])]
];
hm[3, 4, 5][ar[1, 3] + ar[2, 4]] // βForm

$$\begin{pmatrix} 0 & h[5] \\ t[1] & 1 \\ t[2] & 1 + c[1] \end{pmatrix}$$

hm[3, 4, 5][ar[1, 3] + ar[2, 4]] // hfac[5, {1} → 3, 4] // βForm

$$\begin{pmatrix} 0 & h[3] & h[4] \\ t[1] & 1 & 0 \\ t[2] & 0 & 1 \end{pmatrix}$$


```

Conjugation

```

conj[y_, x_] [β_] := Module[
  {v, x0, x1, γ, ξ, η, a},
  v = β // hfac[x, {y} → x0, x1];
  γ = Coefficient[v, ar[y, x0]];
  v = βCollect[v /. W[ws_] ↦ W[ws * (c[y] γ + 1)]];
  ξ = D[v, h[x1]];
  η = D[v, t[y]];
  a = 1 + ξ /. t[s_] ↦ c[s];
  v = βCollect[(v /. t[y] → a t[y]) - c[y] ξ η];
  v // hm[x0, x1, x]
];
conj[y_, x_] [β_] := β // hs[x] // conj[y, x] // hs[x];

```

```
{
   $\beta_1 = W[1] + a[c[1], c[2]] \text{ar}[1, 1] + b[c[1], c[2]] \text{ar}[1, 2] + c[c[1], c[2]] \text{ar}[2, 1] + d[c[1], c[2]] \text{ar}[2, 2],$ 
   $\beta_1 // \text{conj}[1, 1],$ 
   $\beta_1 // \text{conj}[1, 1],$ 
   $\beta_1 // \text{conj}[1, 1] // \text{conj}[1, 1]$ 
} /. e-[c[1], c[2]]  $\Rightarrow$  e //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & a & b \\ t[2] & c & d \end{pmatrix}, \begin{pmatrix} W[1+a c[1]] & h[1] & h[2] \\ t[1] & \frac{a(1+a c[1]+c c[2])}{1+a c[1]} & \frac{b(1+a c[1]+c c[2])}{1+a c[1]} \\ t[2] & \frac{c}{1+a c[1]} & \frac{d-b c c[1]+a d c[1]}{1+a c[1]} \end{pmatrix}, \right.$ 

 $\left. \begin{pmatrix} W\left[\frac{1+c c[2]}{1+a c[1]+c c[2]}\right] & h[1] & h[2] \\ t[1] & \frac{a}{1+c c[2]} & \frac{b}{1+c c[2]} \\ t[2] & \frac{c(1+a c[1]+c c[2])}{1+c c[2]} & \frac{d+b c c[1]+c d c[2]}{1+c c[2]} \end{pmatrix}, \begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & a & b \\ t[2] & c & d \end{pmatrix} \right\}$ 

( $\beta_2 = W[1] + \alpha_1 \text{ar}[1, 1] + \alpha_2 \text{ar}[2, 1] + \alpha_3 \text{ar}[2, 2] + \alpha_4 \text{ar}[2, 3]$ ) //  $\beta\text{Form};$ 
( $\beta_2 = W[1] + \text{Sum}[\alpha_{10 i+j} \text{ar}[i, j], \{i, 2\}, \{j, 3\}]$ ) //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} W[1] & h[1] & h[2] & h[3] \\ t[1] & \alpha_{11} & \alpha_{12} & \alpha_{13} \\ t[2] & \alpha_{21} & \alpha_{22} & \alpha_{23} \end{pmatrix}, \right.$ 

 $\beta_2 // \text{conj}[1, 2] // \beta\text{Form}$ 

 $\left. \begin{pmatrix} W[1+c[1] \alpha_{12}] & h[1] & h[2] & h[3] \\ t[1] & \frac{\alpha_{11} (1+c[1] \alpha_{12}+c[2] \alpha_{22})}{1+c[1] \alpha_{12}} & \frac{\alpha_{12} (1+c[1] \alpha_{12}+c[2] \alpha_{22})}{1+c[1] \alpha_{12}} & \frac{\alpha_{13} (1+c[1] \alpha_{12}+c[2] \alpha_{22})}{1+c[1] \alpha_{12}} \\ t[2] & \frac{\alpha_{21}+c[1] \alpha_{12} \alpha_{21}-c[1] \alpha_{11} \alpha_{22}}{1+c[1] \alpha_{12}} & \frac{\alpha_{22}}{1+c[1] \alpha_{12}} & \frac{-c[1] \alpha_{13} \alpha_{22}+\alpha_{23}+c[1] \alpha_{12} \alpha_{23}}{1+c[1] \alpha_{12}} \end{pmatrix} \right)$ 

(t1 =  $\beta_2 // \text{conj}[1, 2] // \text{conj}[1, 3] // \text{hm}[2, 3, 2]$ ) //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} W[1+c[1] \alpha_{12}+c[1] \alpha_{13}+c[1]^2 \alpha_{12} \alpha_{13}+c[1] c[2] \alpha_{13} \alpha_{22}] \\ t[1] \\ t[2] \end{pmatrix}, \frac{\frac{\alpha_{11} (1+c[1] c)}{1+c[1] \alpha_{12}+c[:}}}{\frac{\alpha_{21}+c[1] \alpha_{12} \alpha_{21}+c[1] \alpha_{13} \alpha_{21}+c[1]^2 \alpha_{12} \alpha_{13} \alpha_{21}-c[1] \alpha_{11}}{1+c[1] \alpha_{12}+c[:]}} \right.$ 

(t2 =  $\beta_2 // \text{hm}[2, 3, 2] // \text{conj}[1, 2]$ ) //  $\beta\text{Form}$ 

 $\left\{ \begin{pmatrix} W[1+c[1] \alpha_{12}+c[1] \alpha_{13}+c[1]^2 \alpha_{12} \alpha_{13}+c[1] c[2] \alpha_{13} \alpha_{22}] \\ t[1] \\ t[2] \end{pmatrix}, \frac{\frac{\alpha_{11} (1+c[1] c)}{1+c[1] \alpha_{12}+c[:}}}{\frac{\alpha_{21}+c[1] \alpha_{12} \alpha_{21}+c[1] \alpha_{13} \alpha_{21}+c[1]^2 \alpha_{12} \alpha_{13} \alpha_{21}-c[1] \alpha_{11}}{1+c[1] \alpha_{12}+c[:]}} \right.$ 

 $\beta\text{Simplify}[t1 == t2]$ 

True

 $\beta\text{Simplify}[$ 
 $(\beta_2 // \text{conj}[1, 2] // \text{conj}[1, 3] // \text{hm}[3, 2, 2]) == (\beta_2 // \text{hm}[3, 2, 2] // \text{conj}[1, 2])]$ 

True


```

```

{β3 = w[1] + Sum[α10 i+j ar[i, j], {i, 3}, {j, 2}],  

 t1 = β3 // tm[1, 2, 1] // conj[1, 1],  

 t2 = β3 // conj[1, 1] // conj[2, 1] // tm[1, 2, 1],  

 t1 == t2  

} // βForm // MatrixForm

```

$$\left(\begin{array}{ccc} W[1] & h[1] & h[2] \\ t[1] & \alpha_{11} & \alpha_{12} \\ t[2] & \alpha_{21} & \alpha_{22} \\ t[3] & \alpha_{31} & \alpha_{32} \end{array} \right)$$

$$\left(\begin{array}{ccc} W[1 + c[1] \alpha_{11} + c[1] \alpha_{21}] & h[1] & h[2] \\ t[1] & \frac{(\alpha_{11} + \alpha_{21}) (1 + c[1] \alpha_{11} + c[1] \alpha_{21} + c[3] \alpha_{31})}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} & \frac{(\alpha_{12} + \alpha_{22}) (1 + c[1] \alpha_{11} + c[1] \alpha_{21} + c[3] \alpha_{31})}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} \\ t[3] & \frac{\alpha_{31}}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} & \frac{-c[1] \alpha_{12} \alpha_{31} - c[1] \alpha_{22} \alpha_{31} + c[1] \alpha_{11} \alpha_{32} + c[1] \alpha_{21} \alpha_{31}}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} \end{array} \right)$$

$$\left(\begin{array}{ccc} W[1 + c[1] \alpha_{11} + c[1] \alpha_{21}] & h[1] & h[2] \\ t[1] & \frac{(\alpha_{11} + \alpha_{21}) (1 + c[1] \alpha_{11} + c[1] \alpha_{21} + c[3] \alpha_{31})}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} & \frac{(\alpha_{12} + \alpha_{22}) (1 + c[1] \alpha_{11} + c[1] \alpha_{21} + c[3] \alpha_{31})}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} \\ t[3] & \frac{\alpha_{31}}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} & \frac{-c[1] \alpha_{12} \alpha_{31} - c[1] \alpha_{22} \alpha_{31} + c[1] \alpha_{11} \alpha_{32} + c[1] \alpha_{21} \alpha_{31}}{1 + c[1] \alpha_{11} + c[1] \alpha_{21}} \end{array} \right)$$

$$(\text{True})$$

■ “4T”

```

Riffle[  

  ComposeList[  

    ops = {conj[2, 1], hΔ[1, 1, 3], hm[2, 3, 2], hΔ[1, 1, 3], hs[3], hm[3, 2, 2]},  

    α1 ar[1, 1] + α2 ar[2, 2]  

  ] // βForm,  

  ops
]

```

$$\left\{ \left(\begin{array}{ccc} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & 0 \\ t[2] & 0 & \alpha_2 \end{array} \right), \text{conj}[2, 1], \left(\begin{array}{ccc} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & -c[2] \alpha_1 \alpha_2 \\ t[2] & 0 & (1 + c[1] \alpha_1) \alpha_2 \end{array} \right), \right.$$

$$hΔ[1, 1, 3], \left(\begin{array}{ccc} 0 & h[1] & h[2] & h[3] \\ t[1] & \alpha_1 & -c[2] \alpha_1 \alpha_2 & \alpha_1 \\ t[2] & 0 & (1 + c[1] \alpha_1) \alpha_2 & 0 \end{array} \right), hm[2, 3, 2],$$

$$\left. \left(\begin{array}{ccc} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & \alpha_1 \\ t[2] & 0 & (1 + c[1] \alpha_1) \alpha_2 \end{array} \right), hΔ[1, 1, 3], \left(\begin{array}{cccc} 0 & h[1] & h[2] & h[3] \\ t[1] & \alpha_1 & \alpha_1 & \alpha_1 \\ t[2] & 0 & (1 + c[1] \alpha_1) \alpha_2 & 0 \end{array} \right), \right.$$

$$hs[3], \left(\begin{array}{cccc} 0 & h[1] & h[2] & h[3] \\ t[1] & \alpha_1 & \alpha_1 & -\frac{\alpha_1}{1 + c[1] \alpha_1} \\ t[2] & 0 & (1 + c[1] \alpha_1) \alpha_2 & 0 \end{array} \right), hm[3, 2, 2], \left. \left(\begin{array}{ccc} 0 & h[1] & h[2] \\ t[1] & \alpha_1 & 0 \\ t[2] & 0 & \alpha_2 \end{array} \right) \right\}$$

$$\{$$

$$\beta1 = R[1, 1] + R[2, 2],$$

$$\beta1 // \text{conj}[2, 1] // hΔ[1, 1, 3] // hm[2, 3, 2] // hΔ[1, 1, 3] // hs[3] // hm[3, 2, 2]$$

$$\} // \betaForm$$

$$\left\{ \left(\begin{array}{ccc} W[1] & h[1] & h[2] \\ t[1] & \frac{-1+e^{c[1]}}{c[1]} & 0 \\ t[2] & 0 & \frac{-1+e^{c[2]}}{c[2]} \end{array} \right), \left(\begin{array}{ccc} W[1] & h[1] & h[2] \\ t[1] & \frac{-1+e^{c[1]}}{c[1]} & 0 \\ t[2] & 0 & \frac{-1+e^{c[2]}}{c[2]} \end{array} \right) \right\}$$

```

Riffle[
ComposeList[
 ops = {hΔ[1, 1, 3], hm[2, 3, 2], hΔ[1, 1, 3], hs[3], hm[3, 2, 2]},
 α1 ar[1, 1] + α2 ar[1, 2]
 ] // βForm,
 ops
]
{(
 0   h[1]   h[2] ), hΔ[1, 1, 3], (
 0   h[1]   h[2]   h[3] ), hm[2, 3, 2],
 t[1] α1      α2          α1
 (
 0   h[1]   h[2] ), hΔ[1, 1, 3], (
 0   h[1]   h[2]   h[3] ),
 t[1] α1      α1 + α2 + c[1] α1 α2      α1
 hs[3], (
 0   h[1]   h[2]   h[3] ),
 t[1] α1      α1 + α2 + c[1] α1 α2 - α1
 1+c[1] α1
 , hm[3, 2, 2], (
 0   h[1]   h[2] )
 t[1] α1      α2
 }

```

The Double

```

dm[x_, y_, z_][β_] := β // conji[y, x] // hm[x, y, z] // tm[x, y, z];
dΔ[z_, x_, y_][β_] := β // hΔ[z, x, y] // tΔ[z, x, y];
dη[x_][β_] := β // hη[x] // tη[x];
ds[x_][β_] := β // ts[x] // conj[x, x] // hs[x];
dA[x_][β_] := β // tA[x] // conj[x, x] // hA[x];
dP[rules___Rule][β_] := β // hP[rules] // tP[rules];
dP[ks_Integer][β_] := β // (dP @@ Thread[Range[Length[{ks}]] → {ks}]);
dd[k_][β_] := Module[
  {shifts},
  shifts = Select[dL[β], (# > k) &,
  β // (dP @@ Thread[shifts → (1 + shifts)]) // dΔ[k, k, k + 1]
 ];
Unprotect[NonCommutativeMultiply];
β_ ** v_ := Module[
  {ρ, σ, labels},
  ρ = β + (v /. {h[s_] → h[σ[s]], t[s_] → t[σ[s]], c[s_] → c[σ[s]]});
  labels = Union[Cases[{{β, v}, h[s_] | t[s_] | c[s_] → s, Infinity}], 
  Do[
    ρ = ρ // dm[s, σ[s], s],
    {s, labels}
  ];
  ρ
];
ar[1, 2] ** ar[1, 3] // βForm
(
 0   h[2]   h[3] )
t[1]   1      1
ar[1, 3] ** ar[2, 3] // βForm
(
 0   h[3] )
t[1]   1
t[2] 1 + c[1]

```

```

ar[1, 2] ** ar[2, 3] // βForm

$$\begin{pmatrix} 0 & h[2] & h[3] \\ t[1] & 1 & \frac{c[2]}{1+c[1]} \\ t[2] & 0 & \frac{1}{1+c[1]} \end{pmatrix}$$

{ar[1, 2] ** ar[1, 3] ** ar[2, 3], ar[2, 3] ** ar[1, 3] ** ar[1, 2]} // βForm

$$\left\{ \begin{pmatrix} 0 & h[2] & h[3] \\ t[1] & 1 & 1+c[2] \\ t[2] & 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & h[2] & h[3] \\ t[1] & 1 & 1+c[2] \\ t[2] & 0 & 1 \end{pmatrix} \right\}$$

ar[1, 3] ** ar[1, 2] // βForm

$$\begin{pmatrix} 0 & h[2] & h[3] \\ t[1] & 1 & 1 \end{pmatrix}$$

ar[2, 3] ** ar[1, 3] // βForm

$$\begin{pmatrix} 0 & h[3] \\ t[1] & 1+c[2] \\ t[2] & 1 \end{pmatrix}$$

ar[2, 3] ** ar[1, 2] // βForm

$$\begin{pmatrix} 0 & h[2] & h[3] \\ t[1] & 1 & 0 \\ t[2] & 0 & 1 \end{pmatrix}$$

{ar[1, 2] // ds[1], ar[1, 2] // ds[2]}

$$\left\{ -h[2] t[1], -\frac{h[2] t[1]}{1+c[1]} \right\}$$

{β3 = W[1] + Sum[α10 i+j ar[i, j], {i, 3}, {j, 3}], β3 // dm[1, 2, 1]
} // βForm

$$\left\{ \begin{pmatrix} W[1] & h[1] & h[2] & h[3] \\ t[1] & α_{11} & α_{12} & α_{13} \\ t[2] & α_{21} & α_{22} & α_{23} \\ t[3] & α_{31} & α_{32} & α_{33} \end{pmatrix}, \begin{pmatrix} W\left[\frac{1+c[1] α_{11}+c[3] α_{31}}{1+c[1] α_{11}+c[1] α_{21}+c[3] α_{31}}\right] \\ t[1] \\ t[3] \end{pmatrix} \right\}$$


$$\frac{α_{11}+c[1] α_{11}^2+α_{12}+2 c[1] α_{11} α_{12}+c[1]^2 α_{11}^2 α_{12}+α_{21}+c[1] α_{11} α_{21}+c[1] α_{12} α_{21}+c[1]^2 α_{11} α_{12} α_{21}+α_{22}+2 c[1] α_{11} α_{22}+c[1]^2 α_{11}^2 α_{22}+c[1] α_{21} α_{22}+c[1]^2 α_{11} α_{21} α_{22}+c[3] α_{11} α_{31}+2 c[3] α_{12} α_{31}+2 c[1] c[3] α_{11} α_{12} α_{31}+c[1] c[3] α_{12} α_{21} α_{31}+c[3] α_{22} α_{31}+c[1] c[3] α_{11} α_{22} α_{31}+c[3]^2 α_{12} α_{31}^2 \right]}{1+c[1] α_{11}+c[3] α_{31}}$$

Simplify[
$$\frac{1}{1+c[1] α_{11}+c[3] α_{31}}$$


$$(α_{11}+c[1] α_{11}^2+α_{12}+2 c[1] α_{11} α_{12}+c[1]^2 α_{11}^2 α_{12}+α_{21}+c[1] α_{11} α_{21}+c[1] α_{12} α_{21}+c[1]^2 α_{11} α_{12} α_{21}+α_{22}+2 c[1] α_{11} α_{22}+c[1]^2 α_{11}^2 α_{22}+c[1] α_{21} α_{22}+c[1]^2 α_{11} α_{21} α_{22}+c[3] α_{11} α_{31}+2 c[3] α_{12} α_{31}+2 c[1] c[3] α_{11} α_{12} α_{31}+c[1] c[3] α_{12} α_{21} α_{31}+c[3] α_{22} α_{31}+c[1] c[3] α_{11} α_{22} α_{31}+c[3]^2 α_{12} α_{31}^2) \frac{1}{(α_{21}+α_{22}+c[1] α_{21} α_{22}+c[1] α_{11}^2 (1+c[1] α_{12}+c[1] α_{22})+c[3] α_{22} α_{31}+α_{12} (1+c[3] α_{31}) (1+c[1] α_{21}+c[3] α_{31})+α_{11} (1+2 c[1] α_{22}+c[1] α_{21} (1+c[1] α_{22})+c[3] α_{31}+c[1] c[3] α_{22} α_{31}+c[1] α_{12} (2+c[1] α_{21}+2 c[3] α_{31})) \frac{1}{1+c[1] α_{11}+c[3] α_{31}})$$


```

```
{
  1/2 ar[1, 1] // dΔ[1, 1, 2] // Wheel,
  1/2 ar[1, 1] // Wheel // dΔ[1, 1, 2]
} // βForm

{ 
$$\begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} \\ t[2] & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} \end{pmatrix}, \begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} \\ t[2] & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} & \frac{-1+e^2}{c[1]+c[2]} \cdot \frac{c[1], c[2]}{2} \end{pmatrix} \}$$

}


$$\beta_1 = W[1] + a ar[1, 1] + b ar[1, 2] + c ar[2, 1] + d ar[2, 2],$$


$$\beta_1 // ds[1],$$


$$\beta_1 // dA[1],$$


$$\beta_1 // ds[1] // ds[2] // FullSimplify,$$


$$\beta_1 // dA[1] // dA[2] // FullSimplify$$

} /. c[s_] → cs // βForm // ColumnForm


$$\begin{pmatrix} W[1] & h[1] & h[2] \\ t[1] & a & b \\ t[2] & c & d \end{pmatrix}$$


$$\begin{pmatrix} W[1 - a c_1] & h[1] & h[2] \\ t[1] & -\frac{a}{-1+a c_1} & -\frac{b (-1+a c_1 - c c_2)}{-1+a c_1} \\ t[2] & \frac{c}{(-1+a c_1) (1-a c_1 + c c_2)} & \frac{-d-b c c_1 + a d c_1}{-1+a c_1} \end{pmatrix}$$


$$\begin{pmatrix} W[1 + a c_1] & h[1] & h[2] \\ t[1] & -\frac{a}{1+a c_1} & \frac{b (1+a c_1 + c c_2)}{1+a c_1} \\ t[2] & -\frac{c}{(1+a c_1) (1+a c_1 + c c_2)} & \frac{d-b c c_1 + a d c_1}{1+a c_1} \end{pmatrix}$$


$$\begin{pmatrix} W[1 - (d + b c c_1) c_2 + a c_1 (-1 + d c_2)] & h[1] & h[2] \\ t[1] & -\frac{-a-b c c_2 + a d c_2}{1-a c_1 - d c_2 - b c c_1 c_2 + a d c_1 c_2} & -\frac{b (-1+a c_1 + c c_2)}{(-1+b c_1 + d c_2) (-1+a c_1 + d c_2)} \\ t[2] & -\frac{c (-1+b c_1 + d c_2)}{(-1+a c_1 + c c_2) (-1+a c_1 + d c_2 + b c c_1 c_2 - a d c_1 c_2)} & -\frac{-d-b c c_1 + a}{1-a c_1 - d c_2 - b c c_1 + a} \end{pmatrix}$$


$$\begin{pmatrix} W[1 + a c_1 + (d - b c c_1 + a d c_1) c_2] & h[1] & h[2] \\ t[1] & -\frac{a-b c c_2 + a d c_2}{1+a c_1 + d c_2 - b c c_1 c_2 + a d c_1 c_2} & \frac{b (1+a c_1 + c c_2)}{(1+b c_1 + d c_2) (-1-a c_1 - d c_2 + b c c_1 c_2 - a d c_1 c_2)} \\ t[2] & -\frac{c (1+b c_1 + d c_2)}{(1+a c_1 + c c_2) (-1-a c_1 - d c_2 + b c c_1 c_2 - a d c_1 c_2)} & -\frac{d-b c c_1 + a d c_1}{1+a c_1 + d c_2 - b c c_1 c_2 + a d c_1 c_2} \end{pmatrix}$$


```

The R Matrix

```
{ρ = F[c[1], c[2]] * ar[1, 2], ρ // ds[1], ρ // ds[2]} // βForm

{ 
$$\begin{pmatrix} 0 & h[2] \\ t[1] & F[c[1], c[2]] \\ t[2] & 0 \end{pmatrix}, \begin{pmatrix} 0 & h[2] \\ t[1] & -F[-c[1], c[2]] \\ t[2] & 0 \end{pmatrix}, \begin{pmatrix} 0 & h[2] \\ t[1] & -\frac{F[c[1], -c[2]]}{1+c[1] F[c[1], -c[2]]} \\ t[2] & 0 \end{pmatrix} \}$$

}
```

```

{ (ρ // ds[2]) ** ρ, (ρ // ds[1]) ** ρ} // βForm

{ { 0 h[2]
  t[1] - F[c[1], -c[2]] - F[c[1], c[2]]
  t[2] 1+c[1] F[c[1], -c[2]] } ,
  { 0 h[2]
  t[1] - F[-c[1], c[2]] + F[c[1], c[2]] - c[1] F[-c[1], c[2]] F[c[1], c[2]]
  t[2] 0 } }

```

F must be so that the above vanishes. Here's a solution:

```

{ -F[c[1], -c[2]] + F[c[1], c[2]]
  1 + c[1] F[c[1], -c[2]],
  F[c[1], c[2]] - F[-c[1], c[2]] (1 + c[1] F[c[1], c[2]]) } /.
F[x_, y_] := (E^x - 1) / x // βSimplify
{0, 0}

R[i_, j_] := w[1] + ar[i, j] (E^c[i] - 1) / c[i];
RInv[i_, j_] /; i ≠ j := R[i, j] // ds[i];
(* R[i, i, p] is R[i,i]^p. Two cases were computed in "120103 Calculator.nb",
the rest guessed and checked there. *)
R[i_, i_, p_] := w[1] + (-1 + E^{p*c[i]}) / c[i];
RInv[i_, i_] := R[i, i, -1];
{ρ = R[1, 2], RInv[1, 2], ρ // ds[1], ρ // ds[2]} // βForm
{ { w[1] h[2]
  t[1] -1+e^{c[1]}
  c[1] } , { w[1] h[2]
  t[1] -e^{-c[1]} (-1+e^{c[1]}) / c[1] } , { w[1] h[2]
  t[1] -e^{-c[1]} (-1+e^{c[1]}) / c[1] } , { w[1] h[2]
  t[1] -e^{-c[1]} (-1+e^{c[1]}) / c[1] } }

{R[1, 2] ** RInv[1, 2], R[1, 1] ** RInv[1, 1]}
{w[1], w[1]}

```

Rotation by 90 degrees

```
Rot90[β_] := β // dP[2, 1] // ds[1]
```

```

Clear[α, β, γ, δ];
{
ρ = W[w[c[1], c[2]]] + α[c[1], c[2]] ar[1, 1] +
    β[c[1], c[2]] ar[1, 2] + γ[c[1], c[2]] ar[2, 1] + δ[c[1], c[2]] ar[2, 2],
ρ // dP[1 → 2, 2 → 1],
ρ // Rot90,
ρ // Rot90 // Rot90,
ρ // Rot90 // Rot90 // Rot90,
ρ // Rot90 // Rot90 // Rot90 // Rot90
} /. c[s_] := c[s] // βForm // ColumnForm


$$\begin{pmatrix} W[w[c_1, c_2]] & h[1] & h[2] \\ t[1] & \alpha[c_1, c_2] & \beta[c_1, c_2] \\ t[2] & \gamma[c_1, c_2] & \delta[c_1, c_2] \end{pmatrix}$$


$$\begin{pmatrix} W[w[c_2, c_1]] & h[1] & h[2] \\ t[1] & \delta[c_2, c_1] & \gamma[c_2, c_1] \\ t[2] & \beta[c_2, c_1] & \alpha[c_2, c_1] \end{pmatrix}$$


$$\begin{pmatrix} W[-(-1+c_1\delta[c_2, -c_1])w[c_2, -c_1]] & h[1] & h[: \\ t[1] & -\frac{\delta[c_2, -c_1]}{-1+c_1\delta[c_2, -c_1]} & \frac{\gamma[c_2, -c_1](1+c_2\beta[c_2, -c_1])}{-1+c_1\delta[c_2, -c_1]} \\ t[2] & \frac{\beta[c_2, -c_1]}{(1+c_2\beta[c_2, -c_1]-c_1\delta[c_2, -c_1])(-1+c_1\delta[c_2, -c_1])} & \frac{-\alpha[c_2, -c_1]-c_1\beta[c_2, -c_1]\gamma[c_2, -c_1]}{-1+c_1\delta[c_2, -c_1]} \end{pmatrix}$$


$$\begin{pmatrix} W[(1-c_1\alpha[-c_1, -c_2]-c_1c_2\beta[-c_1, -c_2])\gamma[-c_1, -c_2]-c_2\delta[-c_1, -c_2]+c_1c_2\alpha[-c_1, -c_2]\delta[-c_1, -c_2]] & t[1] \\ t[2] & t[2] \end{pmatrix}$$


$$\begin{pmatrix} W[-(-1+c_2\alpha[-c_2, c_1])w[-c_2, c_1]] & h[1] & h[:] \\ t[1] & \frac{-c_2\beta[-c_2, c_1]\gamma[-c_2, c_1]-\delta[-c_2, c_1]+c_2\alpha[-c_2, c_1]\delta[-c_2, c_1]}{-1+c_2\alpha[-c_2, c_1]} & \frac{\gamma[-c_2, c_1](1+c_2\beta[-c_2, c_1])}{-1+c_2\alpha[-c_2, c_1]} \\ t[2] & \frac{\beta[-c_2, c_1](-1+c_2\alpha[-c_2, c_1]-c_1\gamma[-c_2, c_1])}{-1+c_2\alpha[-c_2, c_1]} & \frac{-\alpha[-c_2, c_1]-c_1\beta[-c_2, c_1]\gamma[-c_2, c_1]}{-1+c_2\alpha[-c_2, c_1]} \end{pmatrix}$$


$$\begin{pmatrix} W[w[c_1, c_2]] & h[1] & h[2] \\ t[1] & \alpha[c_1, c_2] & \beta[c_1, c_2] \\ t[2] & \gamma[c_1, c_2] & \delta[c_1, c_2] \end{pmatrix}$$

R[1, 2]**(R[1, 2] // dP[1 → 2, 2 → 1] // ds[1] // dP[1 → 2, 2 → 1]) // βForm
(W[1])

```

Rotation by 120 degrees

```
Rot120[β_] := β // ds[2] // dΔ[2, 2, 3] // dm[1, 3, 1] // dP[2, 1]
```

```

{ρ = ar[1, 2],
 ρ // Rot120,
 ρ // Rot120 // Rot120,
 ρ // Rot120 // Rot120 // Rot120
} /. c[s_] → 0 // βForm // ColumnForm


$$\begin{pmatrix} 0 & h[2] \\ t[1] & 1 \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] & h[2] \\ t[2] & -1 & -1 \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] \\ t[1] & -1 \\ t[2] & -1 \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[2] \\ t[1] & 1 \end{pmatrix}$$


Clear[α, β, γ, δ];
{
ρ = W[w[c[1], c[2]]] + α[c[1], c[2]] ar[1, 1] +
β[c[1], c[2]] ar[1, 2] + γ[c[1], c[2]] ar[2, 1] + δ[c[1], c[2]] ar[2, 2],
ρ // Rot120,
ρ // Rot120 // Rot120,
ρ // Rot120 // Rot120 // Rot120
} /. c[s_] → cs // βForm // ColumnForm


$$\begin{pmatrix} W[w[c_1, c_2]] & h[1] & h[2] \\ t[1] & \alpha[c_1, c_2] & \beta[c_1, c_2] \\ t[2] & \gamma[c_1, c_2] & \delta[c_1, c_2] \end{pmatrix}$$


$$\left( W\left[ -\frac{\left(-1-c_2 \alpha[c_2, -c_1-c_2]+c_1 \gamma[c_2, -c_1-c_2]-c_2^2 \beta[c_2, -c_1-c_2] \gamma[c_2, -c_1-c_2]+c_1 \delta[c_2, -c_1-c_2]+c_2 \delta[c_2, -c_1-c_2]+c_1 c_2 \alpha[c_2, -c_1-c_2] \delta[c_2, -c_1-c_2]}{1+c_2 \alpha[c_2, -c_1-c_2]-c_1 \gamma[c_2, -c_1-c_2]} \right] t[1]$$


$$\left( W\left[ -\frac{\left(1-c_1 \alpha[-c_1-c_2, c_1]-c_2 \alpha[-c_1-c_2, c_1]-c_2 \beta[-c_1-c_2, c_1]+c_1 c_2 \alpha[-c_1-c_2, c_1] \beta[-c_1-c_2, c_1]+c_2^2 \alpha[-c_1-c_2, c_1] \beta[-c_1-c_2, c_1]+c_1^2 \beta[-c_1-c_2, c_1]-1+c_1 \beta[-c_1-c_2, c_1]+c_2 \beta[-c_1-c_2, c_1]}{-1+c_1 \beta[-c_1-c_2, c_1]+c_2 \beta[-c_1-c_2, c_1]} \right] t[2]$$


$$\begin{pmatrix} W[w[c_1, c_2]] & h[1] & h[2] \\ t[1] & \alpha[c_1, c_2] & \beta[c_1, c_2] \\ t[2] & \gamma[c_1, c_2] & \delta[c_1, c_2] \end{pmatrix}$$


```

Wheeling and η

```
{
  ρ = Sum[α10 i+j ar[i, j], {i, 2}, {j, 2}],
  ρ // dη[2],
  ρ // DeWheel,
  ρ // DeWheel // dη[2],
  ρ // DeWheel // dη[2] // Wheel
} // βForm // ColumnForm


$$\begin{pmatrix} 0 & h[1] & h[2] \\ t[1] & \alpha_{11} & \alpha_{12} \\ t[2] & \alpha_{21} & \alpha_{22} \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] \\ t[1] & \alpha_{11} \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] \\ t[1] & \frac{\log[1+c[1]\alpha_{11}+c[2]\alpha_{21}]\alpha_{11}}{c[1]\alpha_{11}+c[2]\alpha_{21}} & \frac{h[2]}{\log[1+c[1]\alpha_{12}+c[2]\alpha_{22}]\alpha_{12}} \\ t[2] & \frac{\log[1+c[1]\alpha_{11}+c[2]\alpha_{21}]\alpha_{21}}{c[1]\alpha_{11}+c[2]\alpha_{21}} & \frac{\log[1+c[1]\alpha_{12}+c[2]\alpha_{22}]\alpha_{22}}{c[1]\alpha_{12}+c[2]\alpha_{22}} \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] \\ t[1] & \frac{\log[1+c[1]\alpha_{11}]}{c[1]} \end{pmatrix}$$


$$\begin{pmatrix} 0 & h[1] \\ t[1] & \alpha_{11} \end{pmatrix}$$

```