

Once and for All

February-11-09
10:00 AM

what means

$$M = \boxed{\begin{array}{|c|c|} \hline \nearrow & \searrow \\ \searrow & \nearrow \\ \hline \end{array}}$$

global
in Lie theory?

Alternatively, how is $U(Ig) \otimes U(Ig) \otimes U(g)$ to be interpreted?

$$\underbrace{U(Ig) \otimes U(Ig)}_{\text{tangential differential operators on } \text{Fun}(g \oplus g), \text{ with not-necessarily-constant coefficients}} \otimes \underbrace{U(g)}_{\text{Constant-coefficient tangential differential operators on } \text{Fun}(g) \sim \text{measures on } g}.$$

tangential differential operators on $\text{Fun}(g \oplus g)$, with not-necessarily-constant coefficients

Constant-coefficient tangential differential operators on $\text{Fun}(g) \sim$ measures on g .

From this perspective, "convolution" takes functions on $g \oplus g$ to measures on g , by integrating $M(f(x)g(y))$ w.r.t. both x and y .

$$M = \boxed{\begin{array}{|c|c|} \hline \nearrow & \searrow \\ \searrow & \nearrow \\ \hline \end{array}}$$

$$m = \boxed{\begin{array}{|c|c|} \hline \nearrow & \searrow \\ \searrow & \nearrow \\ \hline \end{array}}$$

Both are functions on g with values in $U(g)$

What means $F \hat{M} = \hat{m} F$

for a tangential differential operator $F \in U(Ig)^{\otimes 2}$?

" T is tangential" implies that if F is invariant then $TF = \hat{T}_0 F$, where T_0 is the [well-defined?] degree 0 part of T .

Let $f \& g$ be invariant. Then

Goal: up to n
j-correction,

$$\int F \hat{M}(f \otimes g) = \int \hat{M} F(f \otimes g) \quad | \quad \int M f \otimes g = \int m F_0 f \otimes g$$

$$\Rightarrow \int (F^*)_0 M(f \otimes g) = \int M F_0(f \otimes g)$$

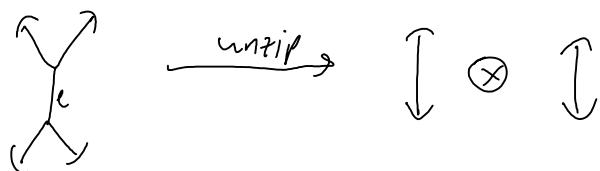
$$\Rightarrow \int (F^*)_0 M f \otimes g = \int m F_0 f \otimes g$$

So all we need is to interpret $(F^*)_0$ and F_0 as "the j correction". There seem to be two equations here, one to fix F_0 and one to fix $(F^*)_0$. There should be a way to reduce this to one.

Question For which $j_0, j_1 \in A^w(\mathbb{N}_n^+)$ can we find a $V \in A^w(\mathbb{N}_n)$ so that

$$j_0 = V_0 \quad \text{and} \quad j_1 = (V^*)_0 \quad ?$$

Might the topological interpretation of all that be the need for "edge renormalization"?



There may another topological operation?

