

Dror Bar-Natan: Talks: Oberwolfach-0805:
Projectivization, Welded Knots and Alekseev-Torossian

Circuit Algebras

- * Have "circuits" with "ends"
- * Can be wired arbitrary.
- * May have "relations" - de-Morgan, etc.
- * "Welded trivalent (framed) tangles" are a circuit algebra:

$WT = \langle \text{Diagram} \rangle / R123, R4 \text{ (for vertices), } F1.$

Further operations: delete, unzip, $\Rightarrow = \Xi(\Rightarrow)$.
 The "Chord Diagrams" - A_n^{ref} . As we did for quantities, substitute into the various moves, to get relations. Also switch to arrow diagram language: $\text{Diagram} \leftrightarrow \text{Diagram}$. Cf:

$\text{Diagram} \mapsto \text{Diagram} + (\text{Diagram} - \text{Diagram}) = \text{Diagram} + \text{Diagram}$

$R3 \mapsto \text{Diagram} - \text{Diagram} = \text{Diagram} - \text{Diagram}$ (r3)

$R4 \mapsto \text{Diagram} - \text{Diagram} = \text{Diagram} - \text{Diagram} = 0$ (vertex pairing)

Theorem. A_n^{ref} is $\mathcal{U}(\text{tder}_n)$.

Here A_n^{ref} is

Kids: tails commute

The Map $\alpha: A_n^{\text{ref}} \rightarrow A_n^{\text{ref}}$

This handout and further links are at <http://www.math.toronto.edu/~drorbn/Talks/Oberwolfach-0805/>

Kaufmann in Siegen

Projectivization

Forbidden

add F1
 $\forall K = \text{Welded knot}$

Kuf to Ferry-Kiming-Rourke

The Dictionary

$(R, F) \leftrightarrow (\Xi, \lambda)$, $(\epsilon, t) \leftrightarrow (\text{Diagram}, H)$

$R^{12} R^{23} R^{31} = R^{23} R^{12} R^{31} \leftrightarrow \text{Diagram} = \text{Diagram}$

$F F^{-1} = I \leftrightarrow \text{Diagram} = \text{Diagram}$

$F^{-1}(x \circ y) F = F(x \circ y)$

$F^{23} R^{12} = R^{12} R^{23} F^{23} \leftrightarrow \text{Diagram} = \text{Diagram}$

$R^{12} = R^{12} R^{23}$

$F^{123} R^{12,3} = R^{12} R^{23} F^{12,3}$ (unfortunate! F1 makes this automatic)

$R F^{21} \alpha(-t) = F \leftrightarrow \text{Diagram} = \text{Diagram}$

$\Xi(F^{12,3})^{-1} F^{45} F^{45} F^{12,3} \leftrightarrow \text{Diagram} = \text{Diagram}$

$\Xi(\text{der}) \leftrightarrow \text{Diagram} = \text{Diagram}$

Disclaimer: The pentagons and the hexagons follow, with a minor twist, from the fact that we have an unipotent invariant of kTG 's.
 When we see it.

**God created the knots,
 all else in topology is the work of mortals!**

Visit!

Edit!

http://katlas.org

- To do.
- ✓ 1. Add $t \leftrightarrow H$
 $r \leftrightarrow \text{Diagram}$
 2. Rearrange Vicks
 - ✓ 3. Add the vertex invariance relations.
 - ✓ 4. Draw a picture of RY .
 - ✓ 5. Re-order the formulas in "The Dictionary".
 - ✓ 6. Add "This is a standard 3-part math talk, with a tangent".
 - ✓ 7. Fix the wheels issue.
 & change "Theorems" to "Theorems".
 - ✓ 8. Better study unzip.
 - ✓ 9. Start with the disclaimer.
 10. start with the disclaimer.

As we did for quantities, substitute into the various moves, to get relations. Also switch to arrow diagram language: $\text{Diagram} \leftrightarrow \text{Diagram}$. Cf:

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Here A_n^{ref} is

Kids: tails commute

Hands satisfy the only possible tree tails ITIX and vertex invariance

Furthermore, this is a simple characterization of tder_n . So we can tell if an invariant element when we see it.